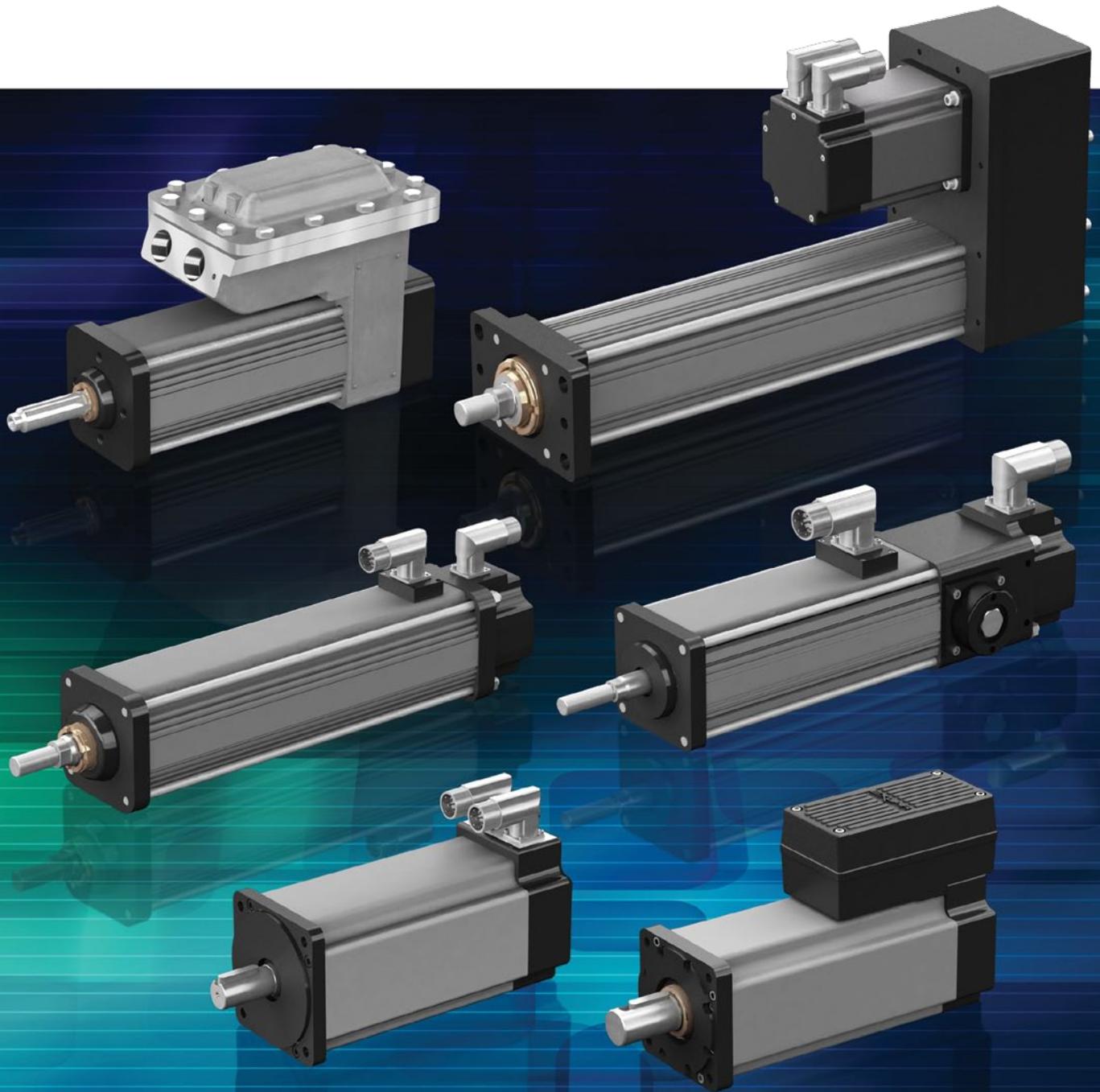


Electric Actuator

PRODUCT CATALOG



EXLAR
a Curtiss-Wright Company

The Global Leader in Actuator Technology

Your Actuator Solution Source

Exlar's product offering covers a wide range of performance specifications and capabilities. Please view the chart below as a thumbnail guide to assist you in choosing the best product for your application. Three product families shown in the table below are not included in this catalog, but are offered in separate brochures as offered below. You may also visit www.exlar.com to download the brochures and view complete specifications.

ROD STYLE LINEAR ACTUATORS	Series	Standard Environmental Rating	Integrated Control Electronics	Integrated Brushless Motor	Nominal Frame Sizes in (mm)	Max Stroke Length in (mm)	Max Cont. Force lbf (kN)	Max Velocity in/sec (mm/sec)	Explosion Proof (CID1)	Non-Incendive (CID2)
Tritex II AC Integrated Drive / Motor / Actuator	T2M	IP54	●	●	90, 115 mm	18 (455)	3,685 (16.4)	37.5 (953)		○
	T2X	IP65								
Tritex II DC Integrated Drive / Motor / Actuator	TDM	IP54	●	●	60, 75 mm	18 (455)	955 (4.2)	33.3 (847)		○
	TDX	IP66								
GS Series Integrated Motor / Actuator	GSM	IP54		●	2-4 inch	18 (455)	3,966 (17.6)	37.5 (953)		○
	GSX	IP65		●	2-7 inch	18 (455)	12,389 (55.1)	40.0 (1,016)		
Hazardous Location Integrated Motor / Actuator	EL100	IP66		●	4 inch	6 (150)	2,011 (8,943)	33.3 (847)	●	
	EL30	IP65			4 inch	6 (150)	885 (3,936)	25.0 (635)	●	
K Series Universal Actuator	KA	IP54			60, 90 mm	48 (1,225)	1,550 (6.9)	2.9 (73)		
	KM	IP54				60 (1,525)	3,500 (15.6)	33.8 (833)		
	KX	IP65				60 (1,525)	3,500 (15.6)	33.8 (833)		
FT Series Universal Actuator	FT	IP65*			3-8 inch	48 (1,225)	40,000 (178)	59.3 (1,500)		

○ = Available option *Base unit only

ROTARY ACTUATORS	Series	Standard Environmental Rating	Integrated Control Electronics	Integrated Planetary Gearhead	Frame Sizes in (mm)	Max Cont. Torque in-lbf (Nm)	Max Velocity RPM	Explosion Proof (CID1)	Non-Incendive (CID2)
Tritex II AC Rotary Gearmotor	R2G	IP65	●	●	90, 115 mm	4,066 (459)	1,000		○
Tritex II AC Rotary Motor	R2M					95 (10.7)	4,000		
Tritex II DC Rotary Gearmotor	RDG	IP66	●	●	60, 90 mm	1,798 (203)	1,250		○
Tritex II DC Rotary Motor	RDM					42 (4.8)	5,000		
Brushless Rotary Gearmotor	SLG	IP65		●	60, 90, 115 mm	4,696 (530)	1,250		○
Brushless Rotary Motor	SLM	IP65			60, 90, 115, 142, 180 mm	615 (69.49)	5,000		○
Hazardous Location Rotary Gearmotor	ER115	P65		●	4 inch	4,128 (466)	750	●	
Hazardous Location Rotary Motor	ER115	IP65			4 inch	120 (13.6)	3,000	●	

○ = Available option

Please contact Exlar to receive these separate brochures.



Exlar Tritex II™
AC actuators integrate an AC powered servo drive, digital position controller, brushless motor and linear or rotary actuator in one compact, sealed package. Simply connect power, I/O, communications and solve your application with one integrated device.



Exlar Tritex II™
DC actuators integrate a DC powered servo drive, digital position controller, brushless motor and linear or rotary actuator in one compact, sealed package. Tritex II DC actuators offer the ideal solution for customers needing 12-48 VDC power input.



Exlar K Series
actuators provide a universal solution for linear motion rod style applications. Two grades of planetary roller screws or an Acme screw are offered allowing you to meet your exact application needs as well as your budget.

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GSX Series

GSM Series

FT Series

SLM/SLG Series

Cables

EL Series

ER Series

CID2, GSX & GSM Series

CID2, SLM & SLG Series

Why Consider Roller Screw Technology

Designers have five basic choices when it comes to achieving controlled linear motion. The table on page 3 gives you a quick overview of what general advantages are associated with each. Because the roller screw technology common to all Exlar linear actuators might not be familiar to everyone using this catalog, allow us to present a general overview.

Roller Screw Basics

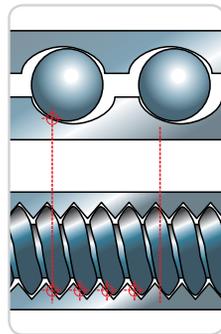
A roller screw is a mechanism for converting rotary torque into linear motion in a similar manner to acme screws or ball screws. But unlike those devices, roller screws can carry heavy loads for thousands of hours in the most arduous conditions. This makes roller screws the ideal choice for demanding, continuous-duty applications.

The difference is in the roller screw's design for transmitting forces. Multiple threaded helical rollers are assembled in a planetary arrangement around a threaded shaft (shown below), which converts a motor's rotary motion into linear movement of the shaft or nut.



Roller Screw vs Hydraulic & Pneumatic – Comparisons:

In applications where high loads are anticipated or faster cycling is desired, Exlar's roller screw actuators provide an attractive alternative to the hydraulic or pneumatic options. With their vastly simplified controls, electro-mechanical units using roller screws have major advantages. They do not require a complex support system of valves, pumps, filters and sensors. Thus, Exlar units take up much less space and deliver extremely long working lives with virtually no maintenance. Hydraulic fluid leaks are non-existent. Noise levels are reduced significantly. Additionally, the flexibility of computer programmed positioning can be very desirable in many applications.

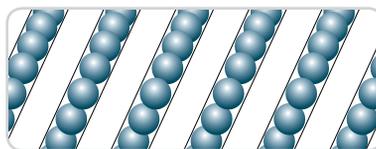


Roller vs Ball Screw Performance – Comparisons:

Loads and Stiffness: Due to design factors, the number of contact points in a ball screw is limited by the ball size. Exlar's planetary roller screw designs provide many more contact points than possible on comparably sized ball screws. Because this number of contact points is greater, roller screws have higher load carrying capacities, plus improved stiffness. In practical terms, this means

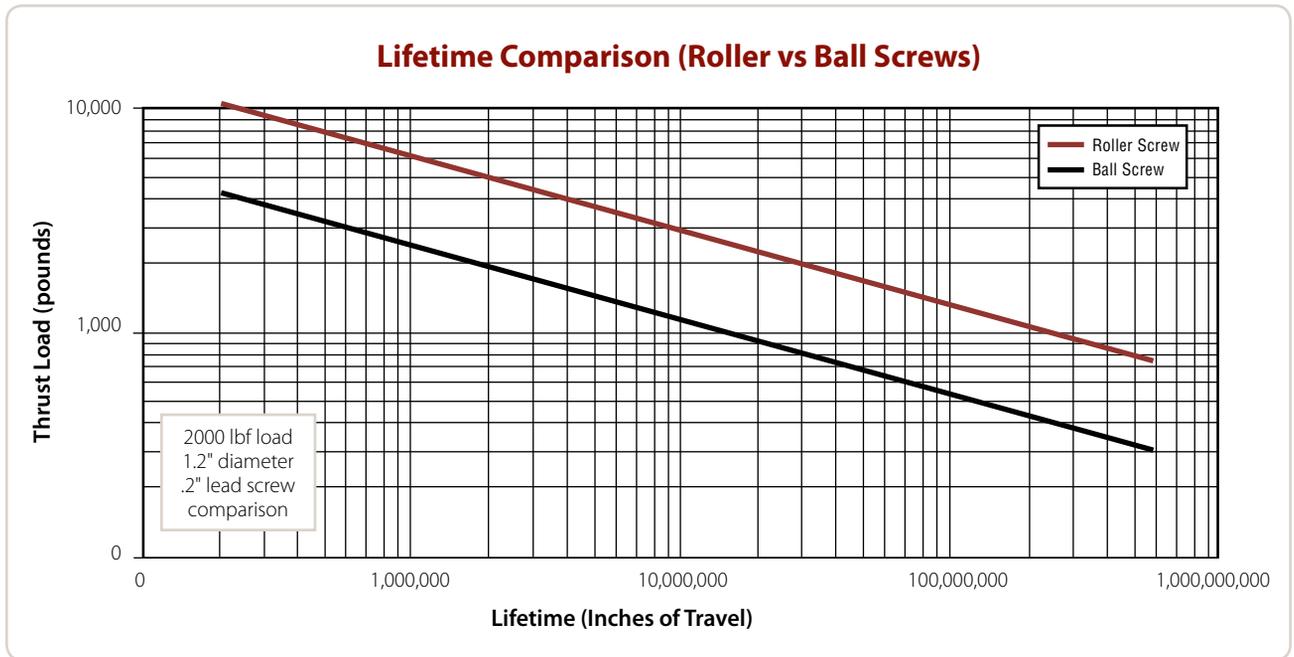
that typically an Exlar roller screw actuator takes up much less space to meet the designer's specified load rating.

Travel Life: As you would expect, with their higher load capacities, roller screws deliver major advantages in working life. Usually measured in "Inches of Travel," the relative travel lives for roller and ball screws are displayed on the graph on page 3. As you can see there, in a 2,000 lb. average load application applied to a 1.2 inch (approximate) screw diameter with a 0.2 inch (approximate) lead, you can predict that the roller screw will have an expected service life that is **15 times greater**.



Speeds: Typical ball screw speeds are limited to 2000 rpm and less, due to the interaction of the balls colliding with each other as the race rotates. In contrast, the

rollers in a roller screw are fixed in planetary fashion by journals at the ends of the nut and therefore do not have this limitation. Hence, roller screws can work at 5000 rpm and higher – producing comparably higher linear travel rates.



Roller Screw vs. Other Linear Motion Technologies (Used in electronic positioning applications)

	EXLAR ROLLER SCREWS	ACME SCREWS	BALL SCREWS	HYDRAULIC CYLINDERS	PNEUMATIC CYLINDERS
Load ratings	Very High	High	High	Very High	High
Lifetime	Very long, many times greater than ball screw	Very low, due to high friction & wear	Moderate	Can be long with proper maintenance	Can be long with proper maintenance
Speed	Very high	Low	Moderate	Moderate	Very high
Acceleration	Very high	Low	Moderate	Very high	Very high
Electronic Positioning	Easy	Moderate	Easy	Difficult	Very Difficult
Stiffness	Very high	Very high	Moderate	Very high	Very low
Shock Loads	High	Very high	Moderate	Very high	High
Relative Space Requirements	Minimum	Moderate	Moderate	High	High
Friction	Low	High	Low	High	Moderate
Efficiency	>90%	approx 40%	>90%	<50%	<50%
Installation	Compatible with standard servo electronic controls	User may have to engineer a motion/actuator interface	Compatible with standard servo electronic controls	Complex, requires servo-valves, high pressure plumbing, filtering, pumps linear positioning & sensing	Very complex requires servo-valves, plumbing, filtering, compressors linear positioning & sensing
Maintenance	Very low	High, due to poor wear characteristics	Moderate	Very high	High
Environmental	Minimum	Minimum	Minimum	Hydraulic fluid leaks & disposal	High noise levels

GS Series Linear Actuators with Integrated Motor

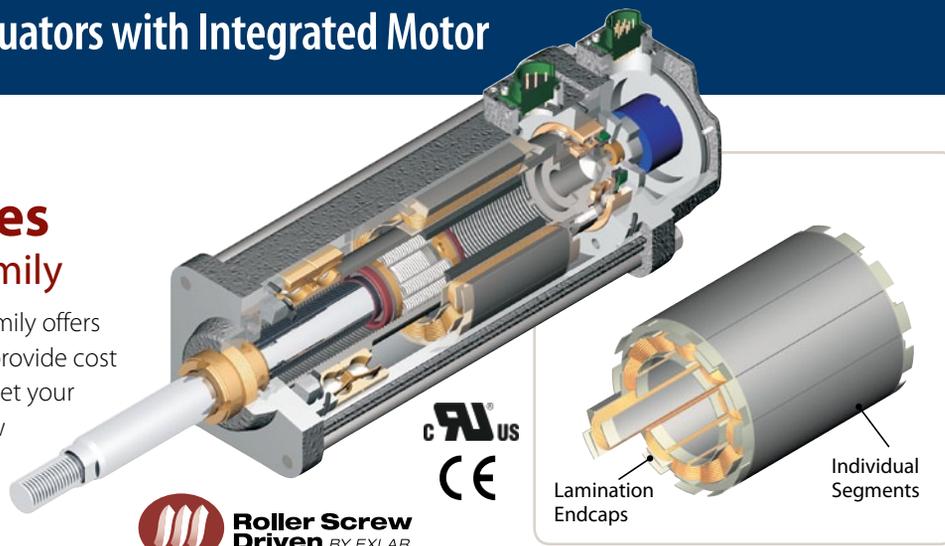
Exlar GS Series Linear Actuator Family

The GS Series linear actuator family offers you two grades of actuator to provide cost effective options in order to meet your application's requirements. View the chart below to compare the GSX and GSM models.

All GS Series actuators use a specially designed roller screw mechanism for converting electric motor power into linear motion within the actuator. Planetary rollers assembled around the actuator's extending rod follow threads which are precisely machined on the inside surface of the actuator's hollow armature. Linear motion is produced in precise synchronization with the armature rotation. Because this roller screw mechanism has an inherently larger cumulative contact surface, these actuators have a much longer working life, and can handle heavier loads at higher speeds than is possible from a similarly sized unit built around a ball screw system.

Exlar's T-LAM™ segmented lamination stator technology delivers higher continuous motor torque than is available in traditionally wound motors. T-LAM technology consists of stator segments, each containing individual phase wiring for maximum motor performance. The improved efficiencies of the GSX Series are a result of the limited heat generation qualities inherent in the segmented stator design as seen above. The elimination of end turns in the stator, and use of thermally conductive potting removes the parts most susceptible to failure in a traditional stator. Other design advantages include:

- Neodymium-iron-boron magnets provide high flux density and maximum motor torque.
- Thermally conductive potting of the entire stator provides increased heat dissipation and provides protection from contamination in oil-cooled units.
- Each stator segment contains individual phase wiring. External winding of individual segments provides maximum slot fill for maximum motor performance.
- Motors with T-LAM technology have Class 180 H insulation systems compliant with UL requirements.
- UL recognized component.
- Motors with T-LAM technology are CE compliant



The Actuator & Motor, All in one Compact Unit

With other actuator technologies, customers are usually responsible for engineering the completed linear motion system. This usually includes purchasing the motor, gear reducer, timing belt, mounting hardware, flexible couplings, etc. separately. Then they all must be assembled to perform properly in a given application.

GS Series actuators eliminate all this systems engineering. These units are single, fully integrated component packages – much smaller than traditional rotary-to-linear conversion mechanisms.

Designed for Closed Loop Servo Systems

Their brushless servo design means GS Series units can be used in advanced closed-loop servo systems when velocity and positioning is required. Position feedback can be delivered in a number of different forms. These include resolvers, encoders or internally mounted linear position feedback sensors.

GSX and GSM Differences	GSX (pg 4)	GSM (pg 42)
Roller Screw Option	High Capacity	Standard Capacity
Ingress Protection	IP65S	IP54S (IP65S optional)
No. of Stacks	1, 2, 3	1, 2
Life BSY (Ball Screw Years)	15X	2 to 5X
Oil Cooling	Yes	No
Food Grade Paint	Yes	No
Electroless Nickel Housing	Yes	Yes
Stainless Steel Case	Yes	No
Hard Coat Anodized	Yes	Yes
LVDT FB	Yes (except 2" frame)	Yes (except 2" frame)
5.5 in. Frame	Yes	No
7 in. Frame	Yes	No
Force (lbf)	92 - 15,000	92 - 3,966
1.0 Lead	50 & 60 only	No
Rear Brake	all	all
Speeds (ips)	5 - 40	5 - 37.5
Electroless Nickel Connectors	Yes	Yes
Backlash (in)	.004	.008

GSX Series—High Capacity Roller Screw Option

For applications that require long life and continuous duty, even in harsh environments the GSX Series actuator offers a robust solution. The life of the GSX Series can exceed that of a ball screw actuator by 15X while delivering high speeds and high forces. This compact package has all the advantages that our GS Series offers.

Sealed for Long Life with Minimum Maintenance

GSX Series actuators have strong advantages whenever outside contaminants are an issue. In most rotary-to-linear devices, critical mechanisms are exposed to the environment. Thus, they must be frequently inspected, cleaned and lubricated.

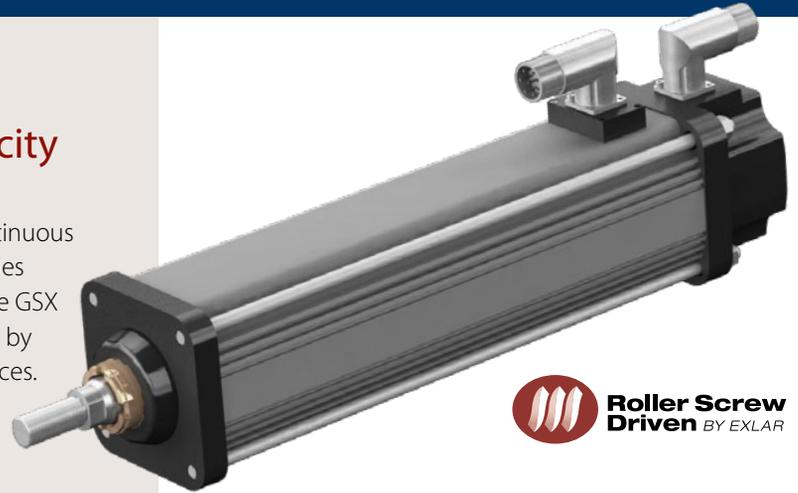
In contrast, the converting components in all Exlar GSX units are mounted within the sealed motor housing. With a simple bushing and seal arrangement on the smooth extending rod, abrasive particles or other contaminants are prevented from reaching the actuator's critical mechanisms. This assures trouble-free operation even in the most harsh environments.

Lubrication requirements are minimal. GSX actuators can be lubricated with either grease or recirculated oil. Grease lubricated units will run up to 10,000 hours without regreasing. Recirculated oil systems eliminate this type of maintenance altogether. A GSX Series actuator with a properly operating recirculating oil system will operate indefinitely without any other lubrication requirements.

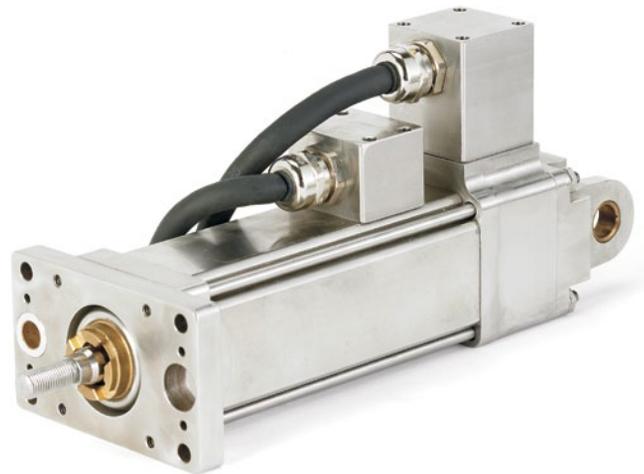
Available in Five Frame Sizes

2" GSX20 3" GSX30 4" GSX40
5" GSX50 7" GSX60

If you need a custom design, your local sales representative will work with you to engineer a solution specifically tailored to your application.



GSX Series



Feature	Standard	Optional
External anti-rotate mechanism	No	Yes
Internal Anti-rotate	No	Yes
Pre-loaded follower	No	Yes
Electric brake	No	Yes
External End switches	No	Yes
Connectors	MS or Threaded Circular Style Connectors	Electroless Nickel Connectors/ Male NPT with Potted Leads/ Manufacturers Connectors
Mounting Style	Extended Tie Rods, Side Tapped Mounting Holes, Trunnion, Rear Clevis, Front or Rear Flange	Custom Mountings
Rod End	Male or Female: U.S. Standard or Metric	Specials Available To Meet OEM Requirements
Lubrication	Greased, Oil Connection Ports are Built-in for Customer Supplied Recirculated Oil Lubrication	Specials Available To Meet OEM Requirements
Primary Feedback	Standard Encoders or Resolvers to Meet Most Amplifier Requirements	Custom Feedback
Absolute Linear Feedback	No	ICT, including signal conditioner

GSX Series Linear Actuators with Integrated Motor

Exlar GSX Series Linear Actuators Applications Include:

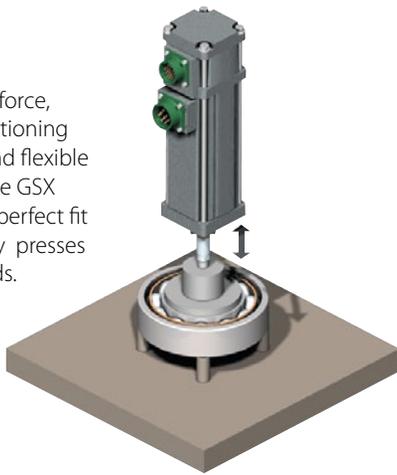
Hydraulic cylinder replacement
 Ball screw replacement
 Pneumatic cylinder replacement
 Chip and wafer handling
 Automated flexible fixturing
 Dispensers
 Machine tool
 Automated assembly
 Parts clamping
 Automatic tool changers
 Volumetric pumps

Medical equipment
 Conveyor diverters / gates
 Plastics equipment
 Cut-offs
 Die cutters
 Packaging machinery
 Entertainment
 Sawmill equipment
 Open / close doors
 Fillers
 Formers
 Precision grinders
 Indexing stages

Lifts
 Product sorting
 Material cutting
 Material handling
 Riveting / fastening / joining
 Molding
 Volumetric pumps
 Semiconductor
 Pick and place systems
 Robot manipulator arms
 Simulators
 Precision valve control

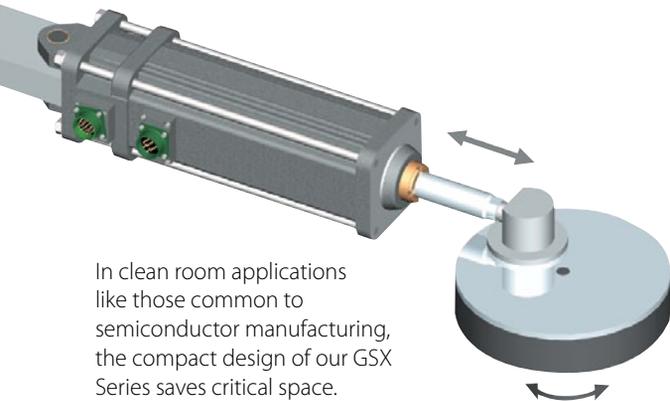
Ventilation control systems
 Pressing
 Process control
 Tube bending
 Welding
 Stamping
 Test stands
 Tension control
 Web guidance
 Wire winding
 Food Processing

Repeatable force, reliable positioning accuracy, and flexible control make GSX actuators a perfect fit for assembly presses or test stands.

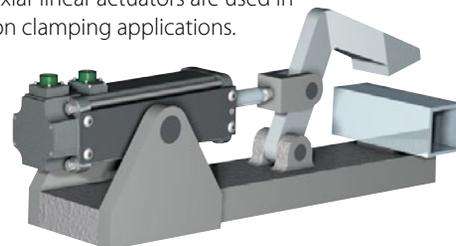


Because they cycle quickly and can be synchronized to line speeds, Exlar actuators produce dramatic improvements in web control applications.

In clean room applications like those common to semiconductor manufacturing, the compact design of our GSX Series saves critical space.



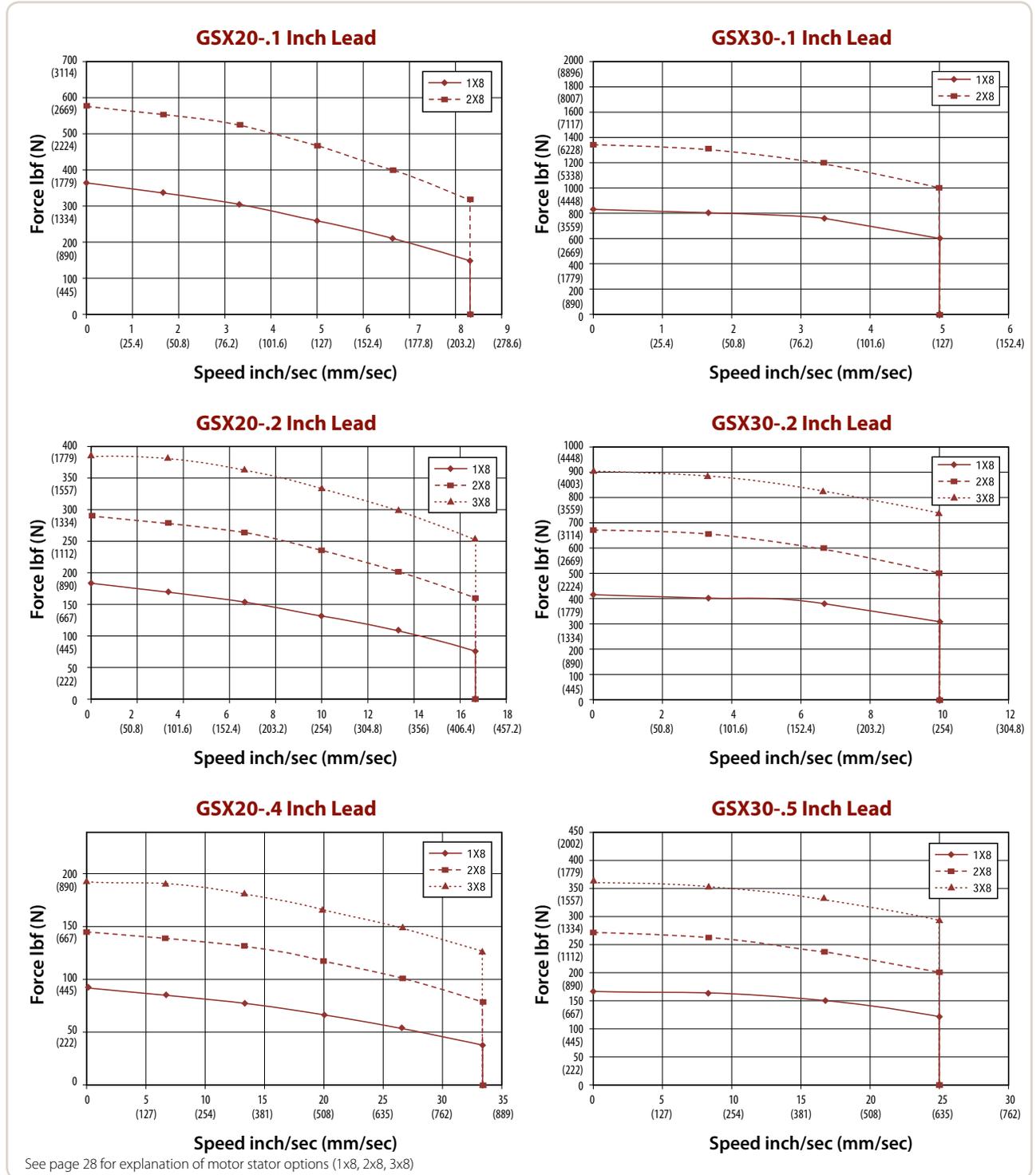
Repeatable force control plus positioning accuracy extends the life of costly tools when Exlar linear actuators are used in precision clamping applications.



GSX Series Speed vs. Force Curves

These charts represent typical linear speed versus linear force curves for the GSX actuators using common brushless motor amplifiers. The GSX Series are compatible with many different brushless motor amplifiers, and differences in the

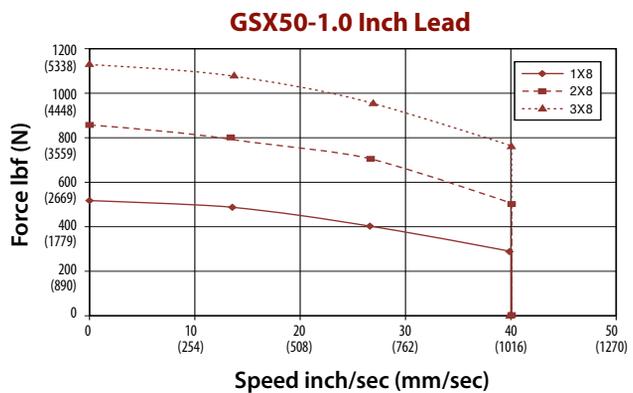
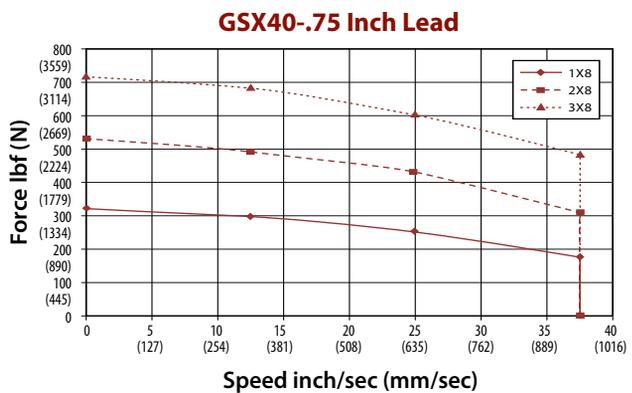
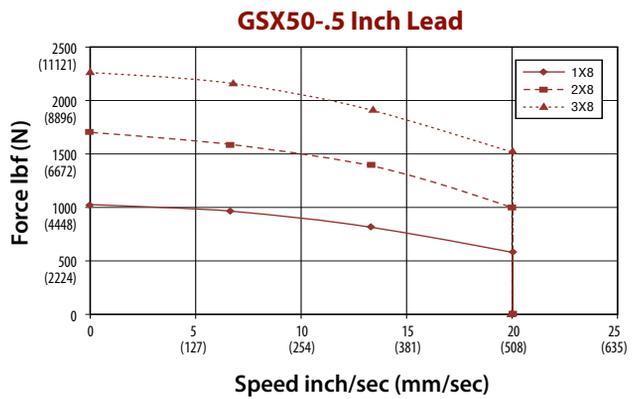
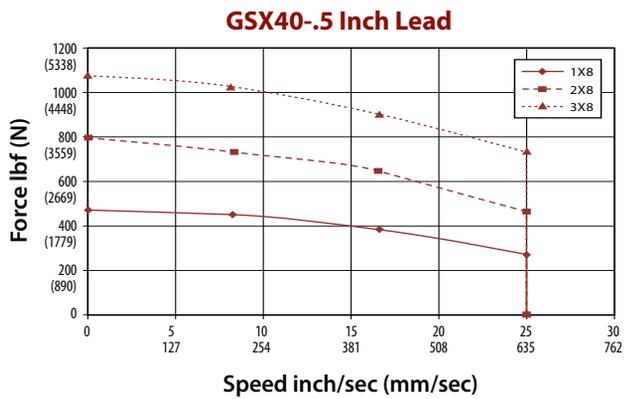
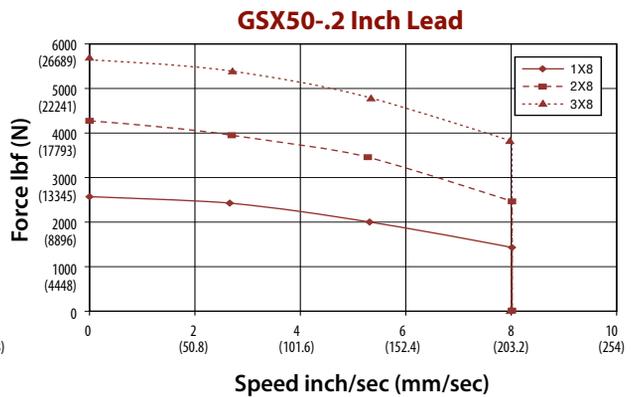
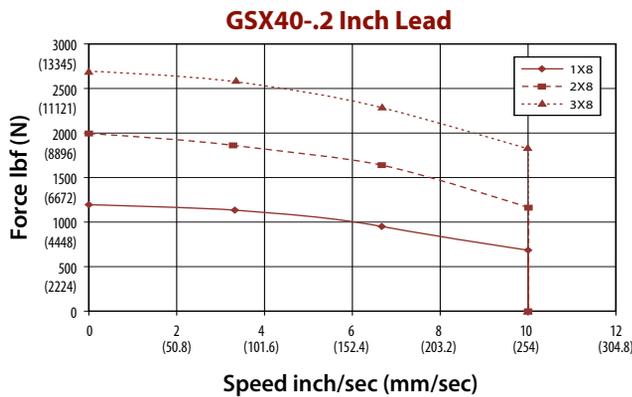
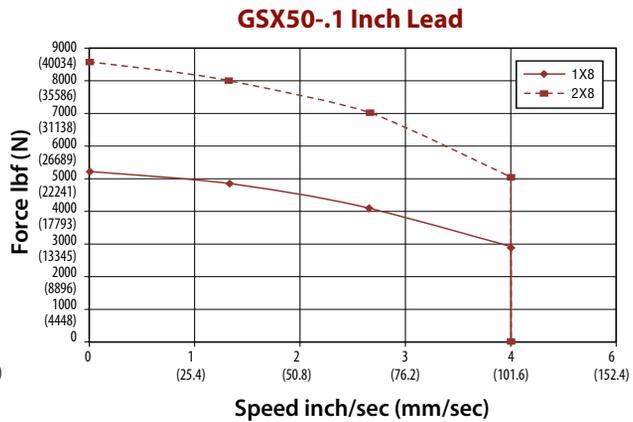
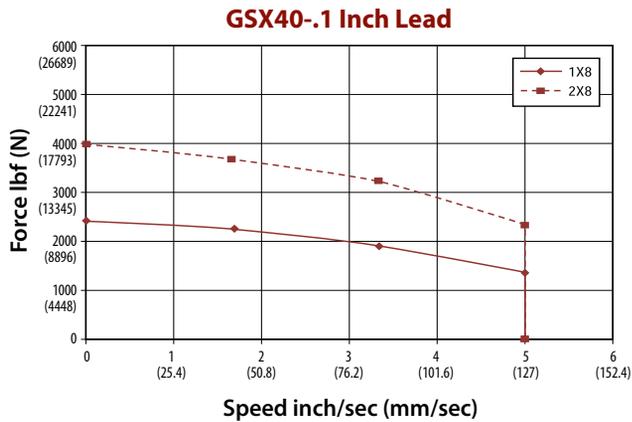
performance ratings of these amplifiers can alter the actuator's performance. Thus, the curves below should be used for estimation only. (Further information is available by contacting your local sales representative.)



Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4" for GSX20 and 10" x 10" x 3/8" for GSX30

GSX Series Linear Actuators with Integrated Motor

GSX Series Speed vs. Force Curves



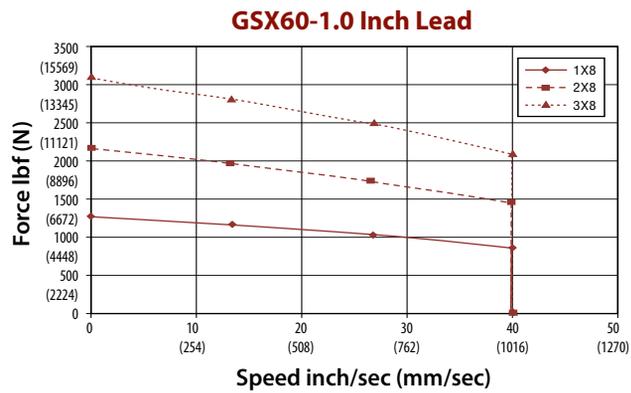
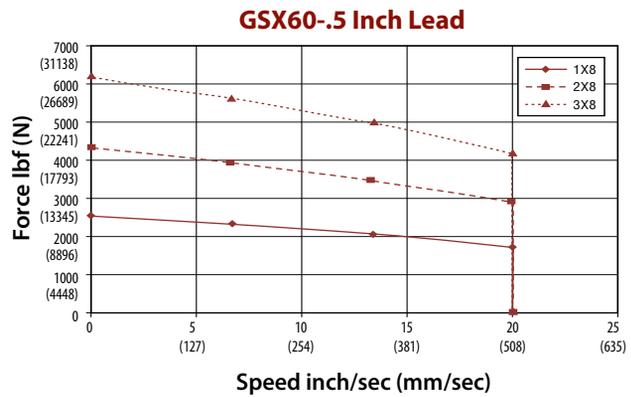
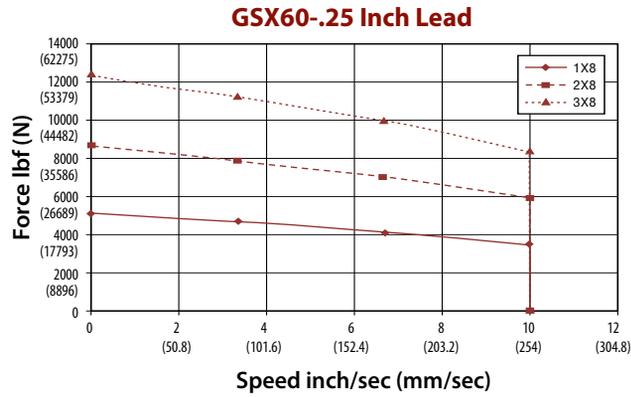
See page 28 for explanation of motor stator options (1x8, 2x8, 3x8)

Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2" for GSX40 and 12" x 12" x 1/2" for GSX50

GSX Series Speed vs. Force Curves

These charts represent typical linear speed versus linear force curves for GSX actuators using common brushless motor amplifiers. The GSX Series are compatible with many different brushless motor amplifiers, and differences in the

performance ratings of these amplifiers can alter the actuator's performance. Thus, the curves below should be used for estimation only. (Further information is available by contacting your local sales representative.)



See page 28 for explanation of motor stator options (1x8, 2x8, 3x8)

GSX Series Linear Actuators with Integrated Motor

GSX Series Lifetime Curves

The L_{10} expected life of a roller screw linear actuator is expressed as the linear travel distance that 90% of properly maintained roller screws manufactured are expected to meet or exceed. For higher than 90% reliability, the result should be multiplied by the following factors: 95% x 0.62; 96% x 0.53; 97% x 0.44; 98% x 0.33; 99% x 0.21. This is not a guarantee and these charts should be used for estimation purposes only.

The underlying formula that defines this value is:

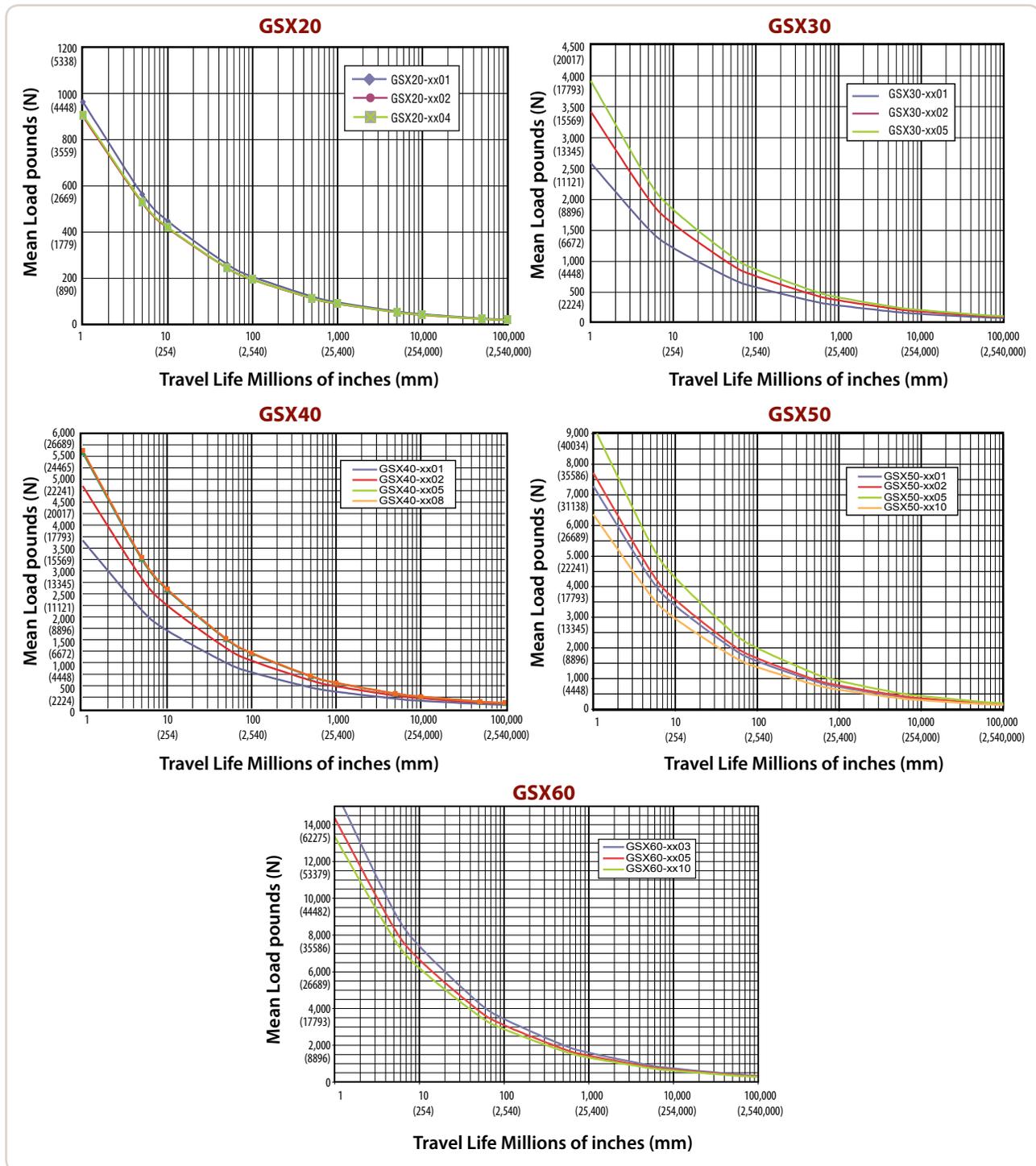
Travel life in millions of inches, where:

C = Dynamic load rating (lbf)

F = Cubic mean applied load (lbf) $L_{10} = \left(\frac{C}{F}\right)^3 \times S$

S = Roller screws lead (inches)

All curves represent properly lubricated and maintained actuators.



GSX Series Linear Actuators with Integrated Motor

GSX20 & GSX30 Performance Specifications

Model No.	Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Continuous Force Rating lb (N) 1/2/3 stack	Max Velocity in/sec (mm/sec)	Maximum Static Load lb (N)	Armature Inertia** lb-in-s ² (Kg-m ²)	Dynamic Load Rating lb (N)	Weight (approx.) lb (kg)
GSX20-0301	2.25 (57)	3 (76)	0.1 (2.54)	367/578/NA (1,632/2,571/NA)	8.33 (211.67)	1250 (5560)	0.00101 (0.000114)	2075 (9230)	6.5 (2.9)
GSX20-0302			0.2 (5.08)	195/307/NA (867/1,366/NA)	16.77 (423.33)			1540 (6850)	
GSX20-0304			0.4 (10.16)	103/163/NA (459/723/NA)	33.33 (846.67)			1230 (5471)	
GSX20-0601	2.25 (57)	6 (152)	0.1 (2.54)	367/578/NA (1,632/2,571/NA)	8.33 (211.67)	1250 (5560)	0.00114 (0.000129)	2075 (9230)	8.0 (3.6)
GSX20-0602			0.2 (5.08)	195/307/409 (867/1,366/1,817)	16.67 (423.33)			1540 (6850)	
GSX20-0604			0.4 (10.16)	103/163/216 (459/723/962)	33.33 (846.67)			1230 (5471)	
GSX20-1001	2.25 (57)	10 (254)	0.1 (2.54)	367/578/NA (1,632/2,571/NA)	8.33 (211.67)	1250 (5560)	0.00133 (0.000150)	2075 (9230)	9.5 (4.3)
GSX20-1002			0.2 (5.08)	195/307/409 (867/1,366/1,817)	16.67 (423.33)			1540 (6850)	
GSX20-1004			0.4 (10.16)	103/163/216 (459/723/962)	33.33 (846.67)			1230 (5471)	
GSX20-1201	2.25 (57)	12 (305)	0.1 (2.54)	367/578/NA (1,632/2,571/NA)	8.33 (211.67)	1250 (5560)	0.00143 (0.000162)	2075 (9230)	11.0 (4.9)
GSX20-1202			0.2 (5.08)	195/307/409 (867/1,366/1,817)	16.67 (423.33)			1540 (6850)	
GSX20-1204			0.4 (10.16)	103/163/216 (459/723/962)	33.33 (846.67)			1230 (5471)	
GSX30-0301	3.125 (79)	3 (76)	0.1 (2.54)	792/1,277/NA (3,521/5,680/NA)	5 (127)	2700 (12010)	0.00319 (0.000360)	5516 (24536)	9.5 (4.3)
GSX30-0302			0.2 (5.08)	449/724/NA (1,995/3,219/NA)	10 (254)			5800 (25798)	
GSX30-0305			0.5 (12.7)	190/306/NA (845/1,363/NA)	25 (635)			4900 (21795)	
GSX30-0601	3.125 (79)	5.9 (152)	0.1 (2.54)	792/1,277/NA (3,521/5,680/NA)	5 (127)	2700 (12010)	0.00361 (0.000408)	5516 (24536)	11.5 (5.2)
GSX30-0602			0.2 (5.08)	449/724/1,020 (1,995/3,219/4,537)	10 (254)			5800 (25798)	
GSX30-0605			0.5 (12.7)	190/306/432 (845/1,363/1,922)	25 (635)			4900 (21795)	
GSX30-1001	3.125 (79)	10 (254)	0.1 (2.54)	792/1,277/NA (3,521/5,680/NA)	5 (127)	2700 (12010)	0.00416 (0.00047)	5516 (24536)	19 (8.6)
GSX30-1002			0.2 (5.08)	449/724/1,020 (1,995/3,219/4,537)	10 (254)			5800 (25798)	
GSX30-1005			0.5 (12.7)	190/306/432 (845/1,363/1,922)	25 (635)			4900 (21795)	
GSX30-1201	3.125 (79)	12 (305)	0.1 (2.54)	792/1,277/NA (3,521/5,680/NA)	5 (127)	2700 (12010)	0.00443 (0.000501)	5516 (24536)	20.5 (9.3)
GSX30-1202			0.2 (5.08)	449/724/1,020 (1,995/3,219/4,537)	10 (254)			5800 (25798)	
GSX30-1205			0.5 (12.7)	190/306/432 (845/1,363/1,922)	25 (635)			4900 (21795)	
GSX30-1401	3.125 (79)	14 (356)	0.1 (2.54)	792/1,277/NA (3,521/5,680/NA)	5 (127)	2700 (12010)	0.00473 (0.000534)	5516 (24536)	20.5 (9.3)
GSX30-1402			0.2 (5.08)	449/724/1,020 (1,995/3,219/4,537)	10 (254)			5800 (25798)	
GSX30-1405			0.5 (12.7)	190/306/432 (845/1,363/1,922)	25 (635)			4900 (21795)	
GSX30-1801	3.125 (79)	18 (457)	0.1 (2.54)	792/1,277/NA (3,521/5,680/NA)	5 (127)	2700 (12010)	0.00533 (0.000602)	5516 (24536)	25 (11.3)
GSX30-1802			0.2 (5.08)	449/724/1,020 (1,995/3,219/4,537)	10 (254)			5800 (25798)	
GSX30-1805			0.5 (12.7)	190/306/432 (845/1,363/1,922)	25 (635)			4900 (21795)	
GSX30-2401	3.125 (79)	24 (610)	0.1 (2.54)	792/1,277/NA (3,521/5,680/NA)	5 (127)	2700 (12010)	0.00615 (0.000695)	5516 (24536)	30 (13.6)
GSX30-2402			0.2 (5.08)	449/724/1,020 (1,995/3,219/4,537)	10 (254)			5800 (25798)	
GSX30-2405			0.5 (12.7)	190/306/432 (845/1,363/1,922)	25 (635)			4900 (21795)	

**Inertia +/- 5%
See page 13 for definition of terms.

Specifications subject to change without notice.

GSX Series Linear Actuators with Integrated Motor

GSX40 Performance Specifications

Model No.	Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Continuous Force Rating lb (N) 1/2/3 stack	Max Velocity in/sec (mm/sec)	Maximum Static Load lb (N)	Armature Inertia** lb-in-s ² (Kg-m ²)	Dynamic Load Rating lb (N)	Weight (approx.) lb (kg)
GSX40-0401	3.9 (99)	4 (102)	0.1 (2.54)	2,089/NA/NA (9,293/NA/NA)	5 (127)	5400 (24020)	0.0140 (0.001582)	7900 (35141)	16 (7.3)
GSX40-0402			0.2 (5.08)	1,194/NA/NA (5,310/NA/NA)	10 (254)			8300 (36920)	
GSX40-0405			0.5 (12.7)	537/NA/NA (2,390/NA/NA)	25 (635)			7030 (31271)	
GSX40-0408			0.75 (19.05)	358/NA/NA (1,593/NA/NA)	37.5 (953)			6335 (28179)	
GSX40-0601	3.9 (99)	6 (152)	0.1 (2.54)	2,089/3,457/NA (9,293/15,377/NA)	5 (127)	5400 (24020)	0.0152 (0.001717)	7900 (35141)	20 (9.1)
GSX40-0602			0.2 (5.08)	1,194/1,975/NA (5,310/8,787/NA)	10 (254)			8300 (36920)	
GSX40-0605			0.5 (12.7)	537/889/NA (2,390/3,954/NA)	25 (635)			7030 (31271)	
GSX40-0608			0.75 (19.05)	358/593/NA (1,593/2,636/NA)	37.5 (953)			6335 (28179)	
GSX40-0801	3.9 (99)	8 (203)	0.1 (2.54)	2,089/3,457/NA (9,293/15,377/NA)	5 (127)	5400 (24020)	0.0163 (0.001842)	7900 (35141)	24 (10.9)
GSX40-0802			0.2 (5.08)	1,194/1,975/2,687 (5,310/8,787/11,950)	10 (254)			8300 (36920)	
GSX40-0805			0.5 (12.7)	537/889/1,209 (2,390/3,954/5,378)	25 (635)			7030 (31271)	
GSX40-0808			0.75 (19.05)	358/593/806 (1,593/2,636/3,585)	37.5 (953)			6335 (28179)	
GSX40-1001	3.9 (99)	10 (254)	0.1 (2.54)	2,089/3,457/NA (9,293/15,377/NA)	5 (127)	5400 (24020)	0.0175 (0.001977)	7900 (35141)	28 (12.7)
GSX40-1002			0.2 (5.08)	1,194/1,975/2,687 (5,310/8,787/11,950)	10 (254)			8300 (36920)	
GSX40-1005			0.5 (12.7)	537/889/1,209 (2,390/3,954/5,378)	25 (635)			7030 (31271)	
GSX40-1008			0.75 (19.05)	358/593/806 (1,593/2,636/3,585)	37.5 (953)			6335 (28179)	
GSX40-1201	3.9 (99)	12 (305)	0.1 (2.54)	2,089/3,457/NA (9,293/15,377/NA)	5 (127)	5400 (24020)	0.0186 (0.002102)	7900 (35141)	32 (14.5)
GSX40-1202			0.2 (5.08)	1,194/1,975/2,687 (5,310/8,787/11,950)	10 (254)			8300 (36920)	
GSX40-1205			0.5 (12.7)	537/889/1,209 (2,390/3,954/5,378)	25 (635)			7030 (31271)	
GSX40-1208			0.75 (19.05)	358/593/806 (1,593/2,636/3,585)	37.5 (953)			6335 (28179)	
GSX40-1801	3.9 (99)	18 (457)	0.1 (2.54)	2,089/3,457/NA (9,293/15,377/NA)	5 (127)	5400 (24020)	0.022 (0.002486)	7900 (35141)	44 (20)
GSX40-1802			0.2 (5.08)	1,194/1,975/2,687 (5,310/8,787/11,950)	10 (254)			8300 (36920)	
GSX40-1805			0.5 (12.7)	537/889/1,209 (2,390/3,954/5,378)	25 (635)			7030 (31271)	

**Inertia +/- 5%
See page 13 for definition of terms.

Specifications subject to change without notice.

GSX50 & GSX60 Performance Specifications

Model No.	Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Continuous Force Rating lb (N) 1/2/3 stack	Max Velocity in/sec (mm/sec)	Maximum Static Load lb (N)	Armature Inertia** lb-in-s ² (Kg-m ²)	Dynamic Load Rating lb (N)	Weight (approx.) lb (kg)
GSX50-0601	5.5 (140)	6 (152)	0.1 (2.54)	4,399/7,150/NA (19,568/31,802/NA)	4 (101.6)	13200 (58717)	0.03241 (0.003662)	15693 (69806)	54 (24)
GSX50-0602			0.2 (5.08)	2,578/4,189/NA (11,466/18,634/NA)	8 (203)			13197 (58703)	
GSX50-0605			0.5 (12.7)	1,237/2,011/NA (5,503/8,944/NA)	20 (508)			11656 (51848)	
GSX50-0610			1.0 (25.4)	619/1,005/NA (2,752/4,472/NA)	40 (1016)			6363 (28304)	
GSX50-1001	5.5 (140)	10 (254)	0.1 (2.54)	4,399/7,150/NA (19,568/31,802/NA)	4 (101.6)	13200 (58717)	0.03725 (0.004209)	15693 (69806)	62 (28)
GSX50-1002			0.2 (5.08)	2,578/4,189/5,598 (11,466/18,634/24,901)	8 (203)			13197 (58703)	
GSX50-1005			0.5 (12.7)	1,237/2,011/2,687 (5,503/8,944/11,953)	20 (508)			11656 (51848)	
GSX50-1010			1.0 (25.4)	619/1,005/1,344 (2,752/4,472/5,976)	40 (1016)			6363 (28304)	
GSX50-1402	5.5 (140)	14 (356)	0.2 (5.08)	2,578/4,189/5,598 (11,466/18,634/24,901)	8 (203)	13200 (58717)	0.04208 (0.004756)	13197 (58703)	70 (32)
GSX50-1405			0.5 (12.7)	1,237/2,011/2,687 (5,503/8,944/11,953)	20 (508)			11656 (51848)	
GSX60-0603	7.0 (178)	6 (152)	0.25 (6.35)	4,937/8,058/11,528 (21,958/35,843/51,278)	10 (254)	25000 (111200)	0.1736 (0.019614)	25300 (112540)	69 (31)
GSX60-0605			0.5 (12.7)	2,797/4,566/6,533 (12,443/20,311/29,058)	20 (508)			22800 (101420)	
GSX60-0610			1.0 (25.4)	1,481/2,417/3,459 (6,588/10,753/15,383)	40 (1018)			21200 (94302)	
GSX60-1003	7.0 (178)	10 (254)	0.25 (6.35)	4,937/8,058/11,528 (21,958/35,843/51,278)	10 (254)	25000 (111200)	0.1943 (0.021953)	25300 (112540)	101 (46)
GSX60-1005			0.5 (12.7)	2,797/4,566/6,533 (12,443/20,311/29,058)	20 (508)			22800 (101420)	
GSX60-1010			1.0 (25.4)	1,481/2,417/3,459 (6,588/10,753/15,383)	40 (1018)			21200 (94302)	

**Inertia +/- 5%

Specifications subject to change without notice.

DEFINITION OF TERMS:

Continuous Force Rating: The linear force produced by the actuator at continuous motor torque.

Max Velocity: The linear velocity that the actuator will achieve at rated motor rpm.

Maximum Static Load: The mechanical load limit of the actuator if re-circulated oil or other cooling method is used to allow higher than rated torque from the motor.

Armature Inertia: The rotary inertia of the armature of the GSX Series actuators. For calculation purposes, this value includes the screw inertia in a GSX actuator.

Dynamic Load Rating: A design constant used in calculating the estimated travel life of the roller screw. The cubic mean load is the load at which the device will perform one million revolutions.

GSX offers 1, 2, or 3 stack stators providing 3 torque force levels.

GSX Series Linear Actuators with Integrated Motor

GSX20 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.004 (.10)											
Maximum Backlash (pre-loaded)	in (mm)	0.0											
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)											
Maximum Radial Load	lb (N)	20 (90)											
Environmental Rating: Standard		IP65S											
Motor Stator		118	138	158	168	218	238	258	268	318*	338*	358*	368*
RMS SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	7.6 (0.86)	7.3 (0.83)	7.0 (0.79)	7.0 (0.79)	11.9 (1.34)	11.5 (1.30)	11.0 (1.25)	11.3 (1.28)	15.0 (1.70)	15.3 (1.73)	14.6 (1.65)	14.9 (1.69)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	2.5 (0.28)	5.2 (0.59)	7.5 (0.85)	9.5 (1.07)	2.5 (0.28)	5.2 (0.59)	8.6 (0.97)	10.1 (1.15)	2.5 (0.29)	5.3 (0.59)	8.8 (0.99)	10.1 (1.15)
Continuous Current Rating:	Greased (IG) A	3.4	1.6	1.0	0.8	5.4	2.5	1.4	1.2	6.6	3.2	1.9	1.6
	Oiled (IL) A	6.9	3.1	2.1	1.6	10.8	4.9	2.9	2.5	13.2	6.5	3.7	3.3
Peak Current Rating	A	6.9	3.1	2.1	1.6	10.8	4.9	2.9	2.5	13.2	6.5	3.7	3.3
0-PK SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	7.6 (0.86)	7.3 (0.83)	7.0 (0.79)	7.0 (0.79)	11.9 (1.34)	11.5 (1.30)	11.0 (1.25)	11.3 (1.28)	15.0 (1.70)	15.3 (1.73)	14.6 (1.65)	14.9 (1.69)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	1.7 (0.20)	3.7 (0.42)	5.3 (0.60)	6.7 (0.76)	1.7 (0.20)	3.7 (0.42)	6.1 (0.69)	7.2 (0.81)	1.8 (0.20)	3.7 (0.42)	6.2 (0.70)	7.2 (0.81)
Continuous Current Rating	Greased (IG) A	4.9	2.2	1.5	1.2	7.6	3.5	2.0	1.8	9.4	4.6	2.6	2.3
	Oiled (IL) A	9.7	4.5	2.9	2.3	15.2	7.0	4.1	3.5	18.7	9.2	5.3	4.7
Peak Current Rating	A	9.7	4.5	2.9	2.3	15.2	7.0	4.1	3.5	18.7	9.2	5.3	4.7
MOTOR STATOR DATA													
Voltage Constant (Ke)	Vrms/Krpm	16.9	35.5	51.5	64.8	16.9	35.5	58.6	69.3	17.3	36.0	59.9	69.3
	Vpk/Krpm	23.9	50.2	72.8	91.7	23.9	50.2	82.9	98.0	24.5	50.9	84.8	98.0
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	2.6	12.5	28.8	45.8	1.1	5.3	15.5	20.7	0.76	3.1	9.6	12.2
Inductance (L-L)(+/- 15%)	mH	4.6	21.4	47.9	68.3	2.5	10.2	28.3	39.5	1.7	7.4	18.5	27.4
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00012 (0.135)											
Brake Current @ 24 VDC	A	0.33											
Brake Holding Torque	lbf-in (Nm)	19 (2.2)											
Brake Engage/Disengage Time	ms	14/28											
Mechanical Time Constant (tm), ms	min	4.7	5.1	5.5	5.6	2.0	2.1	2.3	2.2	1.3	1.2	1.4	1.3
	max	6.6	7.2	7.9	7.9	2.8	3.0	3.3	3.1	1.8	1.8	1.9	1.8
Electrical Time Constant (te)	ms	1.8	1.7	1.7	1.5	2.2	1.9	1.8	1.9	2.3	2.4	1.9	2.2
Friction Torque	lbf-in (Nm)	1.0 (0.11)				1.1 (0.12)				1.1 (0.12)			
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	1.25 (0.14)				1.25 (0.14)				1.25 (0.14)			
Bus Voltage	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	5000											
Insulation Class		180 (H)											

All ratings at 25 degrees Celsius

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

*Refer to performance specifications on page 11 for availability of 3 stack stator by stroke/lead combination.

Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4"

Specifications subject to change without notice.

GSX30 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.004 (.10)											
Maximum Backlash (pre-loaded)	in (mm)	0.0											
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)											
Maximum Radial Load	lb (N)	30 (134)											
Environmental Rating: Standard		IP65S											
Motor Stator		118	138	158	168	218	238	258	268	318*	338*	358*	368*
RMS SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	16.9 (1.91)	16.8 (1.90)	16.3 (1.84)	16.0 (1.81)	26.9 (3.04)	27.1 (3.06)	26.7 (3.01)	27.0 (3.05)	38.7 (4.37)	38.2 (4.32)	36.2 (4.09)	36.3 (4.10)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.97)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.97)	4.4 (0.50)	8.7 (0.98)	15.6 (1.77)	17.5 (1.98)
Continuous Current Rating:	Greased (IG) A	4.3	2.2	1.2	1.0	6.9	3.5	1.9	1.7	9.7	4.9	2.6	2.3
	Oiled (IL) A	8.6	4.3	2.4	2.0	13.8	6.9	3.8	3.4	19.5	9.9	5.2	4.6
Peak Current Rating	A	8.6	4.3	2.4	2.0	13.8	6.9	3.8	3.4	19.5	9.9	5.2	4.6
0-PK SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	16.9 (1.91)	16.8 (1.90)	16.3 (1.84)	16.0 (1.81)	26.9 (3.04)	27.1 (3.06)	26.7 (3.01)	27.0 (3.05)	38.7 (4.37)	38.2 (4.32)	36.2 (4.09)	36.3 (4.10)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	3.1 (0.35)	6.2 (0.70)	11.0 (1.24)	12.4 (1.40)	3.1 (0.35)	6.2 (0.70)	11.0 (1.24)	12.4 (1.40)	3.1 (0.35)	6.1 (0.69)	11.1 (1.25)	12.4 (1.40)
Continuous Current Rating:	Greased (IG) A	6.1	3.0	1.7	1.4	9.7	4.9	2.7	2.4	13.8	7.0	3.7	3.3
	Oiled (IL) A	12.2	6.1	3.3	2.9	19.5	9.8	5.4	4.9	27.6	13.9	7.3	6.5
Peak Current Rating	A	12.2	6.1	3.3	2.9	19.5	9.8	5.4	4.9	27.6	13.9	7.3	6.5
MOTOR STATOR DATA													
Voltage Constant (Ke)	Vrms/Krpm	29.8	59.7	105.8	119.3	29.8	59.7	105.8	119.3	30.3	59.2	106.8	119.8
	(+/- 10% @ 25°C) Vpk/Krpm	42.2	84.4	149.7	168.7	42.2	84.4	149.7	168.7	42.9	83.7	151.0	169.4
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	2.7	10.8	36.3	47.9	1.1	4.4	14.1	17.6	0.65	2.6	9.3	11.6
Inductance (L-L)(+/- 15%)	mH	7.7	30.7	96.8	123.0	3.7	14.7	46.2	58.7	2.5	9.5	30.9	38.8
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00033 (0.38)											
Brake Current @ 24VDC	A	0.5											
Brake Holding Torque	lbf-in (Nm)	70 (8)											
Brake Engage/Disengage Time	ms	19/29											
Mechanical Time Constant (tm), ms	min	4.9	4.9	5.2	5.4	2.0	2.0	2.0	2.0	1.1	1.2	1.3	1.3
	max	9.4	9.5	10.1	10.5	3.9	3.8	3.9	3.8	2.2	2.3	2.5	2.5
Electrical Time Constant (te)	ms	2.9	2.8	2.7	2.6	3.3	3.4	3.3	3.3	3.8	3.7	3.3	3.3
Friction Torque	lbf-in (Nm)	1.5 (0.17)				1.7 (0.19)				1.9 (0.21)			
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	1.75 (0.20)				1.75 (0.20)				1.75 (0.20)			
Bus Voltage	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	3000											
Insulation Class		180 (H)											

All ratings at 25 degrees Celsius

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

*Refer to performance specifications on page 11 for availability of 3 stack stator by stroke/lead combination.

Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 3/8"

Specifications subject to change without notice.

GSX Series Linear Actuators with Integrated Motor

GSX40 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.004 (.10)											
Maximum Backlash (pre-loaded)	in (mm)	0.0											
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)											
Maximum Radial Load	lb (N)	40 (179)											
Environmental Rating: Standard		IP65S											
Motor Stator		118	138	158	168	218	238	258	268	338*	358*	368*	
RMS SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	47.5 (5.37)	47.5 (5.36)	45.9 (5.19)	45.4 (5.13)	75.1 (8.49)	78.6 (8.89)	78.7 (8.89)	79.5 (8.99)	106.9 (12.08)	105.3 (11.90)	106.9 (12.08)	
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	4.1 (0.46)	8.2 (0.93)	14.5 (1.64)	16.8 (1.90)	4.1 (0.46)	8.2 (0.93)	14.5 (1.64)	16.8 (1.90)	8.4 (0.95)	14.5 (1.64)	16.8 (1.90)	
Continuous Current Rating:	Greased (IG) A	12.9	6.5	3.5	3.0	20.5	10.7	6.0	5.3	14.2	8.1	7.1	
	Oiled (IL) A	25.9	12.9	7.1	6.0	40.9	21.4	12.1	10.6	28.5	16.2	14.2	
Peak Current Rating	A	25.9	12.9	7.1	6.0	40.9	21.4	12.1	10.6	28.5	16.2	14.2	
O-PK SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	47.5 (5.37)	47.5 (5.36)	45.9 (5.19)	45.4 (5.13)	75.1 (8.49)	78.6 (8.89)	78.7 (8.89)	79.5 (8.99)	106.9 (12.08)	105.3 (11.90)	106.9 (12.08)	
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	2.9 (0.33)	5.8 (0.66)	10.3 (1.16)	11.9 (1.34)	2.9 (0.33)	5.8 (0.66)	10.3 (1.16)	11.9 (1.34)	5.9 (0.67)	10.3 (1.16)	11.9 (1.34)	
Continuous Current Rating:	Greased (IG) A	18.3	9.1	5.0	4.3	28.9	15.1	8.5	7.5	20.1	11.4	10.1	
	Oiled (IL) A	36.6	18.3	10.0	8.6	57.9	30.3	17.1	15.0	40.3	22.9	20.1	
Peak Current Rating	A	36.6	18.3	10.0	8.6	57.9	30.3	17.1	15.0	40.3	22.9	20.1	
MOTOR STATOR DATA													
Voltage Constant (Ke)	Vrms/Krpm	28.0	56.0	99.3	114.6	28.0	56.0	99.3	114.6	57.3	99.3	114.6	
	Vpk/Krpm	39.6	79.2	140.5	162.1	39.6	79.2	140.5	162.1	81.0	140.5	162.1	
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	
Resistance (L-L)(+/- 5% @ 25 °C)	Ohms	0.42	1.7	5.7	7.8	0.2	0.72	2.26	3.0	0.5	1.52	2.0	
Inductance (L-L)(+/- 15%)	mH	3.0	11.9	37.5	49.9	1.2	5.4	18.2	23.1	4.0	12.0	16.0	
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00096 (1.08)											
Brake Current @ 24 VDC	A	0.67											
Brake Holding Torque	lbf-in (Nm)	97 (11)											
Brake Engage/Disengage Time	ms	20/29											
Mechanical Time Constant (tm), ms	min	4.5	4.5	4.8	4.9	2.1	1.9	1.9	1.9	1.2	1.3	1.2	
	max	6.0	6.0	6.4	6.6	2.8	2.6	2.6	2.5	1.7	1.7	1.7	
Electrical Time Constant (te)	ms	7.0	7.0	6.6	6.4	5.9	7.5	8.0	7.8	8.2	7.9	8.2	
Friction Torque	lbf-in (Nm)	2.7 (0.31)				3.0 (0.34)				3.5 (0.40)			
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	4.5 (0.51)				4.5 (0.51)				4.5 (0.51)			
Bus Voltage	Vrms	115	230	400	460	115	230	400	460	230	400	460	
Speed @ Bus Voltage	rpm	3000											
Insulation Class		180 (H)											

All ratings at 25 degrees Celsius

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

*Refer to performance specifications on page 12 for availability of 3 stack stator by stroke/lead combination.

Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2"

Specifications subject to change without notice.

GSX50 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.004 (.10)							
Maximum Backlash (pre-loaded)	in (mm)	0.0							
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)							
Maximum Radial Load	lb (N)	75 (337)							
Environmental Rating: Standard		IP65S							
Motor Stator		138	158	168	238	258	268	358*	368*
RMS SINUSOIDAL COMMUTATION									
Continuous Motor Torque	lbf-in (Nm)	107.2 (12.12)	104.8 (11.84)	109.4 (12.36)	179.9 (20.32)	178.8 (20.20)	177.8 (20.09)	237.2 (26.80)	237.6 (26.85)
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	11.8 (1.33)	20.2 (2.28)	23.6 (2.67)	11.8 (1.33)	20.2 (2.28)	23.6 (2.67)	20.2 (2.28)	15.2 (1.71)
Continuous Current Rating:	Greased (IG) A	10.2	5.8	5.2	17.0	9.9	8.4	13.1	17.5
	Oiled (IL) A	20.3	11.6	10.4	34.1	19.8	16.8	26.2	35.0
Peak Current Rating	A	20.3	11.6	10.4	34.1	19.8	16.8	26.2	35.0
O-PK SINUSOIDAL COMMUTATION									
Continuous Motor Torque	lbf-in (Nm)	107.2 (12.12)	104.8 (11.84)	109.4 (12.36)	179.9 (20.32)	178.8 (20.20)	177.8 (20.09)	237.2 (26.80)	237.6 (26.85)
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	8.3 (.94)	14.3 (1.62)	16.7 (1.88)	8.3 (0.94)	14.3 (1.62)	16.7 (1.88)	14.3 (1.62)	10.7 (1.21)
Continuous Current Rating:	Greased (IG) A	14.4	8.2	7.3	24.1	14.0	11.9	18.5	24.8
	Oiled (IL) A	28.7	16.4	14.7	48.2	27.9	23.8	37.1	49.5
Peak Current Rating	A	28.7	16.4	14.7	48.2	27.9	23.8	37.1	49.5
MOTOR STATOR DATA									
Voltage Constant (Ke)	Vrms/Krpm	80.6	138.1	161.1	80.6	138.1	161.1	138.1	103.6
(+/- 10% @ 25 °C)	Vpk/Krpm	113.9	195.3	227.9	113.9	195.3	227.9	195.3	146.5
Pole Configuration		8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25 °C)	Ohms	0.87	2.68	3.34	0.34	1.01	1.39	0.61	0.34
Inductance (L-L)(+/- 15%)	mH	21.7	63.9	78.3	10.4	27.6	41.5	20.0	11.3
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.0084 (9.5)							
Brake Current @ 24VDC	A	1							
Brake Holding Torque	lbf-in (Nm)	354 (40)							
Brake Engage/Disengage Time	ms	25/73							
Mechanical Time Constant (tm), ms	min	2.2	2.3	2.1	0.9	0.9	0.9	0.5	0.5
	max	2.8	3.0	2.7	1.1	1.1	1.1	0.7	0.7
Electrical Time Constant (te)	ms	25.0	23.9	23.4	30.6	27.3	29.9	32.6	32.7
Friction Torque	lbf-in (Nm)	4.1 (0.46)			4.6 (0.53)			5.3 (0.60)	
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	6.00 (0.68)			6.00 (0.68)			6.00 (0.68)	
Bus Voltage	Vrms	230	400	460	230	400	460	400	460
Speed @ Bus Voltage	rpm	2400							
Insulation Class		180 (H)							

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414. Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2"

Specifications subject to change without notice.

GSX Series Linear Actuators with Integrated Motor

GSX60 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.004 (.10)							
Maximum Backlash (pre-loaded)	in (mm)	0.0							
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)							
Maximum Radial Load	lb (N)	100 (445)							
Environmental Rating: Standard		IP65S							
Motor Stator		138	158	168	238	258	268	358	368
RMS SINUSOIDAL COMMUTATION									
Continuous Motor Torque	lbf-in (Nm)	254.2 (28.72)	249.9 (28.23)	261.9 (29.59)	424.8 (47.99)	423.0 (47.79)	427.5 (48.30)	595.6 (67.29)	611.6 (69.10)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	12.6 (1.42)	21.8 (2.46)	25.2 (2.84)	12.6 (1.42)	21.8 (2.46)	25.2 (2.84)	21.4 (2.42)	25.2 (2.84)
Continuous Current Rating:	Greased (IG) A	22.6	12.8	11.6	37.7	21.7	19.0	31.1	27.2
	Oiled (IL) A	45.2	25.6	23.3	75.5	43.4	38.0	62.2	54.3
Peak Current Rating	A	45.2	25.6	23.3	75.5	43.4	38.0	62.2	54.3
O-PK SINUSOIDAL COMMUTATION									
Continuous Motor Torque	lbf-in (Nm)	254.2 (28.72)	249.9 (28.23)	261.9 (29.59)	424.8 (47.99)	423.0 (47.79)	427.5 (48.30)	595.6 (67.29)	611.6 (69.10)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	8.9 (1.01)	15.4 (1.74)	17.8 (2.01)	8.9 (1.01)	15.4 (1.74)	17.8 (2.01)	15.1 (1.71)	17.8 (2.01)
Continuous Current Rating:	Greased (IG) A	31.9	18.1	16.4	53.4	30.7	26.8	44.0	38.4
	Oiled (IL) A	63.9	36.2	32.9	106.7	61.3	53.7	88.0	76.8
Peak Current Rating	A	63.9	36.2	32.9	106.7	61.3	53.7	88.0	76.8
MOTOR STATOR DATA									
Voltage Constant (Ke)	Vrms/Krpm	85.9	148.9	171.8	85.9	148.9	171.8	146.1	171.8
(+/- 10% @ 25°C)	Vpk/Krpm	121.5	210.6	243.0	121.5	210.6	243.0	206.6	243.0
Pole Configuration		8	8	8	8	8	8	8	8
Resistance (L-L) (+/- 5% @ 25°C)	Ohms	0.3	1.0	1.2	0.13	0.41	0.5	0.23	0.3
Inductance (L-L) (+/- 15%)	mH	8.3	24.8	29.4	3.9	11.8	15.8	7.5	10.3
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.02815 (31.8)							
Brake Current @ 24 VDC	A	1.45							
Brake Holding Torque	lbf-in (Nm)	708 (80)							
Brake Engage/Disengage Time	ms	53/97							
Mechanical Time Constant (tm), ms	min	3.9	4.0	3.6	1.6	1.6	1.6	1.0	0.9
	max	4.3	4.5	4.1	1.8	1.8	1.8	1.1	1.0
Electrical Time Constant (te)	ms	25.4	24.6	24.0	29.4	29.1	29.8	32.1	33.8
Friction Torque	lbf-in (Nm)	8.1 (0.91)			10.8 (1.22)			14.5 (1.64)	
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	6.00 (0.68)			6.00 (0.68)			6.00 (0.68)	
Bus Voltage	Vrms	230	400	460	230	400	460	400	460
Speed @ Bus Voltage	rpm	2400							
Insulation Class		180 (H)							

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.
 Test data derived using NEMA recommended aluminum heatsink 16" x 16" x 1"
 The GSX60-06 can only accommodate a single stack stator.

Specifications subject to change without notice.

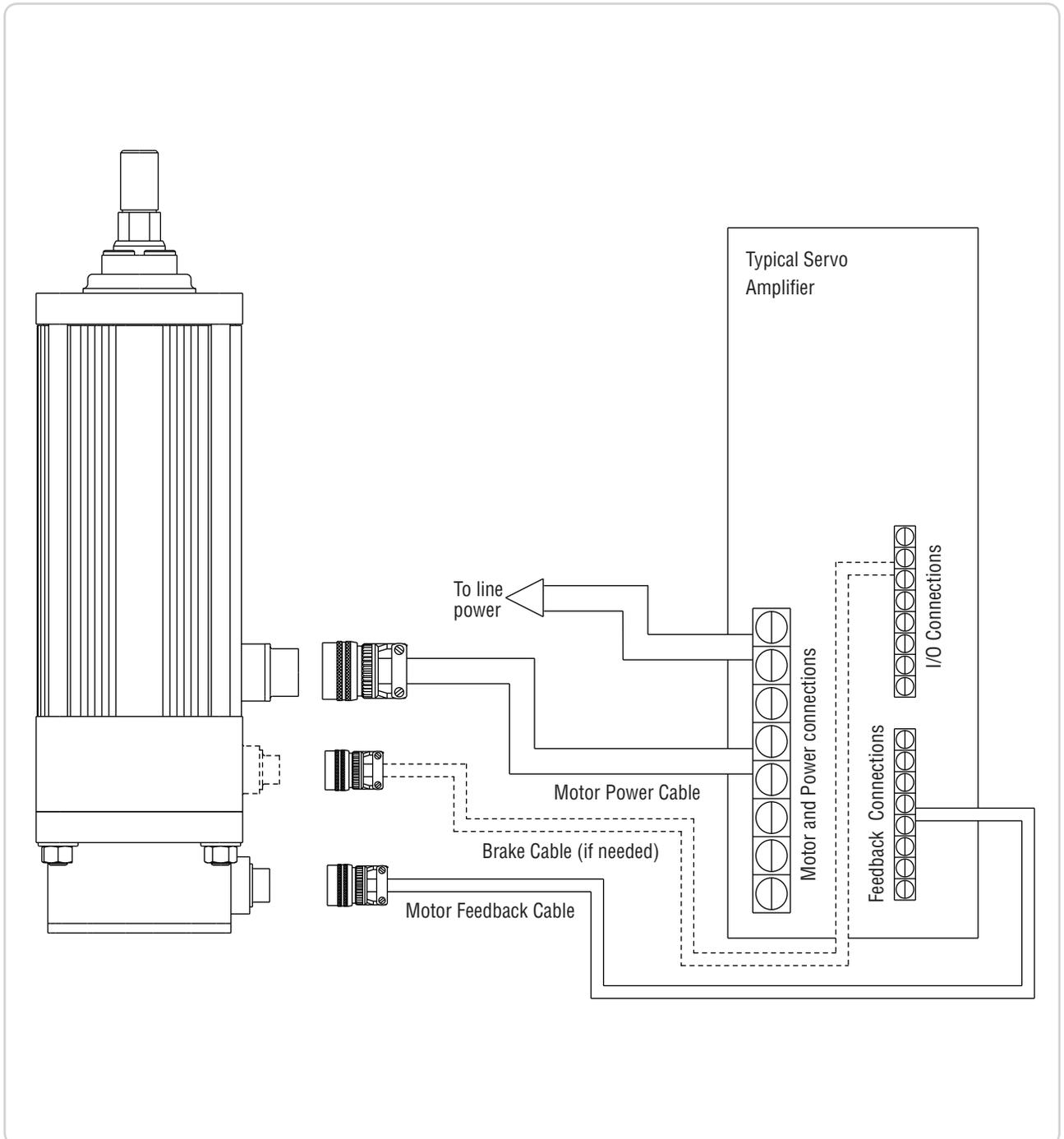
GSX Series – System Configuration

GSX Series actuators include an integrated brushless servo motor. Exlar's unique design gives users a variety of the feedback configuration options so GSX units can be powered by almost any brushless motor amplifier on the market.

This flexibility means GSX actuators can be incorporated into today's highest performance single and multi-axis

motion control systems. In anything from food and beverage packaging, to multi-axis turning centers, to aircraft assembly, GSX Series units show incredible performance and durability.

The schematic below shows the typical connections for a single axis system with actuator and servo amplifier.



Drawings subject to change. Consult Exlar for certified drawings.

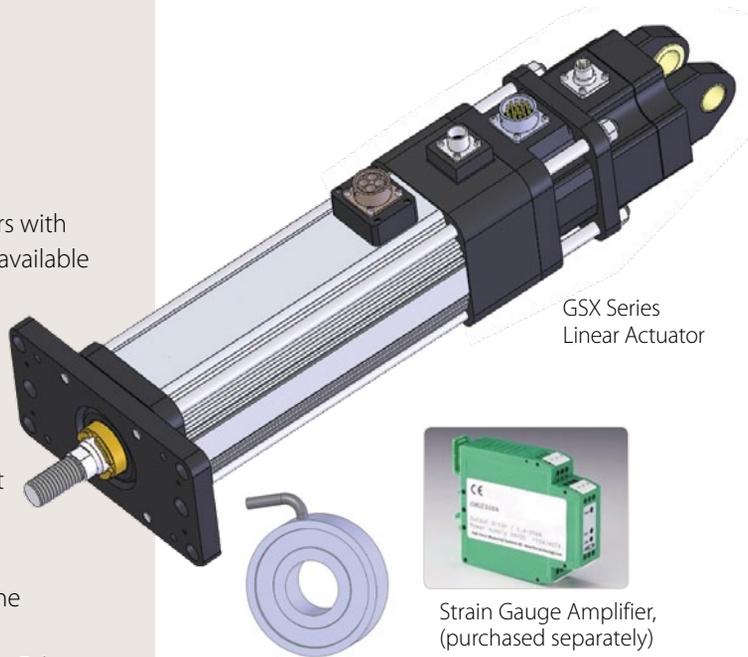
GSX Series Force Measuring Actuators

Exlar offers select models of its GSX Series actuators with integral force measuring capability. This option is available in the GSX30, 40, 50 & 60 models.

A load cell is embedded within the actuator allowing it to directly measure the force being applied by the actuator's output rod. The strain gauge load sensor used to measure applied force is mounted inside the actuator's case, protecting it from external damage and guaranteeing accurate and consistent force data.

A separate connector is supplied for connecting the internal load cell to an external strain conditioner/ amplifier required to excite the strain gauge sensor. Exlar can offer strain gauge conditioners to provide a high level output signal, either 0-10V or 4-20mA.

Alternatively, any one of numerous conditioners/amplifiers available can be used for this purpose.



Applications

Fastening and Joining
Riveting
Bag Sealing
Thermoforming
Welding
Fillers
Formers
Clamping
Molding
Precision Grinders
Precision Pressing
Interference Detection

Die Cutters
Injection Molding
Tube Bending
Stamping
Test Stand Lifts
Tension Control
Wire Winding
Parts Clamping
Dispensers
Circuit Board Testing
Blood Processing

Features/Characteristics

Front flange or rear clevis mount

Bi-directional load measurement

Integrated strain gauge load cell

2 mV/V sensitivity

+/- 1% linearity

+/- 0.5% repeatability

Hysteresis, 1% nominal

250 Hz frequency response

Factory calibrated

Compatible with standard gauge monitors and PLC strain gauge input cards

Requires 10 VDC external excitation

Totally enclosed within the actuator's sealed housing, and connectorized for ease of use

Achieving Precise Measurement

Frequently industrial applications involving linear actuation require the precise measurement of the load being applied by the actuator. Historically these have been accomplished by placing a load cell between the actuator and the connection to the workpiece.

This approach provides several challenges. Load cells need to be sized, selected and ordered. Mechanical linkages and mountings need to be designed, built and assembled. Precise alignment must be maintained to prevent bending moments which can severely degrade the accuracy of any load measurement system involving load cells.

Provisions for securing the wires to the load cell need to be designed particularly if the load cell is moving in the process of applying the force. Moving wires are extremely prone to failure and consideration must be given to the amount of flexing. Lastly, a strain gauge signal conditioner must be selected, ordered, installed and calibrated.

What seems on the front end to be a simple implementation of a force measuring system frequently turns into a project requiring expertise from both electrical and mechanical personnel. It is also common to see such projects extend beyond the target completion date as system components are redesigned or reordered.

Exlar's embedded force measuring option eliminates much of the effort and the risk associated with measuring the

applied force produced by the actuator. This system will deliver specified performance and allow you to meet target dates as all design work is field-proven and factory-tested by Exlar.

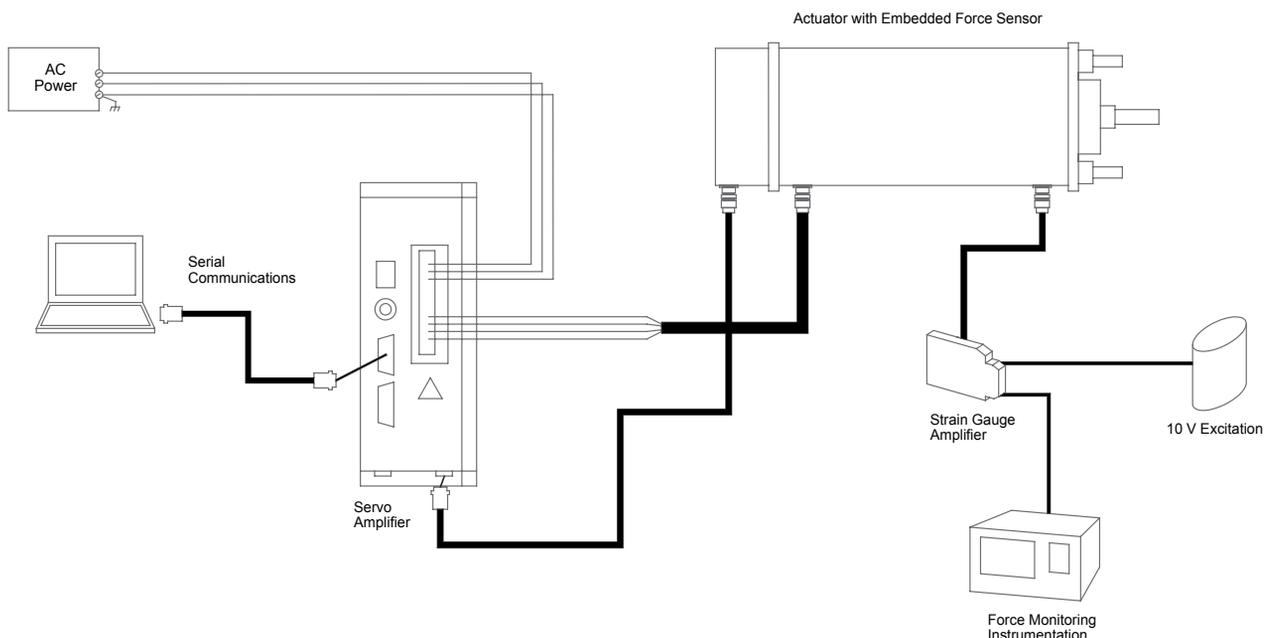
Flexing cables are not necessary. The actuator body typically does not move as it applies force. The force signal cable can be run alongside the actuator's central and power cables. And, the force sensor carries the same IP rating of the actuator since it is located inside the actuator's case.

Configuration

The standard configurations offer measurement of bi-directional loads.

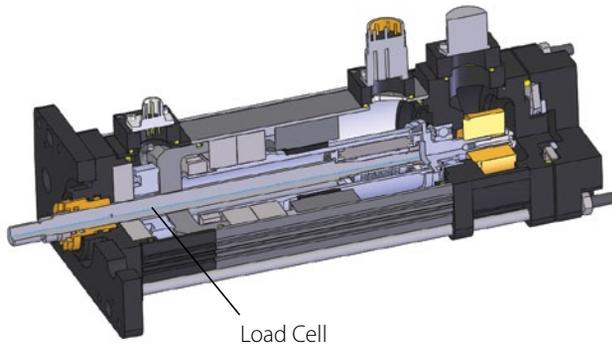
Load cell amplifiers commonly used with load cells contain power, excitation, and signal conditioning. These modules will amplify the output signal from milli-volts to useable levels of 0-10V or 4-20mA. These devices are available as stand-alone devices made for mounting in an electrical panel, incorporated into panel meters with digital displays, or integral to a PLC or other control device.

Exlar's force measuring actuator assemblies are factory calibrated and certified providing you the information needed to quickly and simply set up your measuring system.

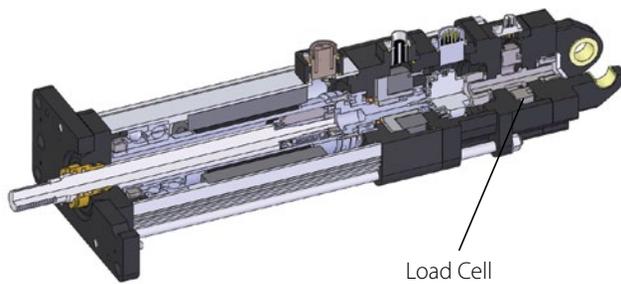


GSX Series Actuators with Integrated Motor

GSX Actuator with Flange-Mount Force Measurement



GSX Actuator with Clevis-Mount Force Measurement



Performance Specifications

GSX Series	
Linearity (% of actuator rated force)	+/- 1%
Repeatability	+/- 0.5%
Hysteresis	2% Nominal
Frequency Response*	>250 Hz
Overload Capability	1.5x Full Scale
Sensitivity (nominal)	2 mV/V
Excitation	+/-10V
Input Impedance	388 Ohms
Output Impedance	350 Ohms

*This is the frequency response of a "locked rotor" force measuring actuator. Frequency response of the load cell/actuator system will depend on total system inertia and the motor and drive amplifier powering the system.

Example Calibration and Load Information

Actuator with Load Cell (GSX40 Only)	
Serial No	6090825
Type	Compression Load Cell
Calibration Factor	2.1809 mV/V Full Scale
Calibration Full Scale Load	20,000 Pounds
Excitation Voltage	+/-10V
Linearity	<1%
Rated Force	3800 Pounds

See Operation Manual for wiring and operation instructions

Performance Specifications

Model	Available Lead inch (mm)	Force Range lbf (N)	Linearity
GSX30	01 = 0.1 (2.54)	50-1300 (222-5783)	+/- 1%
	02 = 0.2 (5.08)	50-900 (222-4004)	
GSX40	01 = 0.1 (2.54)	150-3800 (667-16903)	+/- 1%
	02 = 0.2 (5.08)	150-2600 (667-11565)	
GSX50	01 = 0.1 (2.54)	250-8000 (1112-35586)	+/- 1%
	02 = 0.2 (5.08)	250-5600 (1112-24910)	
GSX60	03 = 0.25 (6.35)	500-10000 (2224-44482)	+/- 1%

Force Measuring Actuator Range/Capacity

Frame	30	40	50	60
GSX Series Force Measurement Range / Capacity lbf (kN)	50 - 1300 (0.2 - 5.78)	150 - 3800 (0.67 - 16.5)	250 - 8000 (1.1- 36)	500 - 10000 (2.2 - 45)

Force Measurement

All Exlar precision load measuring designs are incremental in nature. By this it is intended that force measurements always be conducted as the change in the signal output between the start of each load producing motion and its completion. The force measuring option is not intended to be used as an absolute measurement of force being applied over extended time periods.

Exlar can separately provide strain gauge amplifiers that offer a convenient method for accurately and reliably measuring the resistance change per cycle of the strain gauge load cell embedded in a GSX Series actuator.

These units convert the small mV changes in load cell output to a 0-10 volt or 4-20 mA signal which is proportional to the load or tension being applied by the actuator. These amplifiers can be DIN rail or panel mountable, with or without displays.

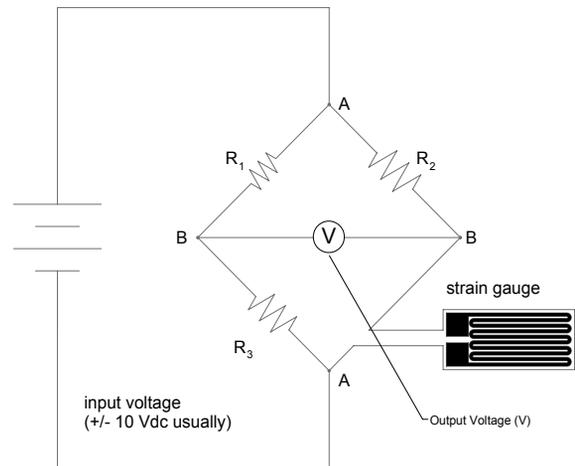
Typical Features

- DIN rail panel
- 24 Volt power
- +/- Volt or 0/4-20 mA output
- Simple gain & offset adjustments
- Auto calibration
- Simple filtering options
- With or without display

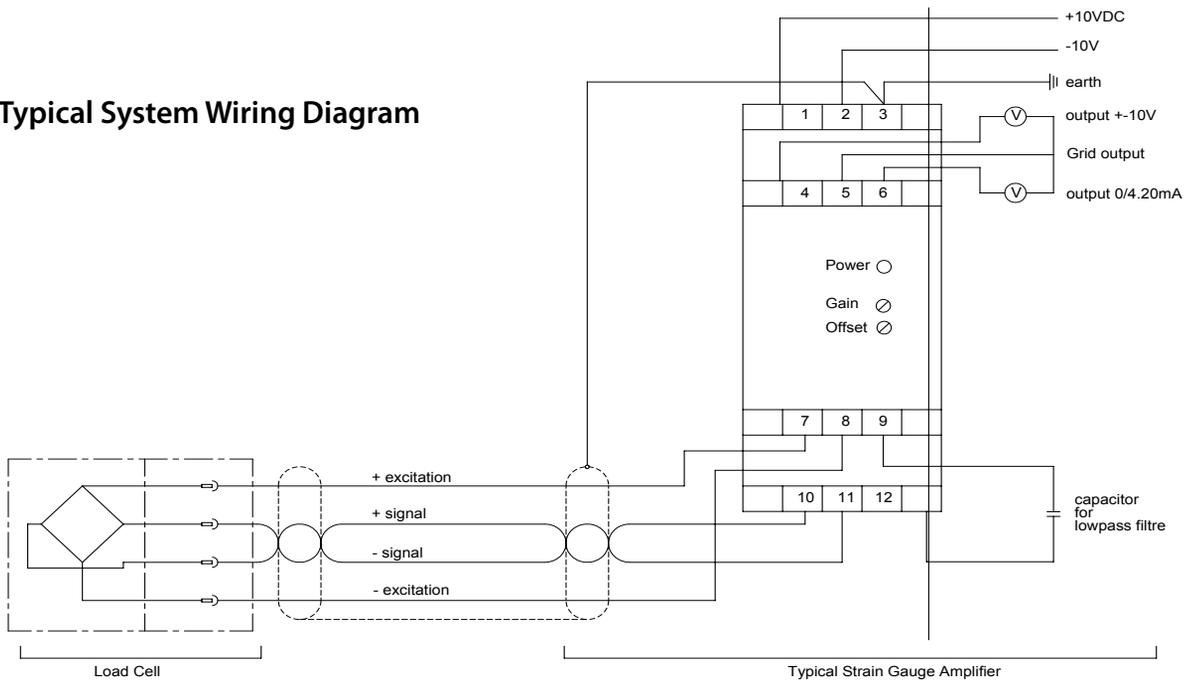
Basic Strain Gauge Function

- The strain gauge acts as a resistor in one leg of a Wheatstone bridge
- The strain gauge amplifier applies voltage across the bridge at A-A (excitation voltage), causing current to flow through the bridge
- The resistance of the strain gauge changes as a function of the force being applied
- The output voltage across B-B changes as a function of the force being applied to the load cell.

Wheatstone Bridge



Typical System Wiring Diagram



GSX Series Linear Actuators with Integrated Motor

Oil Cooling and Lubrication (-XL Oil Cooling Option)

Consult your local sales representative to discuss your application if you plan to use oil cooling with your GSX actuator.

All actuators to be used with oil cooling should have XL in the model mask.

An ideal way to both lubricate and cool a GSX actuator is to flow a small amount of oil through the actuator while it is running.

Exlar GSX actuators are delivered as standard with high performance lithium grease. This provides for the capability to provide thousands of hours of service between re-lubrication periods in most applications.

However, in some applications involving high speed and/or high cycle rate with high acceleration, high force or a combination, internal temperature may exceed the acceptable limit of the actuator. At this elevated temperature, the grease may break down and therefore fail to provide the desired life. In these cases oil lubrication provides the ideal solution. The oil lubrication run requires only low flow rates and low pressures to provide significant additional cooling and ideal lubrication.

There are several application and actuator configuration details that are involved in using a GSX with oil cooling, and any application that will use oil cooling must be discussed with your local sales representative so that an appropriate configuration of the actuator can be constructed.

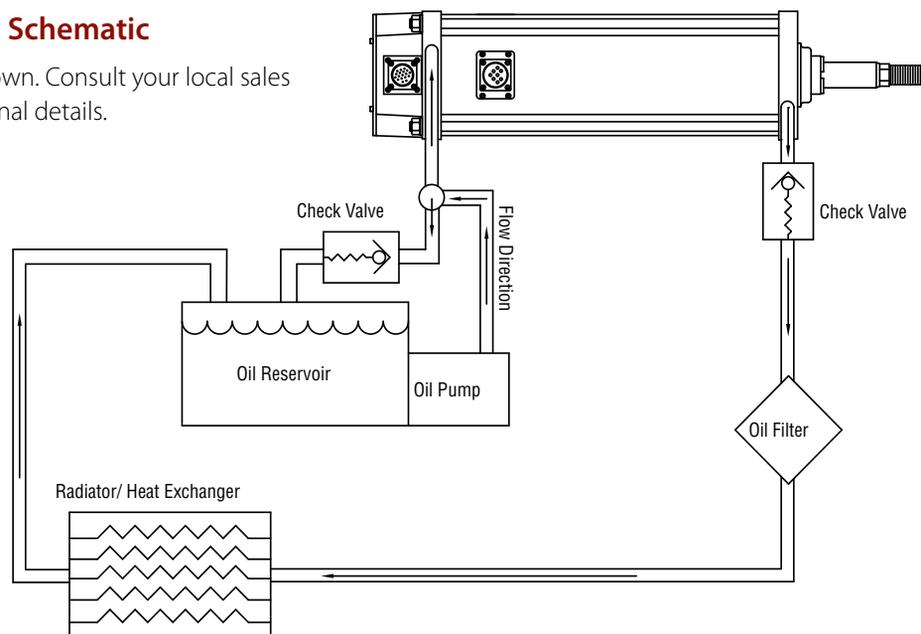
A second advantage of using recirculating oil can exist in applications that may not require oil for cooling. This advantage is that of ease of maintenance. When incorporating a recirculating oil system, you can easily change the system oil without accessing or dismounting the actuator. This can save valuable production time. And, based on the ability to monitor oil condition, possibly extend the usable life of a product by keeping the lubrication clean and fresh.

A schematic of a possible example oil system is shown below. Your local sales representative can assist you in the development of your own oil system, or suggest pre-packaged oil circulation systems.

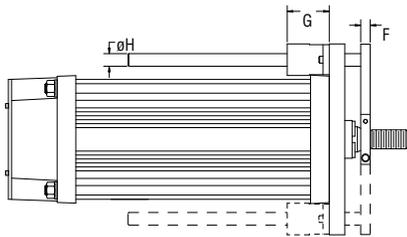
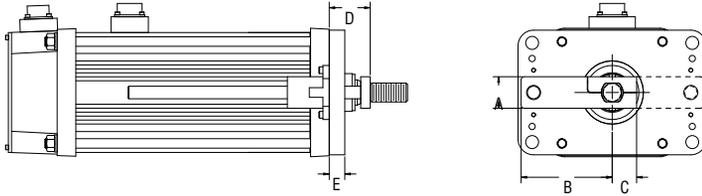
Consult your local sales representative to discuss your application if you plan to use oil cooling with your GSX actuator. All actuators to be used with oil cooling should have XL in the model mask.

Example Oil System Schematic

A typical schematic is shown. Consult your local sales representative for additional details.



Anti-rotation Option GSX/M20, GSX/M30, GSX/M40 and GSX60



A second anti-rotate arm is used on GSX20, GSX30 and GSX40, 10 inch and longer stroke.

GSX60 uses a single sided anti-rotate for all stroke lengths.

Dims- in (mm)	GSX/M20	GSX/M30	GSX/M40	GSX60
A	0.60 (15.2)	0.79 (20.1)	1.25 (31.8)	1.75 (44.5)
B	1.81 (46.0)	2.54 (64.5)	3.78 (96.0)	5.79 (147)
C	0.54 (13.7)	0.71 (18.0)	0.98 (24.9)	1.55 (39.4)
D	1.00 (25.4)	1.30 (33.0)	1.64 (41.7)	1.94 (49.3)
E	0.44 (11.2)	0.44 (11.2)	0.63 (16.0)	0.75 (19.1)
F	0.28 (7.11)	0.32 (8.13)	0.38 (9.65)	0.50 (12.7)
G	0.31 (7.87)	1.69 (42.9)	1.69 (42.9)	2.81 (71.4)
øH	0.37 (9.40)	0.50 (12.7)	0.50 (12.7)	1.00 (25.4)

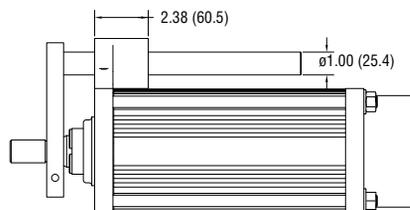
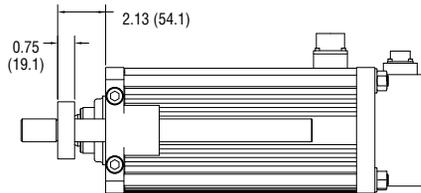
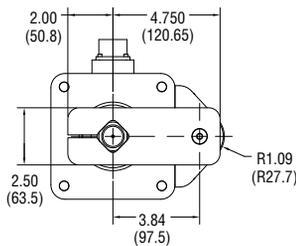
Anti-rotation Option

The unique design of the GSX Series of linear actuators permits the extending rod to rotate. This simplifies actuator setup by allowing the user to rotate the rod and thread it in and out of the actuator for mechanical attachment or system testing.

However, this feature also requires that once setup and testing are completed, the rod be kept from rotating so proper linear motion will be maintained. In most applications the actuator's load is coupled to linear bearings, or some other support device. In these cases the load cannot rotate, and a separate anti-rotation system is not needed.

For applications in which the load is free to rotate, Exlar offers the anti-rotation systems shown right. Shorter GSX units use an anti-rotation arm on one side of the actuator. Longer strokes (defined above right) use arms on both sides.

Anti-rotation Option GSX50



NOTE: GSX50 actuators use one arm for all stroke lengths.

GSX Series Linear Actuators with Integrated Motor

Standard Ratings for Exlar Actuators

The standard IP rating for Exlar Actuators is IP54S or IP65S. Ingress protection is divided into two categories; solids and liquids.

For example, in IP65S the three digits following "IP" represent different forms of environmental influence:

- The first digit represents protection against ingress of solid objects.
- The second digit represents protection against ingress of liquids.
- The suffix digit represents conditions of motion during the operation.

Digit 1 - Ingress of Solid Objects

The IP rating system provides for 6 levels of protection against solids.

1	Protected against solid objects over 50 mm e.g. hands, large tools.
2	Protected against solid objects over 12.5 mm e.g. hands, large tools.
3	Protected against solid objects over 2.5 mm e.g. wire, small tools.
4	Protected against solid objects over 1.0 mm e.g. wires.
5	Limited protection against dust ingress. (no harmful deposit)
6	Totally protected against dust ingress.

Digit 2 - Ingress of Liquids

The IP rating system provides for 9 levels of protection against liquids.

1	Protected against vertically falling drops of water or condensation.
2	Protected against falling drops of water, if the case is disposed up to 15 degrees from vertical.
3	Protected against sprays of water from any direction, even if the case is disposed up to 60 degrees from vertical.
4	Protected against splash water from any direction.
5	Protected against low pressure water jets from any direction. Limited ingress permitted.
6	Protected against high pressure water jets from any direction. Limited ingress permitted.
7	Protected against short periods of immersion in water of 1m or less for 30 minutes or less.
8	Protected against long durations of immersion in water.
9	High-pressure, high-temperature wash-down applications.

Suffix

S	Device standing still during operation	M	Device moving during operation
---	--	---	--------------------------------

GSX Series Travel Options

PF = Preloaded Follower

This option offers a true zero backlash follower for the GSX Series actuator. The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw for the same application. Preloaded follower is not available with LT linear feedback option.

AR = External Anti-rotate Assembly

This option provides a rod and bushing to restrict the actuator rod from rotating when the load is not held by another method. Shorter actuators have single sided anti-rotation attachments. Longer lengths require attachments on both sides for proper operation.

RB = Rear Electric Brake

This option provides an internal holding brake for the GSX Series actuators. The brake is spring activated and electrically released.

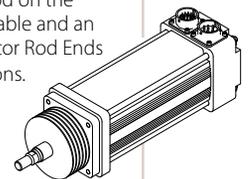
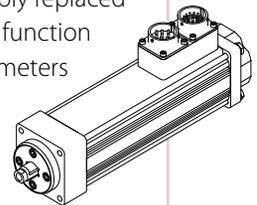
SR = Splined Main Rod

This option provides a main rod manufactured of ball spline shafting, and the front seal and bushing assembly replaced with a ball spline nut to provide the anti-rotate function without using an external mechanism. Rod diameters are the closest metric equivalents to standard Exlar rod sizes. This option is **NOT** sealed in any way. This option is not suitable for any environment in which contaminants come in contact with the actuator, and may enter the actuator.

Note: This option affects overall length and mounting dimensions for GSX actuators. Consult your local sales representative if using splined main rod. Due to the reduced diameter of the splined main rod on the GSX50, the standard "A", "F" and "B" rod ends are not available and an "X" should be used in the model mask. Please see Actuator Rod Ends with Splined Main Rod Options on page 36 for dimensions.

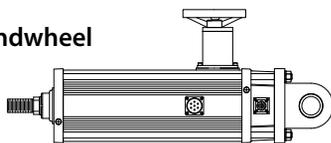
PB = Protective Bellows

This option provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environment in which the actuator must survive. The standard material of this bellows is S2 Neoprene Coated Nylon, Sewn Construction. This standard bellows is rated for environmental temperatures of -40 to 250 degrees F. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Not available with extended tie rod mounting option. Please contact your local sales representative for details.



HW = Manual Drive, Handwheel

This option provides a manual drive handwheel on the side of the actuator. The handwheel has an engage/disengage lever that is tied to an interrupt switch. Not available on GSX20. Also not available with holding brake unless application details have been discussed with your local sales representative.



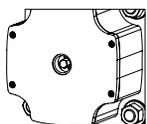
Construction. This standard bellows is rated for environmental temperatures of -67 to 500 degrees F. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Not available with extended tie rod mounting option. Please contact your local sales representative for details.

L1, L2, L3 = Adjustable External Travel Switches

This option allows up to 3 external switches to be included with the GSX Series Actuator. These switches provide travel indication to the controller and are adjustable (must purchase external anti-rotate for this option). See page 35 for details.

RD = Manual Drive, Rear Hex

This option provides a hex shaft at the rear of the actuator for manual operation. The hex shaft is directly coupled to the motor and can be turned by hand with a compatible wrench. The hex shaft is enclosed by a sealed cap during operation. This option is not available w/absolute feedback. If the application requires a brake, discuss manual drive use with your local sales representative.



XL = Non-Standard Lubrication

This option provides for indication in the model number that the customer has specified a lubrication other than the standard provided by Exlar, Mobilith SHC220. Specials include other greases including JAX FG-2 food grade, Mobilgrease 28, or other non-standard grease.

SD = Manual Drive, Side Hex

This option provides a hex shaft on the side of the actuator. The hex can be turned by hand with a wrench. Not available on GSX20. Also not available with holding brake unless application details have been discussed with your local sales representative.



XT = Special Travel Option Selections

The XT Option can be used to specify various special travel options on the GSX Series of Linear Actuators. Because this option can be used to specify many things, it is important that an order including the -XT option spell out in detail, the exact options being selected by the including of the -XT in the model number.

It is recommended that prior to ordering an actuator including the -XT specifier that a quote be obtained through Exlar's special products application engineers for the desired options, and that quote be referenced on, or included with any order placed.

High Temp Protective Bellows, an XT option, provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environment in which the actuator must survive. The high temperature material of this bellows is D1 Teflon Coated Fiberglass, Sewn

GSX Series Linear Actuators with Integrated Motor

Motor Speed Designators

All Exlar T-LAM™ motors and actuators carry a standard motor speed designator as defined below. This is representative of the standard base speed of the motor, for the selected bus voltage.

If the model number is created and the location for the motor speed designator is left blank, this is the base speed to which each motor will be manufactured. The model number can also be created including this standard speed designator.

Designator	Base Speed	Actuator/Motor Series
-50	5000 rpm	GSX20
-30	3000 rpm	GSX30, GSX40
-24	2400 rpm	GSX50, GSX60
01-99	Special Speed, Consult Exlar	

Exlar also provides the flexibility to manufacture all of its T-LAM products with special base speeds to match the customer's exact application requirements. This may be a higher than standard speed motor, or lower base speed than standard which will allow the customer to get the required torque at a speed optimized to their application and use the minimum amount of current from their amplifier.

The call-out for a special speed is configured in the model number by using a two digit code from 01-99. These numbers represent the number, in hundreds, of RPM that will be the base speed for the particular motor.

For example, a GSX30-0301-OSM-AD1-118-30 motor that normally has a 3000 RPM standard winding can be changed to a 3300 RPM winding by changing the -30 to a -33. It can be changed to a 5000 RPM winding by changing the -30 to a -50.

Changing this speed designator will change the ratings of the motor, and these must be obtained from your local sales representative. Also, it is not possible to produce every possible speed from -01 to -99 for each motor at each voltage so please contact your local sales representative for confirmation of the speed that is desired for the application.

Feedback Options

LT = ICT including signal conditioner

This option provides for an actuator containing an internally mounted ICT transducer spanning the full stroke of the actuator. Inquire with Exlar engineering for details and signal conditioner output preference. LT not available with absolute feedback. Not available in GSX20 actuator.

Absolute Feedback

Due to the variability in size of some feedback devices, especially absolute feedback devices which are often very large relative to the size of the actuator motor, the actual size of the actuator may differ in length and width from these drawings for feedback types other than standard resolvers and standard encoders. Please consult Exlar for details. In the event that you order an actuator that differs from these standard dimensions, you will be sent a drawing of the final configuration of your actuator for approval.

Motor Options

GSX motor options are described with a 3 digit code. The first digit calls out the stack length, the second the rated bus voltage, and the third the number of poles of the motor. Refer to the mechanical/electrical specifications for motor torque and actuator rated force.

Motor Code	Stack Length	Rated Bus Voltage	Number of Poles	Class
118	1 stack	115 Vrms	8 Pole	Class 180 H
138		230 Vrms		
158		400 Vrms		
168		460 Vrms		
1A8*	2 stack	24 VDC	8 Pole	Class 180 H
1B8*		48 VDC		
1C8*		120 VDC		
218		115 Vrms		
238	3 stack	230 Vrms	8 Pole	Class 180 H
258		400 Vrms		
268		460 Vrms		
2A8*		24 VDC		
2B8*	1 stack	48 VDC	8 Pole	Class 180 H
2C8*		120 VDC		
318		115 Vrms		
338		230 Vrms		
358	2 stack	400 Vrms	8 Pole	Class 180 H
368		460 Vrms		
3A8*		24 VDC		
3B8*		48 VDC		
3C8*	3 stack	120 VDC	8 Pole	Class 180 H
318		115 Vrms		
338		230 Vrms		
358		400 Vrms		
368	1 stack	460 Vrms	8 Pole	Class 180 H
3A8*		24 VDC		
3B8*		48 VDC		
3C8*		120 VDC		

* Low voltage stators may be limited to less than catalog rated torque and/or speed. Please contact your local sales representative when ordering this option.

Rod End Attachments

Rear Clevis Pin Spherical Rod Eye
Rod Eye Rod Clevis

See drawings on pages 36-38.

Attachments ordered separate from actuator.

Housing Options

FG = Smooth White Epoxy

This option provides for an actuator coated with FDA approved white epoxy.

EN = Electroless Nickel Plating

This option provides for an actuator with electroless nickel plating.

SS = Stainless Steel Housing

This option provides an actuator with all stainless steel construction. Housing dimensions for this option are not equal to the standard housing. Force, torque and current

ratings are reduced 25% with this option. Please inquire with Exlar for dimensions and ratings.

HC = Type III Hard Coat Anodized, Class I

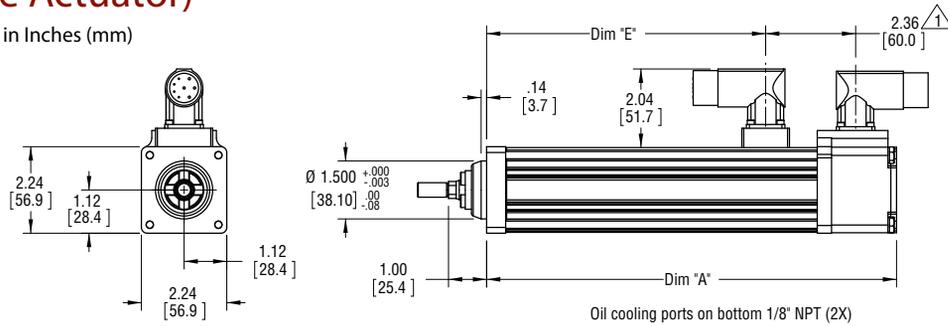
This option provides an actuator with type III hard coat anodized coating. Class I, no dye.

XH = Special Housing Option

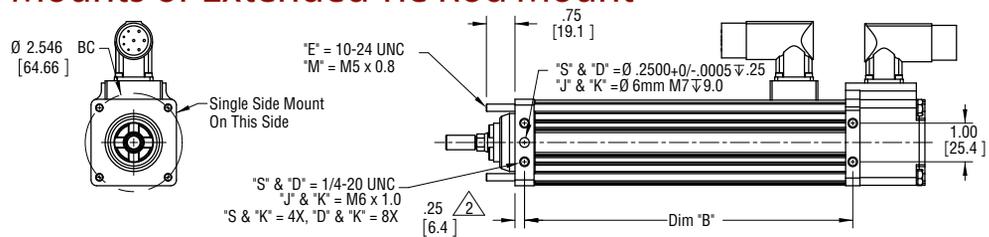
Any housing option that is not designated by the above codes should be listed as XH and described at time of order. All special options must be discussed with your local sales representative.

GSX20 (Base Actuator)

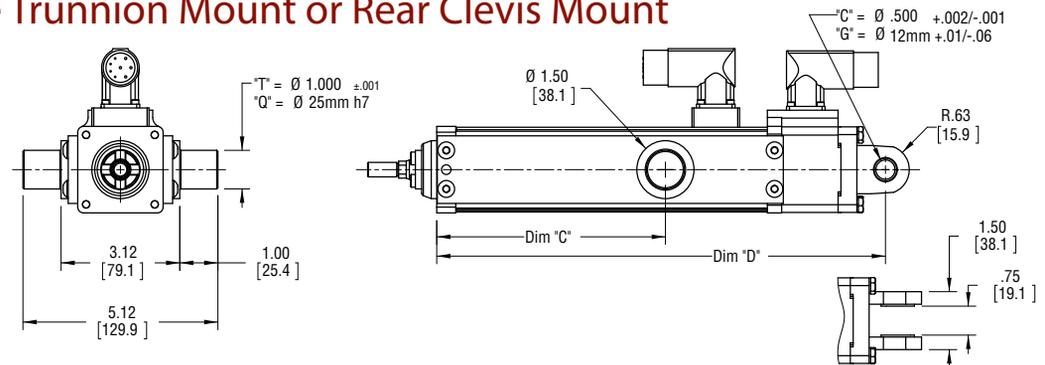
All Dimensions Shown in Inches (mm)



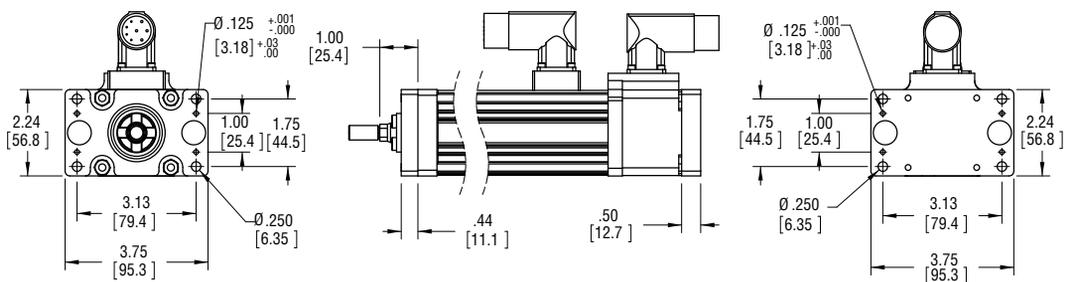
GSX20 Side Mounts or Extended Tie Rod Mount



GSX20 Side Trunnion Mount or Rear Clevis Mount



GSX20 Front or Rear Flange Mount



Dim	3" (76 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)
A	7.8 (198)	10.8 (274)	14.8 (375)	16.8 (426)
B	5.6 (143)	8.6 (219)	12.6 (320)	14.6 (371)
C	3.0 (76)	6.0 (152)	10.0 (254)	12.0 (305)
D	8.8 (223)	11.8 (299)	15.8 (401)	17.8 (452)
E	4.3 (110)	7.3 (186)	11.3 (288)	14.3 (364)

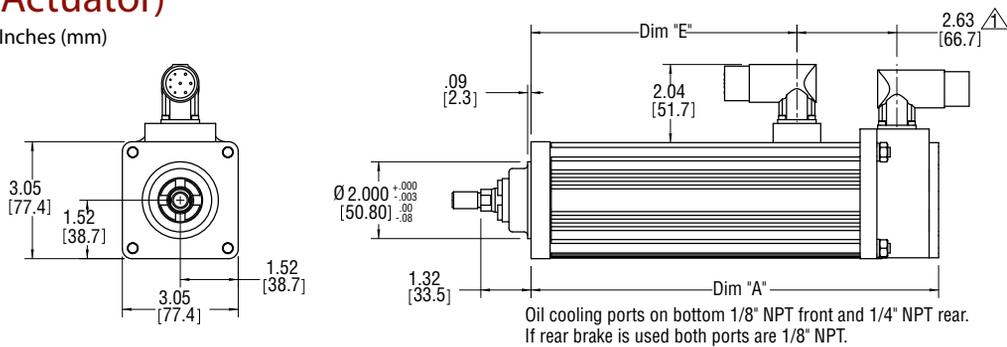
Notes:

1. Add 1.78 inches to Dims "A" & "D" and to Dim Δ if ordering a brake.
2. Models are shown with Exlar standard M23 style connectors (option "I"). See ordering guide for other connector options.
3. Depending on connector and feedback options selected, dimensions may vary. Consult Exlar for details, or refer to the drawings provided after receipt of order.
4. Drawings subject to change.
5. Add .50 inches to Dims "A, C, D, E" and to Dim Δ if ordering splined main rod.

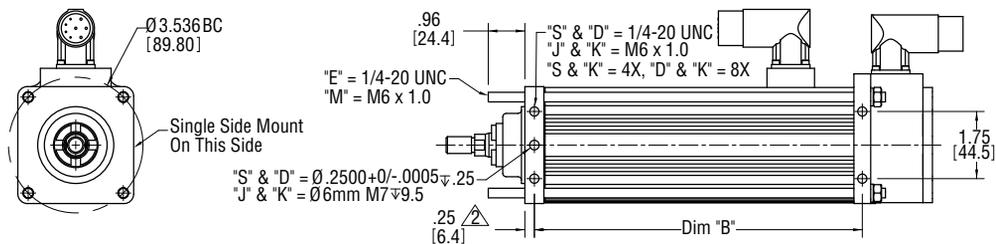
GSX Series Linear Actuators with Integrated Motor

GSX30 (Base Actuator)

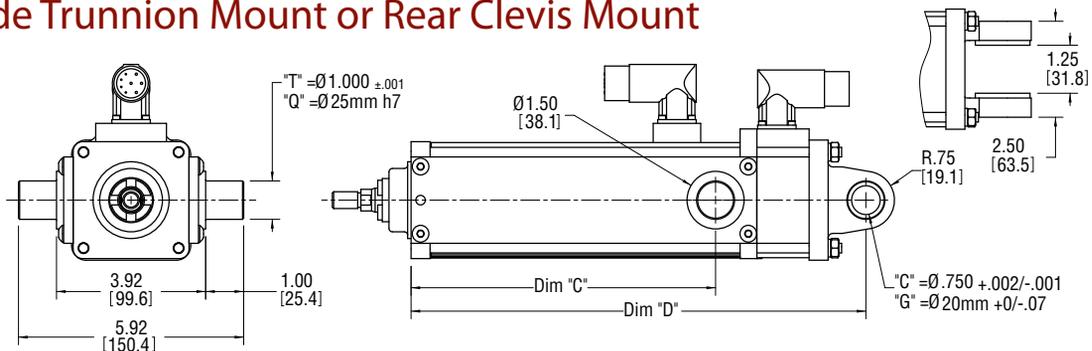
All Dimensions Shown in Inches (mm)



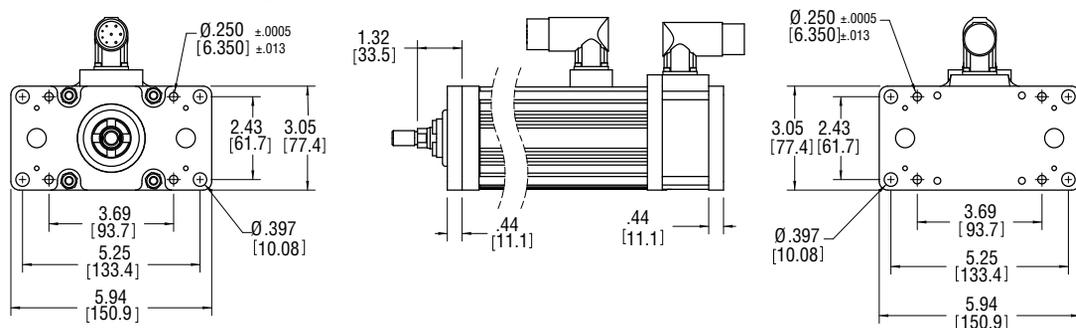
GSX30 Side Mounts or Extended Tie Rod Mount



GSX30 Side Trunnion Mount or Rear Clevis Mount



GSX30 Front or Rear Flange Mount



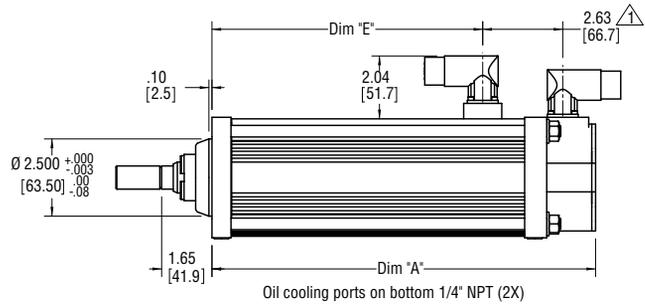
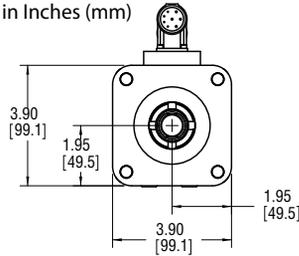
Dim	3" (76 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	14" (355 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	8.2 (209)	10.7 (272)	15.2 (387)	17.2 (437)	19.2 (488)	23.2 (590)
B	6.1 (156)	8.6 (219)	13.1 (333)	15.1 (384)	17.1 (435)	21.1 (536)
C	5.4 (137)	8.0 (203)	10.0 (254)	12.0 (305)	14.0 (356)	18.0 (457)
D	9.5 (241)	12.0 (304)	16.5 (418)	18.5 (469)	20.5 (520)	24.5 (621)
E	4.5 (114)	7.0 (178)	11.5 (292)	13.5 (343)	15.5 (394)	19.5 (495)

Notes:

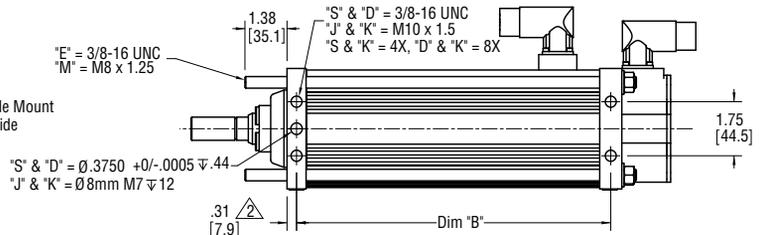
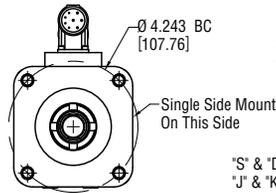
1. Add 1.6 inches to Dims A & D and to Dim Δ if ordering a brake.
2. Add 1.20 inches to Dims A, C, D, E and to Dim Δ if ordering a splined main rod.
3. Models are shown with Exlar standard M23 style connectors (option "I"). See ordering guide for other connector options.
4. Depending on connector and feedback options selected, dimensions may vary. Consult Exlar for details, or refer to the drawings provided after receipt of order.
5. Drawings subject to change.

GSX40 (Base Actuator)

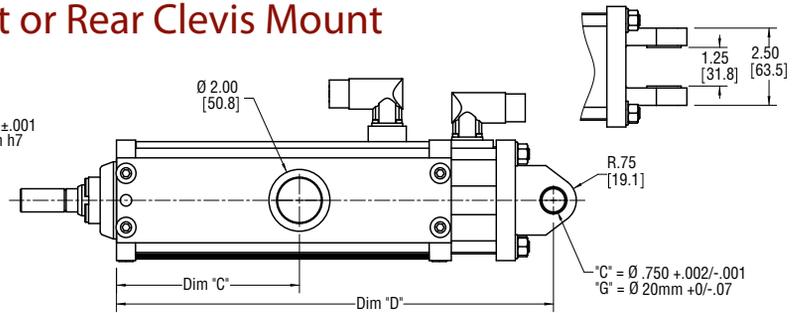
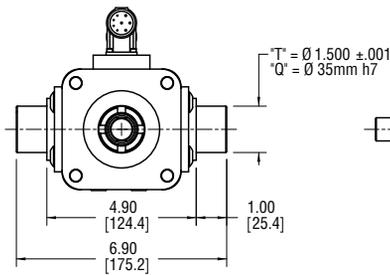
All Dimensions Shown in Inches (mm)



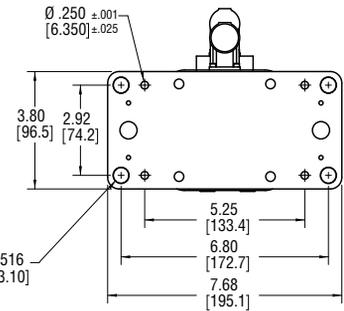
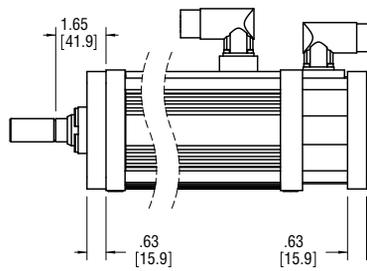
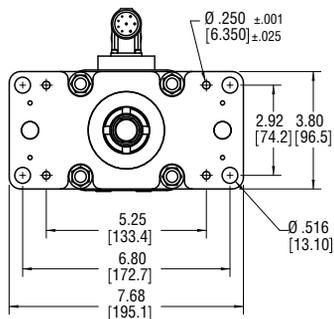
GSX40 Side Mounts or Extended Tie Rod Mount



GSX40 Side Trunnion Mount or Rear Clevis Mount



GSX40 Front or Rear Flange Mount



Dim	4" (102 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	8" (203 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	10.6 (269)	12.6 (320)	14.6 (370)	16.6 (421)	18.6 (472)	24.6 (624)
B	8.3 (211)	10.3 (262)	12.3 (313)	14.3 (364)	16.3 (414)	22.3 (567)
C	4.0 (102)	6.0 (152)	8.0 (203)	10.0 (254)	12.0 (305)	18.0 (457)
D	12.3 (312)	14.3 (363)	16.3 (415)	18.3 (466)	20.3 (516)	26.3 (669)
E	6.9 (175)	8.9 (226)	10.9 (277)	12.9 (328)	14.9 (378)	20.9 (531)

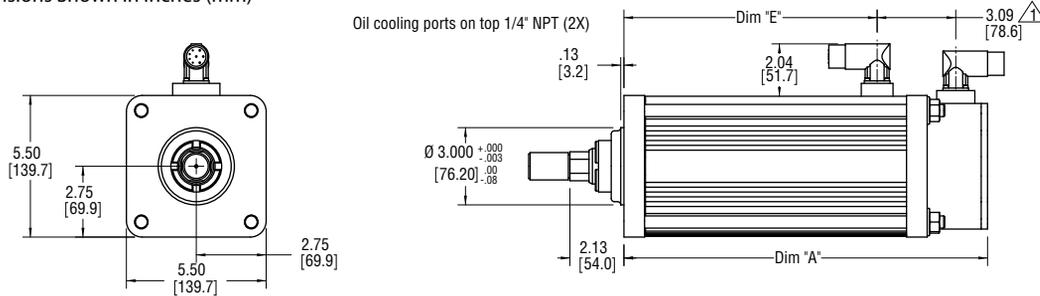
Notes:

1. Add 2.33 inches to Dims A & D and to Dim Δ if ordering a brake.
2. Add 1.77 inches to Dims A, C, D, E and to Dim Δ if ordering a splined main rod.
3. Models are shown with Exlar standard M23 style connectors (option "I"). See ordering guide for other connector options.
4. Depending on connector and feedback options selected, dimensions may vary. Consult Exlar for details, or refer to the drawings provided after receipt of order.
5. Drawings subject to change.

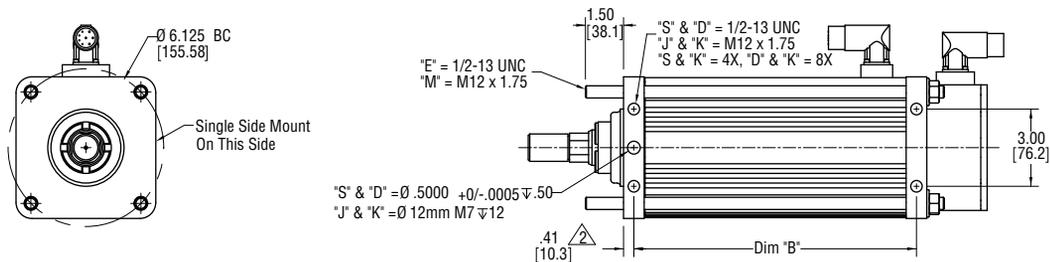
GSX Series Linear Actuators with Integrated Motor

GSX50 (Base Actuator)

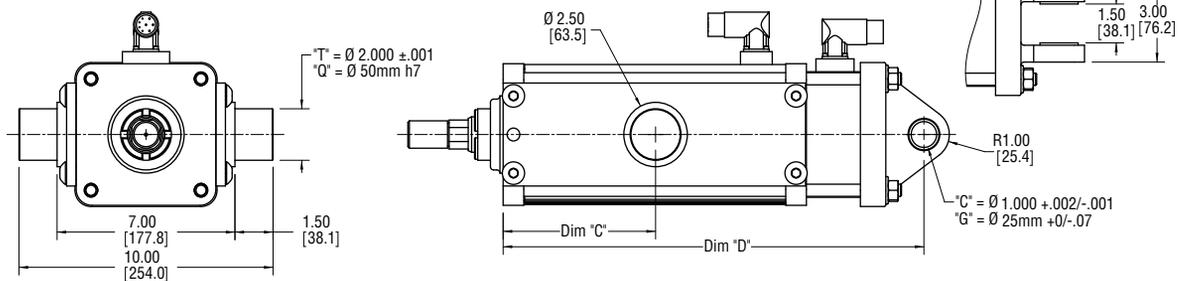
All Dimensions Shown in Inches (mm)



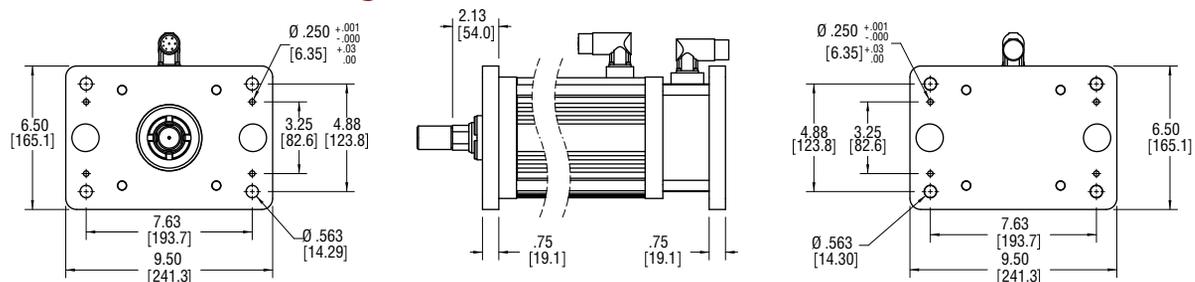
GSX50 Side Mounts or Extended Tie Rod Mount



GSX50 Side Trunnion Mount or Rear Clevis Mount



GSX50 Front or Rear Flange Mount



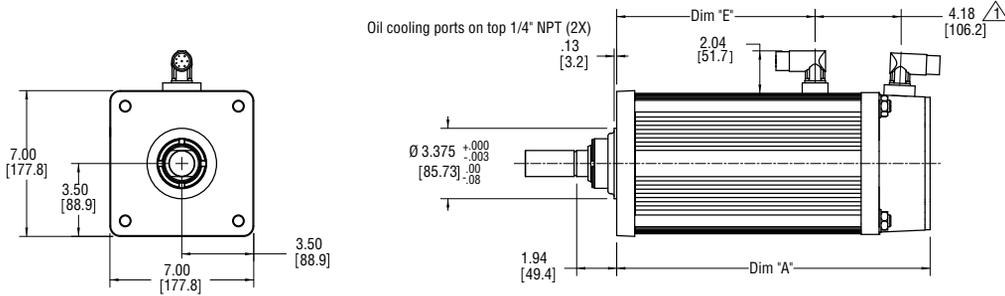
Dim	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	14" (356 mm) Stroke in (mm)
A	14.3 (364)	18.3 (465)	22.3 (567)
B	11.1 (282)	15.1 (384)	19.1 (486)
C	6.0 (152)	10.0 (254)	14.0 (356)
D	16.6 (421)	20.6 (522)	24.6 (624)
E	10.0 (254)	14.0 (356)	18.0 (457)

Notes:

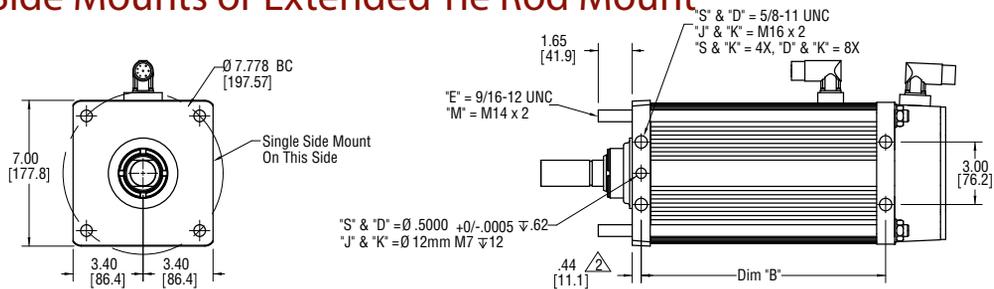
1. Add 2.50 inches to Dims A & D and to Dim Δ if ordering a brake.
2. Add 2.06 inches to Dims A, C, D, E and to Dim Δ if ordering a splined main rod.
3. Models are shown with Exlar standard M23 style connectors (option "I"). See ordering guide for other connector options.
4. Depending on connector and feedback options selected, dimensions may vary. Consult Exlar for details, or refer to the drawings provided after receipt of order.
5. Drawings subject to change.

GSX60 (Base Actuator)

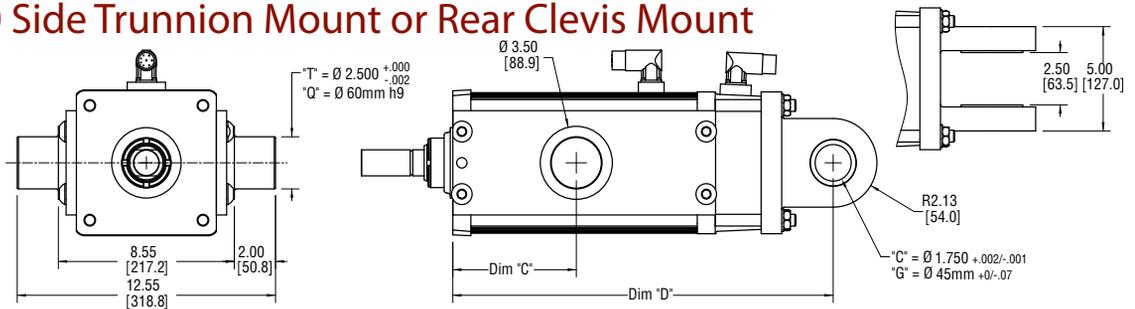
All Dimensions Shown in Inches (mm)



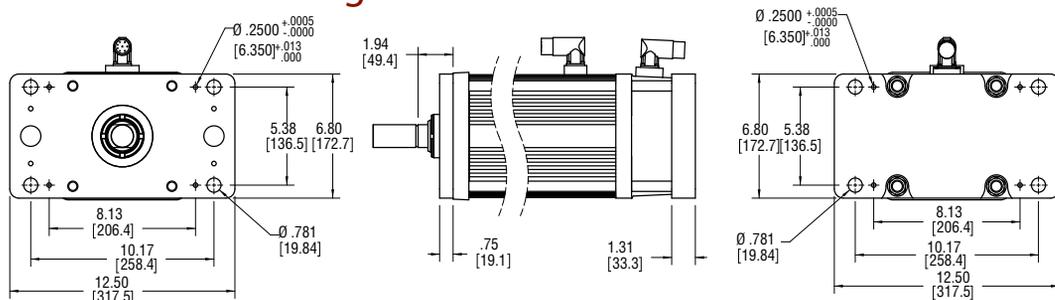
GSX60 Side Mounts or Extended Tie Rod Mount



GSX60 Side Trunnion Mount or Rear Clevis Mount



GSX60 Front or Rear Flange Mount



Dim	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)
A	15.2 (387)	19.2 (488)
B	11.9 (302)	15.9 (403)
C	6.0 (152)	10.0 (254)
D	18.5 (469)	22.5 (571)
E	9.60 (245)	13.6 (346)

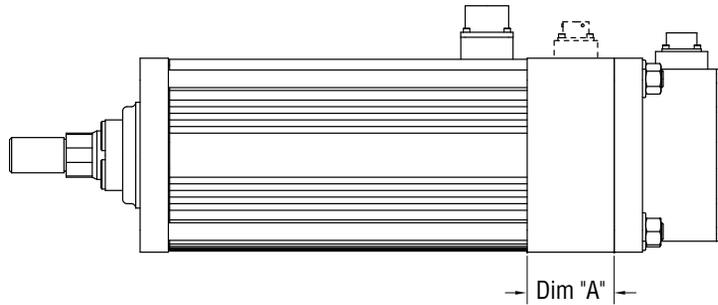
Notes:

1. Add 3.58 inches to Dims A & D and to Dim Δ if ordering a brake.
2. Add 2.73 inches to Dims A, C, D, E and to Dim Δ if ordering a splined main rod.
3. Models are shown with Exlar standard M23 style connectors (option "I"). See ordering guide for other connector options.
4. Depending on connector and feedback options selected, dimensions may vary. Consult Exlar for details, or refer to the drawings provided after receipt of order.
5. Drawings subject to change.

GSX Series Linear Actuators with Integrated Motor

Rear Brake Extension Option

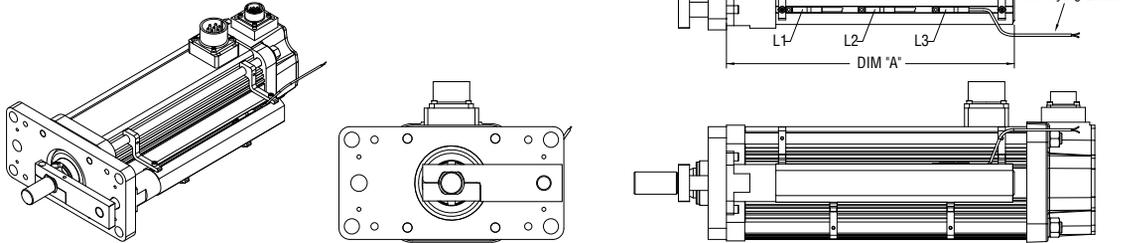
*Brake connector if needed.



	GSX20	GSX30	GSX40	GSX50	GSX60
A in (mm)	1.78 (45.21)	1.61 (40.9)	2.33 (59.18)	2.5 (63.5)	3.575 (90.8)

*Consult Exlar for connector and wiring information if ordering brake option.

GSX20, GSX30, GSX40, GSX50 & GSX60 External Limit Switch Extension Options



Dim A	3" (76 mm) stroke in (mm)	6" (152 mm) stroke in (mm)	8" (203 mm) stroke in (mm)	10" (254 mm) stroke in (mm)	12" (305 mm) stroke in (mm)	14" (355 mm) stroke in (mm)	18" (457 mm) stroke in (mm)
GSX20	5.515 (140.1)	8.515 (216.3)	NA	12.500 (317.5)	14.515 (368.7)	NA	NA
GSX30	6.932 (176.1)	9.832 (249.7)	NA	13.832 (351.3)	15.832 (402.1)	17.832 (452.9)	21.832 (554.5)
GSX40	NA	9.832 (249.7)	11.83 (300.5)	13.832 (351.3)	15.832 (402.1)	NA	21.832 (554.5)
GSX50	NA	11.667 (296.3)	NA	15.667 (397.9)	NA	19.667 (499.5)	NA
GSX60	NA	10.461 (265.7)	NA	14.461 (367.3)	NA	NA	NA

The external limit switch option (requires anti-rotate option) for the GSX Series of linear actuators provides the user with 1, 2 or 3 externally mounted adjustable switches for use as the end of travel limit switches or home position sensors.

The number of switches desired is selected by ordering the L1, L2 or L3 option, in which 1, 2 or 3 switches will be provided, respectively.

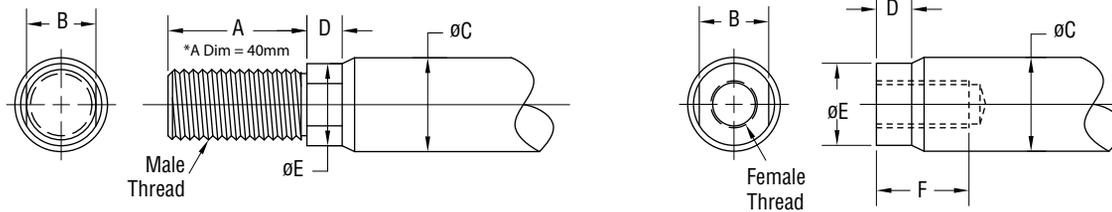
The switches are 9-30 VDC powered, PNP output, with either normally open or normally closed logic operation depending on the switch configuration ordered. Switches are supplied with 1 meter, 3 wire embedded cable. Below is a diagram indicating which logic operation will be provided for each switch, based on the option ordered.

Option	SW1	SW2	SW3
L1	Not Supplied	Normally Open	Not Supplied
L2	Normally Closed	Not Supplied	Normally Closed
L3	Normally Closed	Normally Open	Normally Closed

Switch Type	Exlar Part Number	Turck Part Number
Normally Closed Switch	43404	BIM-UNT-RP6X
Normally Open Switch	43403	BIM-UNT-AP6X

GSX Series Linear Actuators with Integrated Motor

Actuator Rod End Options



Standard Rod End

	A	B	øC	D	øE	F	Male U.S.	Male Metric	Female U.S.	Female Metric
GSX20 in (mm)	0.813 (20.7)	0.375 (9.5)	0.500 (12.7)	0.200 (5.1)	0.440 (11.2)	0.750 (19.1)	3/8 – 24 UNF – 2A	M8 x 1 6g	5/16 – 24 UNF – 2B	M8 x 1 6h
GSX30 in (mm)	0.750 (19.1)	0.500 (12.7)	0.625 (15.9)	0.281 (7.1)	0.562 (14.3)	0.750 (19.1)	7/16 – 20 UNF – 2A	M12 x 1.75* 6g	7/16 – 20 UNF – 2B	M10 x 1.5 6h
GSX40 in (mm)	1.500 (38.1)	0.750 (19.1)	1.000 (25.4)	0.381 (9.7)	0.875 (22.2)	1.000 (25.4)	3/4 – 16 UNF – 2A	M16 x 1.5 6g	5/8 – 18 UNF – 2B	M16 x 1.5 6h
GSX50 in (mm)	1.625 (41.3)	1.125 (28.6)	1.375 (34.9)	0.750 (19.1)	1.250 (31.8)	1.750 (44.5)	1 – 14 UNS – 2A	M27 x 2 6g	1 – 14 UNS – 2B	M24 x 2 6h
GSX60 in (mm)	2.500 (63.5)	1.250 (31.8)	1.750 (44.5)	0.550 (14.0)	1.625 (41.3)	1.750 (44.5)	1 1/4 – 12 UNF – 2A	M30 x 2 6g	7/8 – 14 UNF – 2B	M25 x 1.5 6h

Rod End With Splined Main Rod

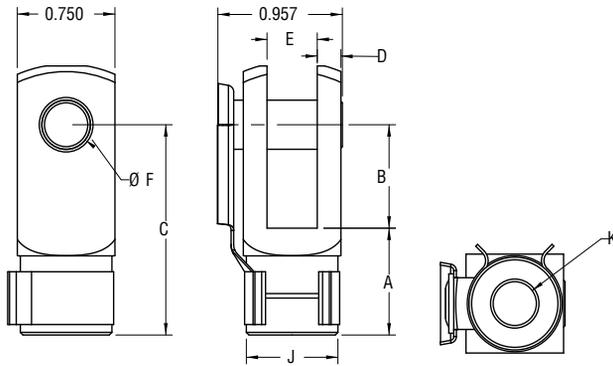
	A	B	C	D	E	F	Male U.S.	Male Metric	Female U.S.	Female Metric
GSX20 in (mm)	0.813 (20.7)	0.375 (9.5)	0.512 (13.0)	0.200 (5.1)	0.440 (11.2)	0.750 (19.1)	3/8 – 24 UNF – 2A	M8 x 1 6g	5/16 – 24 UNF – 2B	M8 x 1 6h
GSX30 in (mm)	0.750 (19.1)	0.500 (12.7)	0.630 (16.0)	0.281 (7.1)	0.562 (14.3)	0.750 (19.1)	7/16 – 20 UNF – 2A	M12 x 1.75 6g	7/16 – 20 UNF – 2B	M10 x 1.5 6h
GSX40 in (mm)	1.500 (38.1)	0.750 (19.1)	0.906 (23.0)	0.381 (9.7)	0.875 (22.2)	1.000 (25.4)	3/4 – 16 UNF – 2A	M16 x 1.5 6g	5/8 – 18 UNF – 2B	M16 x 1.5 6h
GSX50 in (mm)	1.625 (41.3)	1.000* (25.4)	1.102 (28.0)	0.750** (19.1)	1.102 (28.0)	1.500 (38.1)	1 – 14 UNS – 2A	M24 x 2 6g	3/4 – 16 UNF – 2B	M20 x 1.5 6h
GSX60 in (mm)	2.500 (63.5)	1.250 (31.8)	1.850 (47.0)	0.550 (14.0)	1.625 (41.3)	1.750 (44.5)	1 1/4 – 12 UNF – 2A	M30 x 2 6g	7/8 – 14 UNF – 2B	M25 x 1.5 6h

*When Male, Metric (A) = .945 (24 mm)

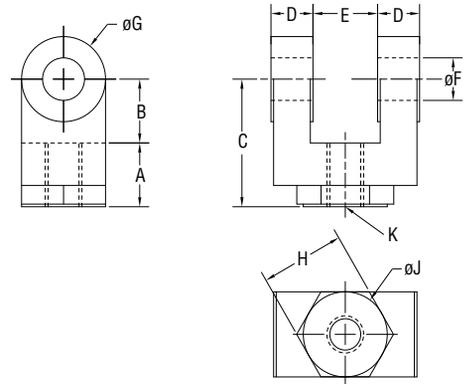
**When Male (M or A) = .500 (12.7 mm)

Part numbers for rod attachment options indicate the through hole size or pin diameter. Before selecting a spherical rod eye for use with a GSX series actuator, please consult the information on the anti-rotation option for the GSX actuators. Spherical rod eyes will allow the rod to rotate if the load is not held.

Rod Clevis Dimensions



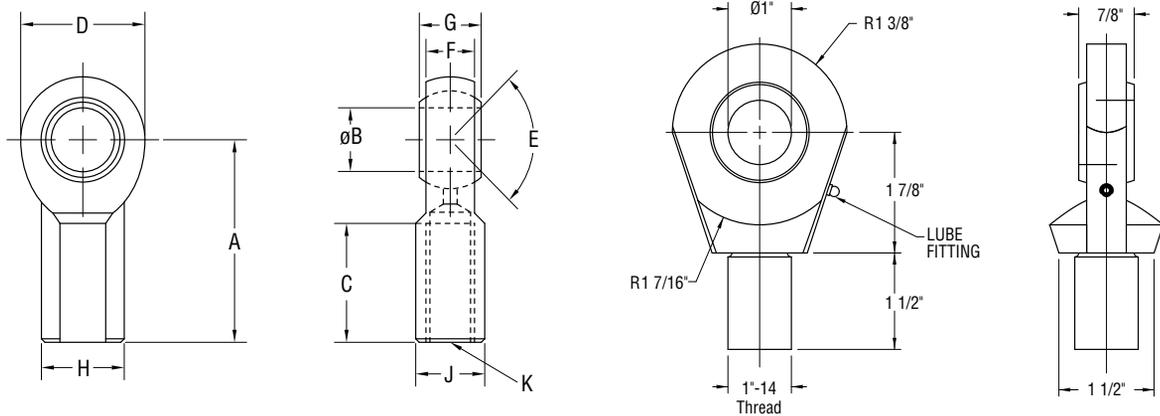
Dimensions for RC038



Dimensions for RE050, RC075, RC100, RC138

	A	B	C	D	E	ØF	ØG	H	ØJ	K
GSX20 RC038 in (mm)	0.810 (20.6)	0.785 (19.9)	1.595 (40.5)	0.182 (4.6)	0.386 (9.8)	0.373 (9.5)	0.951 (24.2)	NA	NA	3/8-24
GSX30 RC050 in (mm)	0.75 (19.1)	0.75 (19.1)	1.50 (38.1)	0.50 (12.7)	0.765 (19.43)	0.50 (12.7)	1.00 (25.4)	1.00 (25.4)	1.00 (25.4)	7/16-20
GSX40 RC075 in (mm)	1.125 (28.58)	1.25 (31.75)	2.375 (60.3)	0.625 (15.88)	1.265 (32.13)	0.75 (19.1)	1.50 (38.1)	1.25 (31.75)	1.25 (31.75)	3/4-16
GSX50 RC100 in (mm)	1.625 (41.2)	1.500 (38.1)	3.125 (79.4)	0.750 (19.1)	1.515 (38.5)	1.000 (25.4)	2.000 (50.8)	1.500 (38.1)	1.500 (38.1)	1-14
GSX60 RC138 in (mm)	2.00 (50.8)	2.125 (53.98)	4.125 (104.78)	1.00 (25.4)	2.032 (51.6)	1.375 (34.93)	2.75 (69.85)	2.00 (50.8)	2.00 (50.8)	1-1/4 - 12

Spherical Rod Eye Dimensions

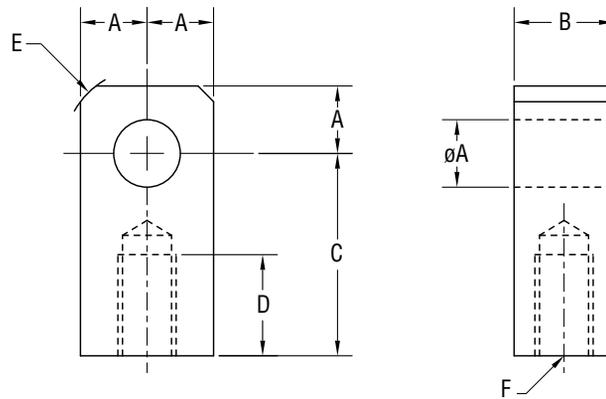


	A	ØB	C	D	E	F	G	H	J	K
GSX20 SRM038 in (mm)	1.625 (41.3)	.375 (9.525)	.906 (23.0)	1.0 (25.6)	12 deg	.406 (10.3)	.500 (12.7)	.688 (17.7)	.562 (14.3)	3/8-24
GSX30 SRM044 in (mm)	1.81 (46.0)	0.438 (11.13)	1.06 (26.9)	1.13 (28.7)	14 deg	0.44 (11.1)	0.56 (14.2)	0.75 (19.1)	0.63 (16.0)	7/16-20
GSX40 SRM075 in (mm)	2.88 (73.2)	0.75 (19.1)	1.72 (43.7)	1.75 (44.5)	14 deg	0.69 (17.5)	0.88 (22.3)	1.13 (28.7)	1.00 (25.4)	3/4-16
GSX50 SRF100 in (mm)	See GSX50 Special Rod Eye drawing below. Requires female rod end.									

Drawings subject to change. Consult Exlar for certified drawings.

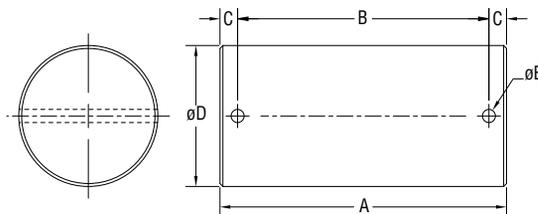
GSX Series Linear Actuators with Integrated Motor

Rod Eye Dimensions



	øA	B	C	D	E	F
GSX20 RE038 in (mm)	0.50 (12.7)	0.560 (14.2)	1.000 (25.4)	0.500 (12.7)	0.25 x 45°	3/8 - 24
GSX30 RE050 in (mm)	0.50 (12.7)	0.75 (19.1)	1.50 (38.1)	0.75 (19.1)	0.63 (15.9)	7/16 - 20
GSX40 RE075 in (mm)	0.75 (19.1)	1.25 (31.8)	2.06 (52.3)	1.13 (28.7)	0.88 (22.3)	3/4 - 16
GSX50 RE100 in (mm)	1.00 (25.4)	1.50 (38.1)	2.81 (71.4)	1.63 (41.4)	1.19 (30.2)	1 - 14
GSX60 RE138 in (mm)	1.375 (34.93)	2.0 (50.8)	3.44 (87.3)	2.0 (50.8)	1.837 (46.67)	1 1/4 - 12

Clevis Pin Dimensions



	A	B	C	øD	øE
CP050 ¹ in (mm)	2.28 (57.9)	1.94 (49.28)	0.17 (4.32)	0.50" +0.000/-0.002 (12.7 mm +0.00/-0.05)	0.106 (2.69)
CP075 ² in (mm)	3.09 (78.5)	2.72 (69.1)	0.19 (4.82)	0.75" +0.000/-0.002 (19.1 mm +0.00/-0.05)	0.14 (3.56)
CP100 ³ in (mm)	3.59 (91.2)	3.22 (81.8)	0.19 (4.82)	1.00" +0.000/-0.002 (25.4 mm +0.00/-0.05)	0.14 (3.56)
CP138 ⁴ in (mm)	4.66 (118.3)	4.25 (108)	0.20 (5.08)	1.375" +0.000/-0.002 (34.93 mm +0.00/-0.05)	0.173 (4.39)
CP175 ⁵ in (mm)	5.656 (143.6)	5.25 (133.3)	0.203 (5.15)	1.750" +0.000/-0.002 (44.4 mm +0.00/-0.05)	0.173 (4.39)

¹ Fits GSX20 and GSX30 rear clevis, RC050 and RE050

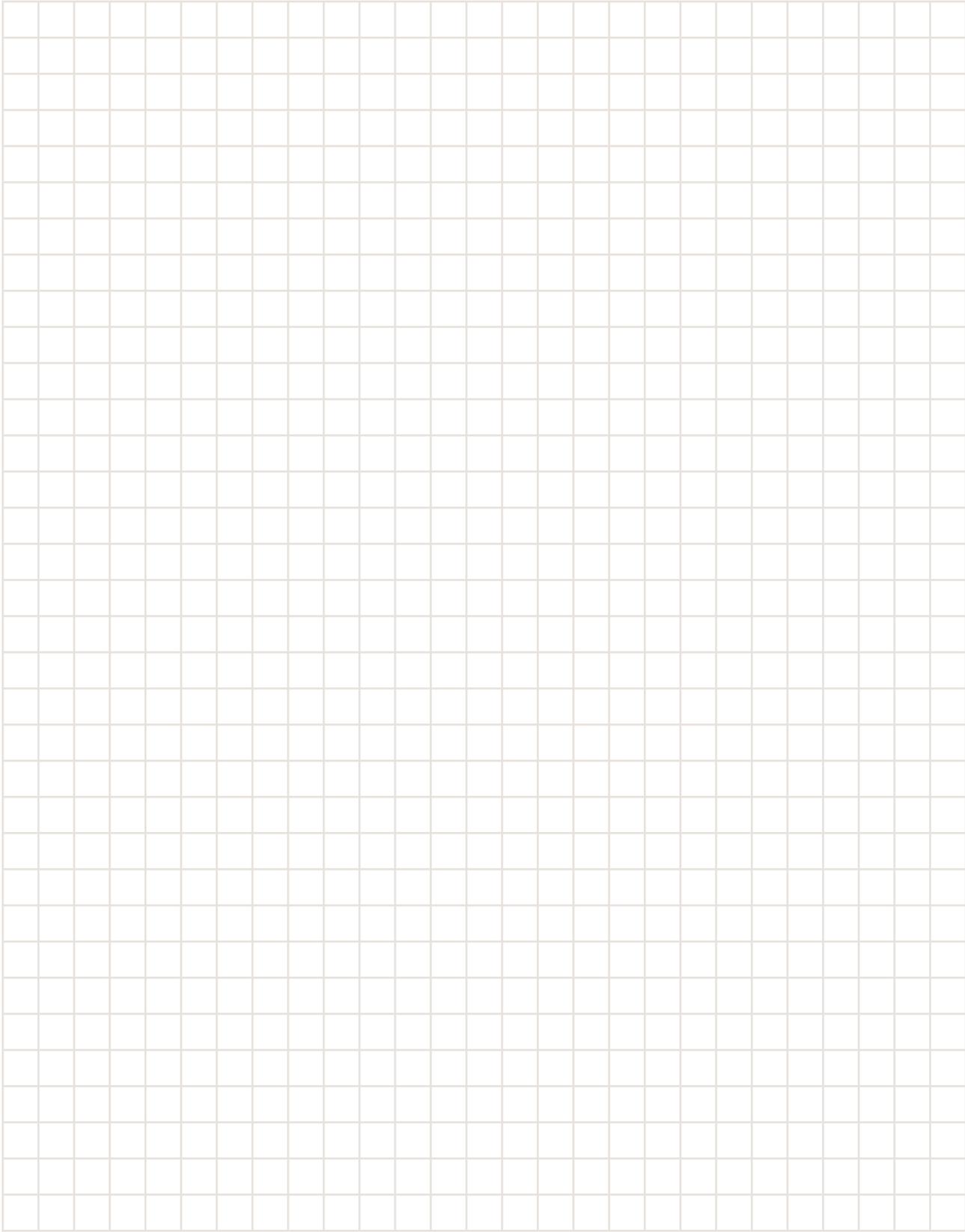
² Fits GSX30, 40 and RC075, RE075 and SMR075

³ Fits GSX50 rear clevis, RC100, RE100

⁴ Fits RC138, RE138

⁵ Fits GSX60 rear clevis

Drawings subject to change. Consult Exlar for certified drawings.



AA = GSX Actuator Frame Size (Nominal)

- 20 = 2 in (60 mm)
- 30 = 3 in (80 mm)
- 40 = 4 in (100 mm)
- 50 = 5.5 in (140 mm)
- 60 = 7 in (180 mm)

BB = Stroke Length

- 03 = 3 in (76 mm) GSX20, GSX30
- 04 = 4 in (102 mm) GSX40
- 06 = 5.9 in (150 mm) GSX30
6 in (152 mm) GSX20, GSX40,
GSX50, GSX60
- 08 = 8 in (203 mm) GSX40
- 10 = 10 in (254 mm) all models
- 12 = 12 in (305 mm) GSX20, GSX30,
GSX40
- 14 = 14 in (356 mm) GSX30, GSX50
- 18 = 18 in (457 mm) GSX30, GSX40
- 24 = 24 in (610 mm) GSX30

CC = Lead

- 01 = 0.1 in (2.54 mm) (GSX20, GSX30,
GSX40, GSX50)¹²
- 02 = 0.2 in (5.08 mm) (GSX20, GSX30,
GSX40, GSX50)
- 03 = 0.25 in (6.35 mm) (GSX60)
- 04 = 0.4 in (10.16 mm) (GSX20 only)
- 05 = 0.5 in (12.7 mm) (GSX30, GSX40,
GSX50, GSX60)
- 08 = 0.75 in (19.05 mm) (GSX40)⁸
- 10 = 1.0 in (25.4 mm) (GSX50, GSX60)⁹

D = Connections

- I = Exlar standard M23 style¹⁰
- M = Manufacturer's connector⁶
- A = MS style (anodized)
- D = MS style (electroless nickel)
- B = Embedded leads 3 ft. std.
- P = Embedded leads w/ "A" plug
3 ft. standard
- J = Embedded leads w/ "I" plug,
3 ft. standard
- X = Special (please specify)

E = Mounting

- B = Front and rear flange
- C = Rear clevis
- F = Front flange
- R = Rear flange
- S = Side mount
- D = Double side mount
- T = Side trunnion
- E = Extended tie rods
- J = Metric side mount
- K = Metric double side mount
- Q = Metric side trunnion
- M = Metric extended tie rods
- G = Metric rear clevis
- X = Special (please specify)

F = Rod End Thread/Rod Material

- M = Male, US std. thread
- A = Male, metric thread
- F = Female, US std. thread
- B = Female, metric thread
- W = Male, US std. thread SS²²
- R = Male, metric thread SS²²
- V = Female, US std. thread SS²²
- L = Female, metric thread SS²²
- X = Special (please specify)

GGG = Feedback Type (Also specify the Amplifier/Drive Model being used when ordering)

- Standard Incremental Encoder – 2048 line (8192 cts) per rev. index pulse, Hall commutation, 5vdc
- Standard Resolver – Size 15, 1024 line (2048 cts) per rev. two pole resolver
- Motor files for use with select Emerson/CT, Rockwell /AB and Danaher/Kollmorgen Drives are available at www.exlar.com

Custom Feedback - contact your local sales representative:

- XX1 = Wiring and feedback device information must be provided and new feedback callout will be created

Allen-Bradley/Rockwell: (Actuators used with Kinetix and/or Sercos based control systems require a .cmf file from AB/Rockwell. Please contact your AB/Rockwell representative for support.)

- AB8 = Standard Incremental Encoder – MPL Circular (Speedtec) DIN connectors for 'M' option
- AB9 = Hiperface Stegmann SRM050 absolute encoder – 40-50-60 Frame Size. MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option¹⁶
- ABB = Hiperface Stegmann SKM036 multi-turn absolute encoder. 20-30 Frame Size. MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option¹⁶

AMKASYN:

- AK1 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 40-50-60 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option
- AK2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 20-30 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option

Advanced Motion Control:

- AM1 = Standard Incremental Encoder
- AM2 = Encoder 1000 line, w/commutation, 5 VDC
- AM3 = Standard Resolver
- AM5 = Encoder 5000 line, w/commutation, 5 VDC

API Controls:

- AP1 = Standard Resolver
- AP2 = Standard Incremental Encoder

Aerotech:

- AR1 = Encoder 5000 line, w/commutation, 5 VDC
- AR2 = Standard Incremental Encoder

ABB Robot:

- BB1 = LTN Resolver

Baldor:

- BD2 = Std Resolver – BSM motor wiring w/M23 connectors for 'M' option
- BD3 = Std Incremental Encoder – BSM motor wiring w/M23 connectors for 'M' option

Beckhoff:

- BE2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AM5XX motor wiring w/M23 euro connectors for 'M' option

Baumüller:

- BM2 = Standard Resolver

B&R Automation:

- BR1 = Standard Resolver

- BR2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 8LS/8LM motor wiring w/M23 euro connectors for 'M' option

Comau Robot:

- CM1 = Standard Resolver

Copley Controls:

- CO1 = Standard Incremental Encoder
- CO2 = Standard Resolver

Control Techniques/Emerson:

- CT1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 40-50-60 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT3 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 20-30 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT4 = Standard Incremental Encoder – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT5 = Std Resolver – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT7 = Encoder 5000 line, with commutation, 5 VDC – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

Delta Tau Data Systems:

- DT1 = Encoder 1000 line, with commutation, 5 VDC
- DT2 = Standard Resolver

Elmo Motion Control:

- EL1 = Standard Resolver
- EL2 = Standard Incremental Encoder
- EL3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

Emerson/Control Techniques:

- EM2 = Std Incremental Encoder – NT motor wiring w/MS connectors for 'M' option
- EM5 = Encoder 5000 line, with commutation, 5 VDC – NT motor wiring w/MS connectors for 'M' option

Elau:

- EU1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 40-50-60 Frame Size. SH motor wiring w/MS connectors for 'M' option
- EU4 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 20-30 Frame Size. SH motor wiring w/MS connectors for 'M' option

Exlar:

- EX4 = Standard Resolver

Fanuc Pulsecoder:^{20,23} Consult Exlar

G&L Motion Control/Danaher Motion:

- GL1 = Std Incremental Encoder – HSM motor wiring w/ MS connectors for 'M' option
- GL2 = Std Incremental Encoder – LSM-MSM motor wiring w/M23 euro connectors for 'M' option
- GL3 = Std Incremental Encoder – NSM motor wiring w/MS connectors for 'M' option
- GL4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

Infranor:

- IF1 = Standard Resolver

Indramat/Bosch-Rexroth:

- IN6 = Std Resolver – MKD/MHD motor wiring w/M23 euro connectors for 'M' option

IN7 = Hiperface Stegmann SKM036 multi-turn absolute encoder – MSK motor wiring w/M23 euro connectors for 'M' option – plug & play option

Jetter Technologies:

JT1 = Standard Resolver – JH/JL motor wiring w/M23 euro connectors for 'M' option

Kollmorgen/Danaher:

KM4 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

KM5 = Standard Resolver – AKM motor wiring w/M23 euro connectors for 'M' option

KM6 = Standard Incremental Encoder – AKM motor wiring w/ M23 euro connectors for 'M' option

Kuka Robot:

KU1 = Tyco Size 21 Resolver²³

Kawasaki Robot:

KW1 = Kawasaki Special Encoder²³

Lenze/AC Tech:

LZ1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MCS motor wiring w/M23 euro connectors for 'M' option

LZ5 = Standard Resolver – MCS motor wiring w/ M23 euro connectors for 'M' option

LZ6 = Standard Incremental Encoder – MCS motor wiring w/ M23 euro connectors for 'M' option

Matuschek:

MC1 = LTN Resolver

Metronix:

MX1 = Standard Resolver

MX2 = Hiperface Stegmann SKM036 multi-turn absolute encoder

MX3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

Mitsubishi²⁰:

MT1 = Mitsubishi Absolute Encoder – HF-SP motor wiring with 'M' option

Modicon:

MD1 = Standard Resolver

Momentum:

MN1 = Hyperface Stegmann SRM050 multi-turn absolute encoder – MN motor wiring w/M23 connectors for 'M' option

MN2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – MN motor wiring connectors for 'M' option

MN3 = Std incremental encoder – MN motor wiring w/M23 connectors for 'M' option

MN4 = Std resolver – MN motor wiring w/M23 connectors for 'M' option

Moog:

MG1 = Standard Resolver

Motoman Robot:

MM1 = Yaskawa Serial Encoder²³

Nachi Robot:

NC1 = Tamagawa Serial Encoder²³

Ormec:

OR1 = Standard Resolver

OR2 = Std Incremental Encoder – G series motor wiring w/ MS connectors for 'M' option

Parker Compumotor:

PC6 = Std Incremental Encoder – SMH motor wiring w/M23 connectors for 'M' option – European only

PC7 = Std Resolver – SMH motor wiring w/M23 connectors for 'M' option – European only

PC8 = Standard Incremental Encoder – MPP series motor wiring w/PS connectors for 'M' option – US Only

PC9 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MPP motor wiring w/PS connectors for 'M' option – US Only

PC0 = Standard Resolver – MPP motor wiring w/PS connectors for 'M' option – US Only

Pacific Scientific:

PS2 = Standard Incremental Encoder

PS3 = Standard Resolver – PMA motor wiring w/M23 connectors for 'M' option

Stober Drives:

SB3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – ED/EK motor wiring w/M23 euro connectors for 'M' option

SB4 = Standard Resolver ED/EK motor wiring w/M23 connector for 'M' option

Siemens:

SM2 = Standard Resolver – 1FK7 motor wiring w/M23 connectors for 'M' option

SM3 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 40-50-60 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

SM4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 20-30 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

SEW/Eurodrive:

SW1 = Standard Resolver – CM motor wiring w/ M23 euro connectors for 'M' option

SW2 = Standard Incremental Encoder

SW3 = Hiperface Stegmann SRM050 multi-turn absolute encoder – CM motor wiring w/ M23 euro connectors for 'M' option

Whedco:

WD1 = Standard Resolver

Yaskawa:

YS2 = Yaskawa Absolute Encoder – SGMGH motor wiring 40 Exlar Frame Size

YS3 = Yaskawa Absolute Encoder – SGMGH motor wiring 20/30 Exlar Frame Sizes

HHH = Motor Stator – 8 Pole² Class 180H¹⁹

118 = 1 stack	115 Vrms	158 = 1 stack	400 Vrms
218 = 2 stack		258 = 2 stack	
318 = 3 stack		358 = 3 stack	
138 = 1 stack	230 Vrms	168 = 1 stack	460 Vrms
238 = 2 stack		268 = 2 stack	
338 = 3 stack		368 = 3 stack	

II = Motor Speed

24 = 2400 rpm, GSX50, GSX60

30 = 3000 rpm, GSX30, GSX40

50 = 5000 rpm, GSX20

01- 99 = Customer specified base speed

XX .. XX = Options

Travel Options

PF = Preloaded follower¹

AR = External anti-rotate assembly¹⁸

RB = Rear electric brake⁴

RD = Manual drive, Simple Rear^{13, 21}

SD = Manual drive, Side Hex²¹

HW = Manual drive, Handwheel with interlock switch^{14, 21}

PB = Protective bellows¹⁵

SR = Splined main rod^{11, 22}

XT = Special travel option (see pg. 23), high temp bellows¹⁵

L1/L2/L3 = External limit switches⁷

Motor Options

XM = Special motor option

XL = Special lubrication food grade or Mobilgrease 28 or use of oil cooling, specify (see page 27)

Housing Options

FG = White epoxy⁵

EN = Electroless nickel plating⁵

HC = Type III hard coat anodized, class I⁵

SS = Stainless steel housing^{5, 17}

XH = Special housing option

Absolute Linear Feedback

LT = ICT, including signal conditioner³

= Part No. Designator for Specials

Optional 5 digit assigned part number to designate unique model numbers for specials.

- The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw. Preloaded follower is not available with absolute linear (LT) internal feedback option.
- Stator voltage and pole options allow for catalog rated performance at varying amplifier bus voltages and pole configuration requirements. Refer to performance specification on pages 11-12 for availability of 3 stack stator.
- Linear feedback is not available in the GSX20 and not available in the GSX30, 14" and 18" or with absolute feedback.
- The brake option may require a third cable, consult local sales representative.
- These housing options would typically be accompanied by the choice of the electroless nickel connectors if a connectorized unit were selected. This choice may also indicate the need for special material main rods or mounting.
- Available as described in Feedback Types.
- Requires AR option.
- 0.75 lead not available above 12".
- 1.0 lead not available above 10" stroke.
- GSX60 uses M40 size 1.5 power connector.
- If not otherwise specified by the customer, an M24X2 male rod end will be used on the GSX50. See note on page 26.
- 0.1 lead not available over 10" stroke on GSX50.
- Not available with absolute feedback.
- Not available on GSX20.
- N/A with extended tie rod mounting option.
- Not compatible with Kinetix 300 Drives.
- Force, torque and current ratings are reduced 25% with this option.
- A second anti-rotate arm is used on GSX20, 30 & 40 for 10" and longer stroke.
- See page 28 for optimized stator offerings.
- Force measuring option N/A with Mitsubishi or Fanuc.
- N/A with holding brake unless application details are discussed with your local sales representative.
- Consult your local sales representative if ordering splined stainless steel main rod.
- Requires Robot Vendor Approval and Support.

GSM Series Linear Actuators with Integrated Motor

GSM Series—Standard Capacity Roller Screw Option

This design incorporates Exlar's patented roller screw technology with an integral brushless servo motor for medium to high performance motion control applications. The GSM Series offers 5 times the travel life of similarly sized ball screw actuators. It also provides a smaller package with higher speed and higher load capacity than ball screws and other traditional rotary to linear conversion mechanisms. These features make the GSM Series an excellent replacement for ball screw actuators.

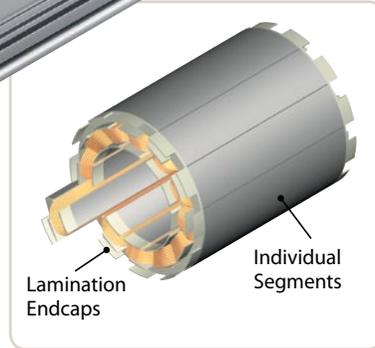
Selection of the proper feedback configuration allows GSM Series actuators to be powered by nearly every brand of brushless motor amplifier on the market. This flexibility allows GSM Series actuators to be incorporated into the highest performance single and multi-axis motion control systems in use today. In applications varying from food and beverage packaging, to multi-axis turning centers, to aircraft assembly, the GSM Series of actuators show incredible performance and durability.

Exlar's T-LAM technology incorporated into the motor design provides a solution with 35% more torque in the same package size as traditional brushless motors. The efficiencies of the GSM Series are a result of the limited heat generation qualities inherent in the segmented stator design. The elimination of end turns in the stator, and the use of thermally conductive potting removes the parts most susceptible to failure in a traditional stator. Other benefits include:

- Neodymium iron boron magnets provide high flux density and maximum motor torque.
- Thermally conductive potting of the entire stator provides increased heat dissipation and provides protection from contamination in oil-cooled units.
- Each stator segment contains individual phase wiring. External winding of individual segments provides maximum slot fill for maximum motor performance.
- Motors with T-LAM technology have Class H insulation systems compliant with UL requirements.



**Roller Screw
Driven** BY EXLAR



Features/Characteristics

T-LAM™ segmented lamination stator technology

2.25, 3.3 or 3.9 inch frame size

3, 4, 5.9, 6, 10, 12, 14, 18 and 24 inch strokes

0.1, 0.2, 0.4, 0.5 and .75 inch lead roller screws

7 to 75 lbf-in torque motor availability

Up to 33 inch per second linear speeds

92 to 1983 lbf thrust capacity depending on motor selection

Front flange, rear flange, rear clevis, trunnion, side, double side or extended tie rods mounting options

Encoder feedback with MS style connectors

Molded and shielded cables available

Anodized aluminum housing

Competitively priced with ball screw actuators

5 times the life of a similar sized ball screw actuator

IP54S or IP65S sealing

Class 180 H insulation

UL recognized component

Exlar GSM Series Linear Actuators Applications Include:

Hydraulic cylinder replacement

Ball screw replacement

Pneumatic cylinder replacement

Chip and wafer handling

Automated flexible fixturing

Dispensers

Machine tool

Automated assembly

Parts clamping

Automatic tool changers

Volumetric pumps

Medical equipment

Conveyor diverters / gates

Plastics equipment

Cut-offs

Die cutters

Packaging machinery

Entertainment

Sawmill equipment

Open / close doors

Fillers

Formers

Precision grinders

Indexing stages

Lifts

Product sorting

Material cutting

Material handling

Riveting / fastening / joining

Molding

Volumetric pumps

Semiconductor

Pick and place systems

Robot manipulator arms

Simulators

Precision valve control

Ventilation control systems

Pressing

Process control

Tube bending

Welding

Stamping

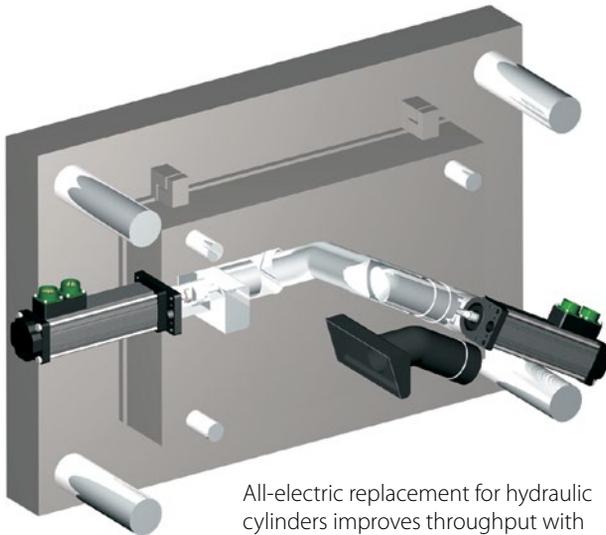
Test stands

Tension control

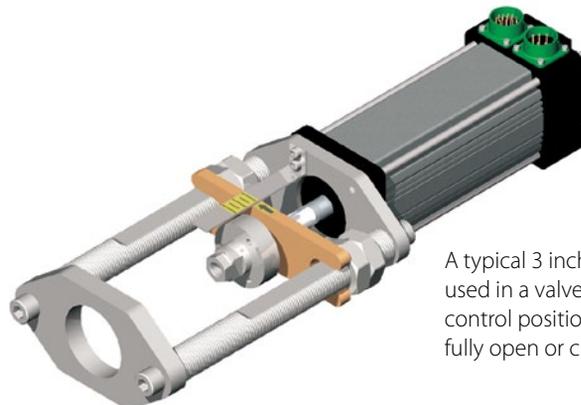
Web guidance

Wire winding

Food Processing



All-electric replacement for hydraulic cylinders improves throughput with servo control and less maintenance for core-pull cylinders.



A typical 3 inch stroke GSM Series actuator used in a valve-modulating application can control position to $\pm 0.5\%$ while ready to fully open or close in less than 200 mSec.

GSM-Series actuators can provide the precision at high force loads for fluid dispensing in a medical environment.

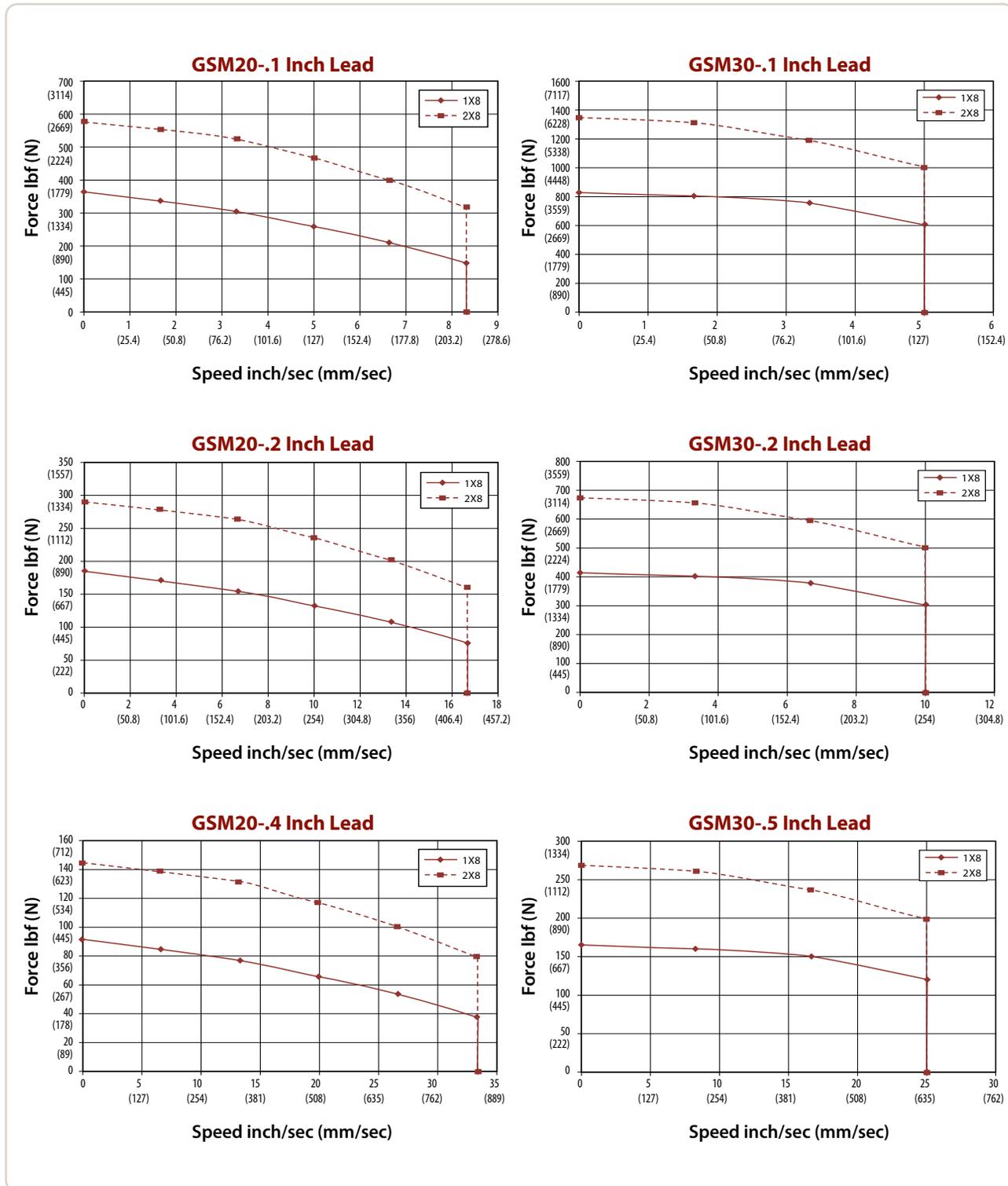


GSM Series Linear Actuators with Integrated Motor

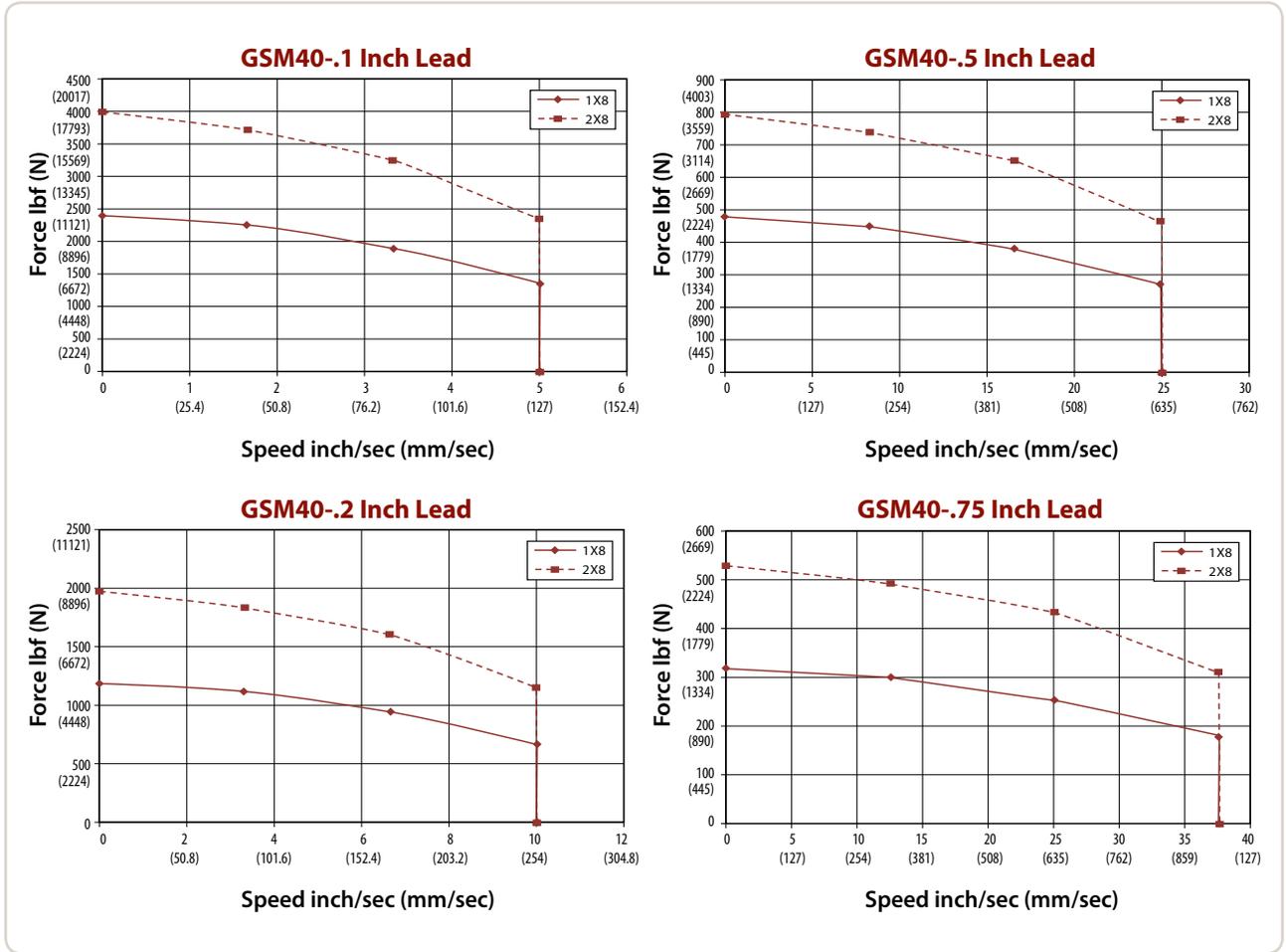
GSM Series Performance

The below speed vs. force curves represent approximate continuous thrust ratings at indicated linear speed. Different types of servo amplifiers will offer varying motor

torque and thus actuator thrust. These values are at constant velocity and do not account for motor torque required for acceleration.



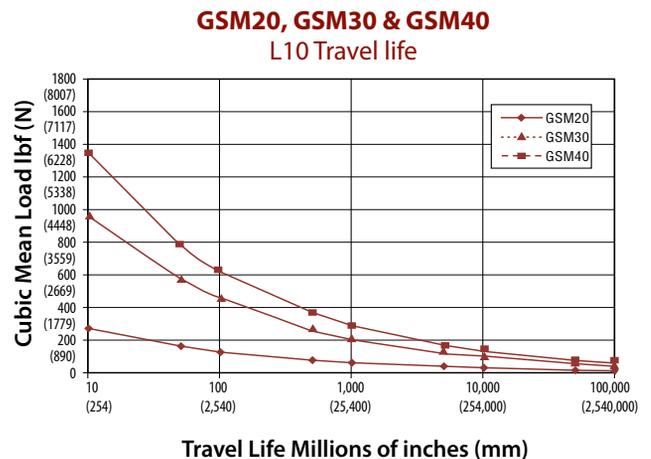
Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4" on GSM20 and 10" x 10" x 3/8" on GSM30



Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2" on GSM40

Life Curves

The estimated travel life indicates the approximate expected travel life from the roller screw mechanism within the GSM30 at indicated cubic mean load. The chart below represents L_{10} travel life estimates. The reliability for these values is 90%. For higher than 90% reliability, the result should be multiplied by the following factors: 95% x 0.62; 96% x 0.53; 97% x 0.44; 98% x 0.33; 99% x 0.21. This information assumes that the roller screw is properly maintained and lubricated. The equation used to calculate the L_{10} life is: $\text{Travel} (\frac{F}{C})^3 \times S$, where S = lead in millions of inches/mm. Where C = the dynamic load rating of the screw and F is the cubic mean load rating of the application. For higher than 90% reliability, derating of this value is implemented. Contact your local sales representative for details.



GSM Series Linear Actuators with Integrated Motor

GSM20 & GSM30 Performance Specifications

Model No.	Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Continuous Force Rating	Max Velocity	Maximum Static Load	Armature Inertia**	Dynamic Load Rating	Weight (approx.)
				lb (N) 1 stack/2 stack	in/sec (mm/sec)	lb (N)	lb-in-s ² (Kg-m ²)	lb (N)	lb (kg)
GSM20-0301	2.25 (57)	3 (76)	0.1 (2.54)	367/578 (1,632/2,571)	8.33 (211.67)	750 (3336)	0.00101 (0.000114)	1568 (6970)	6.5 (2.9)
GSM20-0302			0.2 (5.08)	195/307 (867/1,366)	16.77 (423.33)			1219 (5422)	
GSM20-0304			0.4 (10.16)	103/163 (459/723)	33.33 (846.67)			738 (3283)	
GSM20-0601	2.25 (57)	6 (152)	0.1 (2.54)	367/578 (1,632/2,571)	8.33 (211.67)	750 (3336)	0.00114 (0.000129)	1567 (6970)	7.0 (3.2)
GSM20-0602			0.2 (5.08)	195/307 (867/1,366)	16.67 (423.33)			1219 (5422)	
GSM20-0604			0.4 (10.16)	103/163 (459/723)	33.33 (846.67)			738 (3283)	
GSM20-1001	2.25 (57)	10 (254)	0.1 (2.54)	367/578 (1,632/2,571)	8.33 (211.67)	750 (3336)	0.00133 (0.000150)	1567 (6970)	7.5 (3.4)
GSM20-1002			0.2 (5.08)	195/307 (867/1,366)	16.67 (423.33)			1219 (5422)	
GSM20-1004			0.4 (10.16)	103/163 (459/723)	33.33 (846.67)			738 (3283)	
GSM20-1201	2.25 (57)	12 (305)	0.1 (2.54)	367/578 (1,632/2,571)	8.33 (211.67)	750 (3336)	0.00143 (0.000162)	1567 (6970)	8.0 (3.6)
GSM20-1202			0.2 (5.08)	195/307 (867/1,366)	16.67 (423.33)			1219 (5422)	
GSM20-1204			0.4 (10.16)	103/163 (459/723)	33.33 (846.67)			738 (3283)	
GSM30-0301	3.3 (84)	3 (76)	0.1 (2.54)	792/1,277 (3,521/5,680)	5 (127)	1620 (7206)	0.00319 (0.000360)	3310 (14724)	9.5 (4.3)
GSM30-0302			0.2 (5.08)	449/724 (1,995/3,219)	10 (254)			3570 (15880)	
GSM30-0305			0.5 (12.7)	190/306 (845/1,363)	25 (635)			3016 (13416)	
GSM30-0601	3.3 (84)	5.9 (150)	0.1 (2.54)	792/1,277 (3,521/5,680)	5 (127)	1620 (7206)	0.00361 (0.000408)	3310 (14724)	11.5 (5.2)
GSM30-0602			0.2 (5.08)	449/724 (1,995/3,219)	10 (254)			3570 (15880)	
GSM30-0605			0.5 (12.7)	190/306 (845/1,363)	25 (635)			3016 (13416)	
GSM30-1001	3.3 (84)	10 (254)	0.1 (2.54)	792/1,277 (3,521/5,680)	5 (127)	1620 (7206)	0.00416 (0.00047)	3310 (14724)	19 (8.6)
GSM30-1002			0.2 (5.08)	449/724 (1,995/3,219)	10 (254)			3570 (15880)	
GSM30-1005			0.5 (12.7)	190/306 (845/1,363)	25 (635)			3016 (13416)	
GSM30-1201	3.3 (84)	12 (305)	0.1 (2.54)	792/1,277 (3,521/5,680)	5 (127)	1620 (7206)	0.00443 (0.000501)	3310 (14724)	20.5 (9.3)
GSM30-1202			0.2 (5.08)	449/724 (1,995/3,219)	10 (254)			3570 (15880)	
GSM30-1205			0.5 (12.7)	190/306 (845/1,363)	25 (635)			3016 (13416)	
GSM30-1401	3.3 (84)	14 (356)	0.1 (2.54)	792/1,277 (3,521/5,680)	5 (127)	1620 (7206)	0.00473 (0.000534)	3310 (14724)	22 (10)
GSM30-1402			0.2 (5.08)	449/724 (1,995/3,219)	10 (254)			3570 (15880)	
GSM30-1405			0.5 (12.7)	190/306 (845/1,363)	25 (635)			3016 (13416)	
GSM30-1801	3.3 (84)	18 (457)	0.1 (2.54)	792/1,277 (3,521/5,680)	5 (127)	1620 (7206)	0.00533 (0.000602)	3310 (14724)	25 (11.3)
GSM30-1802			0.2 (5.08)	449/724 (1,995/3,219)	10 (254)			3570 (15880)	
GSM30-1805			0.5 (12.7)	190/306 (845/1,363)	25 (635)			3016 (13416)	
GSM30-2401	3.3 (84)	24 (610)	0.1 (2.54)	792/1,277 (3,521/5,680)	5 (127)	1620 (7206)	0.00615 (0.000695)	3310 (14724)	30 (13.6)
GSM30-2402			0.2 (5.08)	449/724 (1,995/3,219)	10 (254)			3570 (15880)	
GSM30-2405			0.5 (12.7)	190/306 (845/1,363)	25 (635)			3016 (13416)	

**Inertia +/- 5%

See page 47 for definition of terms.

GSM40 Performance Specifications

Model No.	Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Continuous Force Rating lb (N) 1 stack/2 stack	Max Velocity in/sec (mm/sec)	Maximum Static Load lb (N)	Armature Inertia** lb-in-s ² (Kg-m ²)	Dynamic Load Rating lb (N)	Weight (approx.) lb (kg)
GSM40-0401	3.9 (99)	4 (102)	0.1 (2.54)	2,089/NA (9,293/NA)	5 (127)	3966 (17642)	0.0140 (0.001582)	4736 (21067)	16 (7.3)
GSM40-0402			0.2 (5.08)	1,194/NA (5,310/NA)	10 (254)			4890 (21751)	
GSM40-0405			0.5 (12.7)	537/NA (2,390/NA)	25 (635)			4218 (18763)	
GSM40-0408			0.75 (19.05)	358/NA (1,593/NA)	37.5 (953)			3328 (14804)	
GSM40-0601	3.9 (99)	6 (152)	0.1 (2.54)	2,089/3,457 (9,293/15,377)	5 (127)	3966 (17642)	0.0152 (0.001717)	4736 (21067)	20 (9.1)
GSM40-0602			0.2 (5.08)	1,194/1,975 (5,310/8,787)	10 (254)			4890 (21751)	
GSM40-0605			0.5 (12.7)	537/889 (2,390/3,954)	25 (635)			4218 (18763)	
GSM40-0608			0.75 (19.05)	358/593 (1,593/2,636)	37.5 (953)			3328 (14804)	
GSM40-0801	3.9 (99)	8 (203)	0.1 (2.54)	2,089/3,457 (9,293/15,377)	5 (127)	3966 (17642)	0.0163 (0.001842)	4736 (21067)	24 (10.9)
GSM40-0802			0.2 (5.08)	1,194/1,975 (5,310/8,787)	10 (254)			4890 (21751)	
GSM40-0805			0.5 (12.7)	537/889 (2,390/3,954)	25 (635)			4218 (18763)	
GSM40-0808			0.75 (19.05)	358/593 (1,593/2,636)	37.5 (953)			3328 (14804)	
GSM40-1001	3.9 (99)	10 (254)	0.1 (2.54)	2,089/3,457 (9,293/15,377)	5 (127)	3966 (17642)	0.0175 (0.001977)	4736 (21067)	28 (12.7)
GSM40-1002			0.2 (5.08)	1,194/1,975 (5,310/8,787)	10 (254)			4890 (21751)	
GSM40-1005			0.5 (12.7)	537/889 (2,390/3,954)	25 (635)			4218 (18763)	
GSM40-1008			0.75 (19.05)	358/593 (1,593/2,636)	37.5 (953)			3328 (14804)	
GSM40-1201	3.9 (99)	12 (305)	0.1 (2.54)	2,089/3,457 (9,293/15,377)	5 (127)	3966 (17642)	0.0186 (0.002102)	4736 (21067)	32 (14.5)
GSM40-1202			0.2 (5.08)	1,194/1,975 (5,310/8,787)	10 (254)			4890 (21751)	
GSM40-1205			0.5 (12.7)	537/889 (2,390/3,954)	25 (635)			4218 (18763)	
GSM40-1208			0.75 (19.05)	358/593 (1,593/2,636)	37.5 (953)			3328 (14804)	
GSM40-1801	3.9 (99)	18 (457)	0.1 (2.54)	2,089/3,457 (9,293/15,377)	5 (127)	3966 (17642)	0.0220 (0.002486)	4736 (21067)	44 (19.9)
GSM40-1802			0.2 (5.08)	1,194/1,975 (5,310/8,787)	10 (254)			4890 (21751)	
GSM40-1805			0.5 (12.7)	537/889 (2,390/3,954)	25 (635)			4218 (18763)	

**Inertia +/- 5%

See below for definition of terms.

DEFINITION OF TERMS:

Continuous Force Rating: The linear force produced by the actuator at continuous motor torque.

Max Velocity: The linear velocity that the actuator will achieve at rated motor rpm.

Maximum Static Load: The mechanical load limit of the actuator if re-circulated oil or other cooling method is used to allow higher than rated torque from the motor.

Armature Inertia: The rotary inertia of the armature of the GSM Series actuators. For calculation purposes, this value includes the screw inertia in a GSM actuator.

Dynamic Load Rating: A design constant used in calculating the estimated travel life of the roller screw. The cubic mean load is the load at which the device will perform one million revolutions.

GSM Series Linear Actuators with Integrated Motor

GSM20 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.008 (.20)											
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)											
Maximum Radial Load	lb (N)	15 (67)											
Environmental Rating: Standard/Optional		IP54S/IP65S											
Motor Stator		118	138	158	168	218	238	258	268	318	338	358	368
RMS SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	7.6 (0.86)	7.3 (0.83)	7.0 (0.79)	7.0 (0.79)	11.9 (1.34)	11.5 (1.30)	11.0 (1.25)	11.3 (1.28)	15.0 (1.70)	15.3 (1.73)	14.6 (1.65)	14.9 (1.69)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	2.5 (0.28)	5.2 (0.59)	7.5 (0.85)	9.5 (1.07)	2.5 (0.28)	5.2 (0.59)	8.6 (0.97)	10.1 (1.15)	2.5 (0.29)	5.3 (0.59)	8.8 (0.99)	10.1 (1.15)
Continuous Current Rating	A	3.4	1.6	1.0	0.8	5.4	2.5	1.4	1.2	6.6	3.2	1.9	1.6
Peak Current Rating	A	6.9	3.1	2.1	1.6	10.8	4.9	2.9	2.5	13.2	6.5	3.7	3.3
O-PK SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	7.6 (0.86)	7.3 (0.83)	7.0 (0.79)	7.0 (0.79)	11.9 (1.34)	11.5 (1.30)	11.0 (1.25)	11.3 (1.28)	15.0 (1.70)	15.3 (1.73)	14.6 (1.65)	14.9 (1.69)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	1.7 (0.20)	3.7 (0.42)	5.3 (0.60)	6.7 (0.76)	1.7 (0.20)	3.7 (0.42)	6.1 (0.69)	7.2 (0.81)	1.8 (0.20)	3.7 (0.42)	6.2 (0.70)	7.2 (0.81)
Continuous Current Rating	A	4.9	2.2	1.5	1.2	7.6	3.5	2.0	1.8	9.4	4.6	2.6	2.3
Peak Current Rating	A	9.7	4.5	2.9	2.3	15.2	7.0	4.1	3.5	18.7	9.2	5.3	4.7
MOTOR STATOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm Vpk/Krpm	16.9	35.5	51.5	64.8	16.9	35.5	58.6	69.3	17.3	36.0	59.9	69.3
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	2.6	12.5	28.8	45.8	1.1	5.3	15.5	20.7	0.76	3.1	9.6	12.2
Inductance (L-L)(+/- 15%)	mH	4.6	21.4	47.9	68.3	2.5	10.2	28.3	39.5	1.7	7.4	18.5	27.4
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00012 (0.135)											
Brake Current @ 24 VDC	A	0.33											
Brake Holding Torque	lbf-in (Nm)	19 (2.2)											
Brake Engage/Disengage Time	ms	14/28											
Mechanical Time Constant (tm), ms	min	4.7	5.1	5.5	5.6	2.0	2.1	2.3	2.2	1.3	1.2	1.4	1.3
	max	6.6	7.2	7.9	7.9	2.8	3.0	3.3	3.1	1.8	1.8	1.9	1.8
Electrical Time Constant (te)	ms	1.8	1.7	1.7	1.5	2.2	1.9	1.8	1.9	2.3	2.4	1.9	2.2
Friction Torque	lbf-in (Nm)	1.0 (0.12)				1.1 (0.12)				1.1 (0.13)			
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	1.25 (0.14)				1.25 (0.14)				1.25 (0.14)			
Bus Voltage	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	5000											
Insulation Class		180 (H)											

All ratings at 25 degrees Celsius
 For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.
 Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4"

Specifications subject to change without notice.

GSM30 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.008 (.20)											
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)											
Maximum Radial Load	lb (N)	20 (90)											
Environmental Rating: Standard/Optional		IP54S/IP65S											
Motor Stator		118	138	158	168	218	238	258	268	318	338	358	368
RMS SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	16.9 (1.91)	16.8 (1.90)	16.3 (1.84)	16.0 (1.81)	26.9 (3.04)	27.1 (3.06)	26.7 (3.01)	27.0 (3.05)	38.7 (4.37)	38.2 (4.32)	36.2 (4.09)	36.3 (4.10)
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.97)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.97)	4.4 (0.50)	8.7 (0.98)	15.6 (1.77)	17.5 (1.98)
Continuous Current Rating	A	4.3	2.2	1.2	1.0	6.9	3.5	1.9	1.7	9.7	4.9	2.6	2.3
Peak Current Rating	A	8.6	4.3	2.4	2.0	13.8	6.9	3.8	3.4	19.5	9.9	5.2	4.6
0-PK SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	16.9 (1.91)	16.8 (1.90)	16.3 (1.84)	16.0 (1.81)	26.9 (3.04)	27.1 (3.06)	26.7 (3.01)	27.0 (3.05)	38.7 (4.37)	38.2 (4.32)	36.2 (4.09)	36.3 (4.10)
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	3.1 (0.35)	6.2 (0.70)	11.0 (1.24)	12.4 (1.40)	3.1 (0.35)	6.2 (0.70)	11.0 (1.24)	12.4 (1.40)	3.1 (0.35)	6.1 (0.69)	11.1 (1.25)	12.4 (1.40)
Continuous Current Rating	A	6.1	3.0	1.7	1.4	9.7	4.9	2.7	2.4	13.8	7.0	3.7	3.3
Peak Current Rating	A	12.2	6.1	3.3	2.9	19.5	9.8	5.4	4.9	27.6	13.9	7.3	6.5
MOTOR STATOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25 °C)	Vrms/Krpm	29.8	59.7	105.8	119.3	29.8	59.7	105.8	119.3	30.3	59.2	106.8	119.8
	Vpk/Krpm	42.2	84.4	149.7	168.7	42.2	84.4	149.7	168.7	42.9	83.7	151.0	169.4
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25 °C)	Ohms	2.7	10.8	36.3	47.9	1.1	4.4	14.1	17.6	0.65	2.6	9.3	11.6
Inductance (L-L)(+/- 15%)	mH	7.7	30.7	96.8	123.0	3.7	14.7	46.2	58.7	2.5	9.5	30.9	38.8
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00033 (0.38)											
Brake Current @ 24 VDC	A	0.5											
Brake Holding Torque	lbf-in (Nm)	70 (8)											
Brake Engage/Disengage Time	ms	19/29											
Mechanical Time Constant (tm), ms	min	4.9	4.9	5.2	5.4	2.0	2.0	2.0	2.0	1.1	1.2	1.3	1.3
	max	9.4	9.5	10.1	10.5	3.9	3.8	3.9	3.8	2.2	2.3	2.5	2.5
Electrical Time Constant (te)	ms	2.9	2.8	2.7	2.6	3.3	3.4	3.3	3.3	3.8	3.7	3.3	3.3
Friction Torque	lbf-in (Nm)	1.5 (0.17)				1.7 (0.19)				1.9 (0.21)			
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	1.75 (0.20)				1.75 (0.20)				1.75 (0.20)			
Bus Voltage	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	3000											
Insulation Class		180 (H)											

All ratings at 25 degrees Celsius
 For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.
 Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 3/8"

Specifications subject to change without notice.

GSM Series Linear Actuators with Integrated Motor

GSM40 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.008 (.20)											
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)											
Maximum Radial Load	lb (N)	30 (135)											
Environmental Rating: Standard/Optional		IP54S/IP65S											
Motor Stator		118	138	158	168	218	238	258	268	338	358	368	
RMS SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	47.5 (5.37)	47.5 (5.36)	45.9 (5.19)	45.4 (5.13)	75.1 (8.49)	78.6 (8.89)	78.7 (8.89)	79.5 (8.99)	106.9 (12.08)	105.3 (11.90)	106.9 (12.08)	
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/(Nm/A)	4.1 (0.46)	8.2 (0.93)	14.5 (1.64)	16.8 (1.90)	4.1 (0.46)	8.2 (0.93)	14.5 (1.64)	16.8 (1.90)	8.4 (0.95)	14.5 (1.64)	16.8 (1.90)	
Continuous Current Rating	A	12.9	6.5	3.5	3.0	20.5	10.7	6.0	5.3	14.2	8.1	7.1	
Peak Current Rating	A	25.9	12.9	7.1	6.0	40.9	21.4	12.1	10.6	28.5	16.2	14.2	
O-PK SINUSOIDAL COMMUTATION													
Continuous Motor Torque	lbf-in (Nm)	47.5 (5.37)	47.5 (5.36)	45.9 (5.19)	45.4 (5.13)	75.1 (8.49)	78.6 (8.89)	78.7 (8.89)	79.5 (8.99)	106.9 (12.08)	105.3 (11.90)	106.9 (12.08)	
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	2.9 (0.33)	5.8 (0.66)	10.3 (1.16)	11.9 (1.34)	2.9 (0.33)	5.8 (0.66)	10.3 (1.16)	11.9 (1.34)	5.9 (0.67)	10.3 (1.16)	11.9 (1.34)	
Continuous Current Rating	A	18.3	9.1	5.0	4.3	28.9	15.1	8.5	7.5	20.1	11.4	10.01	
Peak Current Rating	A	36.6	18.3	10.0	8.6	57.9	30.3	17.1	15.0	40.3	22.9	20.01	
MOTOR STATOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25 °C)	Vrms/Krpm Vpk/Krpm	28.0	56.0	99.3	114.6	28.0	56.0	99.3	114.6	57.3	99.3	114.6	
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	
Resistance (L-L)(+/- 5% @ 25 °C)	Ohms	0.42	1.7	5.7	7.8	0.2	0.72	2.26	3.0	0.5	1.52	2.0	
Inductance (L-L)(+/- 15%)	mH	3.0	11.9	37.5	49.9	1.2	5.4	18.2	23.1	4.0	12.0	16.0	
Brake Inertia	lb-in-sec ² (Kg-cm ²)	0.00096 (1.08)											
Brake Current @ 24 VDC	A	0.67											
Brake Holding Torque	lbf-in (Nm)	97 (11)											
Brake Engage/Disengage Time	ms	20/29											
Mechanical Time Constant (tm), ms	min	4.5	4.5	4.8	4.9	2.1	1.9	1.9	1.9	1.2	1.3	1.2	
	max	6.0	6.0	6.4	6.6	2.8	2.6	2.6	2.5	1.7	1.7	1.7	
Electrical Time Constant (te)	ms	7.0	7.0	6.6	6.4	5.9	7.5	8.0	7.8	8.2	7.9	8.2	
Friction Torque	lbf-in (Nm)	2.7 (0.31)					3.0 (0.34)				3.5 (0.40)		
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	3.00 (0.34)					3.00 (0.34)				3.00 (0.34)		
Bus Voltage	Vrms	115	230	400	460	115	230	400	460	230	400	460	
Speed @ Bus Voltage	rpm	3000											
Insulation Class		180 (H)											

All ratings at 25 degrees Celsius
For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.
Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2"

Specifications subject to change without notice.

GSM Series Travel Options

PF = Preloaded Follower

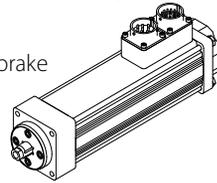
This option offers a true zero backlash follower for the GSM Series actuator. The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw for the same application. Preloaded follower is not available with LT Linear feedback option.

AR = External Anti-rotate Assembly

This option provides a rod and bushing to restrict the actuator rod from rotating when the load is not held by another method. Shorter actuators have single sided anti-rotation attachments. Longer lengths require attachments on both sides for proper operation. For AR dimensions, see page 26.

RB = Rear Electric Brake

This option provides an internal holding brake for the GSM Series actuators. The brake is spring activated and electrically released.



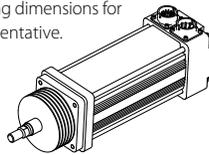
SR = Splined Main Rod

This option provides a main rod manufactured of ball spline shafting, and the front seal and bushing assembly replaced with a ball spline nut to provide the anti-rotate function without using an external mechanism. Rod diameters are the closest metric equivalents to standard Exlar rod sizes. This option is **NOT** sealed in any way. This option is not suitable for any environment in which contaminants come in contact with the actuator, and may enter the actuator.

Note: This option affects overall length and mounting dimensions for GSM actuators. Consult your local sales representative.

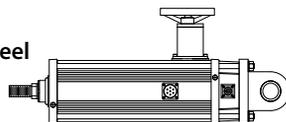
PB = Protective Bellows

This option provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environment in which the actuator must survive. The standard material of this bellows is S2 Neoprene Coated Nylon, Sewn Construction. This standard bellows is rated for environmental temperatures of -40 to 250 degrees F. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Not available with extended tie rod mounting option. Please contact your local sales representative.



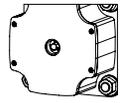
HW = Manual Drive, Handwheel

This option provides a manual drive handwheel on the side of the actuator. The handwheel has an engage/disengage lever that is tied to an interrupt switch. Not available on GSM20. Also not available with holding brake unless application details have been discussed with your local sales representative.



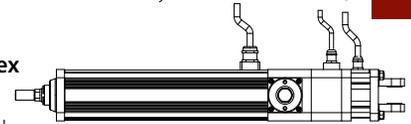
RD = Manual Drive, Rear Hex

This option provides a hex shaft at the rear of the actuator for manual operation. The hex shaft is directly coupled to the motor and can be turned by hand with a compatible wrench. The hex shaft is enclosed by a sealed cap during operation. N/A with holding brake unless application details have been discussed with your local sales representative.



SD = Manual Drive, Side Hex

This option provides a hex manual drive on the side of the actuator. The hex can be turned by hand with a wrench. Not available on GSM20. Also not available with holding brake unless application details have been discussed with your local sales representative.



XT = Special Travel Option Selections

The XT Option can be used to specify various special travel options on the GSM Series of Linear Actuators. Because this option can be used to specify many things, it is important that an order including the -XT option spell out in detail, the exact options being selected by the including of the -XT in the model number.

It is recommended that prior to ordering an actuator including the -XT specifier that a quote be obtained through Exlar's special products application engineers for the desired options, and that quote be referenced on, or included with any order placed.

High Temp Protective Bellows, an XT option, provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environment in which the actuator must survive. The high temperature material of this bellows is D1 Teflon Coated Fiberglass, Sewn Construction. This standard bellows is rated for environmental temperatures of -67 to 500 degrees F. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Not available with extended tie rod mounting option. Please contact your local sales representative for details.

L1, L2, L3 = Adjustable External Travel Switches

This option allows up to 3 external switches to be included with the GSM Series Actuator. These switches provide travel indication to the controller and are adjustable. See drawing on page 57. Must purchase external anti-rotate with this option.

XL = Non-Standard Lubrication

This option provides for indication in the model number that the customer has specified a lubrication other than the standard provided by Exlar, Mobilith SHC220. Specials include other greases including JAX FG-2 food grade, Mobilgrease 28, or other non-standard grease.

GSM Series Linear Actuators with Integrated Motor

Motor Speed Designators

All Exlar T-LAM™ motors and actuators carry a standard motor speed designator as defined below. This is representative of the standard base speed of the motor for the selected bus voltage.

If the model number is created and the location for the motor speed designator is left blank, this is the base speed to which each motor will be manufactured. The model number can also be created including this standard speed designator.

Designator	Base Speed	Actuator/Motor Series
-50	5000 rpm	GSM20
-30	3000 rpm	GSM30, GSM40
01-99	Special Speed, consult your local sales representative	

Exlar also provides the flexibility to manufacture all of its T-LAM products with special base speeds to match the customer's exact application requirements. This may be a higher than standard speed motor, or lower base speed than standard which will allow the customer to get the required torque at a speed optimized to their application and use the minimum amount of current from their amplifier.

The call out for a special speed is configured in the model number by using a two digit code from 01-99. These numbers represent the number, in hundreds, of RPM that will be the base speed for the particular motor.

For example, a GSM30-0301-MFM-EM2-138-30 motor that normally has a 3000 RPM standard winding can be changed to a 3300 RPM winding by changing the -30 to a -33. It can be changed to a 5000 RPM winding by changing the -30 to a -50.

Changing this speed designator will change the ratings of the motor, and these must be obtained from your local sales representative. Also, it is not possible to produce every possible speed from -01 to -99 for each motor at each voltage so please contact your local sales representative for confirmation of the speed that is desired for the application.

Feedback Options

LT = ICT including signal conditioner

This option provides for an actuator containing an internally mounted ICT transducer spanning the full stroke of the actuator. Inquire with your local sales representative for details and signal conditioner output preference. LT is not available with absolute feedback.

Due to the variability in size of some feedback devices, especially absolute feedback devices which are often very large relative to the size of the actuator motor, the actual size of the actuator may differ in length and width from these drawings for feedback types other than standard resolvers and standard encoders. Please consult your local sales representative. In the event that you order an actuator that differs from these standard dimensions, you will be sent a drawing of the final configuration of your actuator for approval.

Motor Options

GSM motor options are described with a 3 digit code. The first digit calls out the stack length, the second the rated bus voltage, and the third the number of poles of the motor. Refer to the mechanical/electrical specifications for motor torque and actuator rated force.

118	1 stack	115 Vrms	8 Pole	Class 180 H
138		230 Vrms		
158		400 Vrms		
168		460 Vrms		
1A8*		24 VDC		
1B8*		48 VDC		
1C8*	120 VDC			
218	2 stack	115 Vrms	8 Pole	Class 180 H
238		230 Vrms		
258		400 Vrms		
268		460 Vrms		
2A8*		24 VDC		
2B8*		48 VDC		
2C8*	120 VDC			

Note: 3 stack not available in GSM Series

* Low voltage stators may be limited to less than catalog rated torque and/or speed. Please contact your local sales representative when ordering this option.

Rod End Attachments

Rear Clevis Pin Rod Eye **Spherical Rod Eye Rod Clevis**

See drawings on pages 56-57.

Attachments ordered separate from actuator.

Housing Options

P5 = IP65S Sealing Option

Please read full description of IP Ratings on page 26.

HC = Type III Hard Coat Anodized, Class I

This option provides an actuator with type III hard coat anodized coating. Class I, no dye.

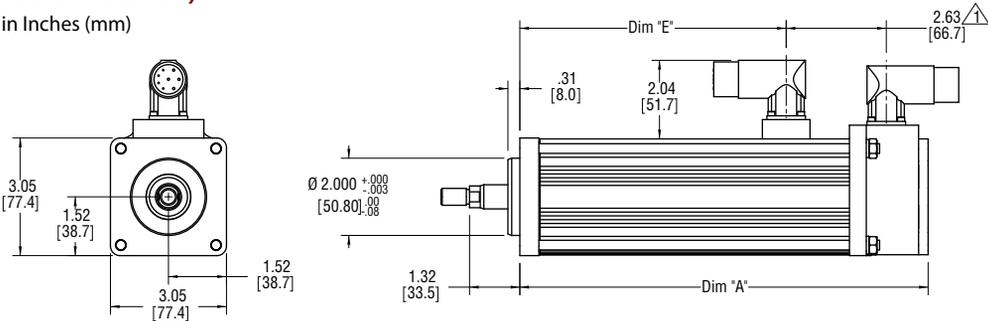
XH = Special Housing Option

Any housing option that is not designated by the above codes should be listed as XH and described at time of order. All special options must be discussed with your local sales representative.

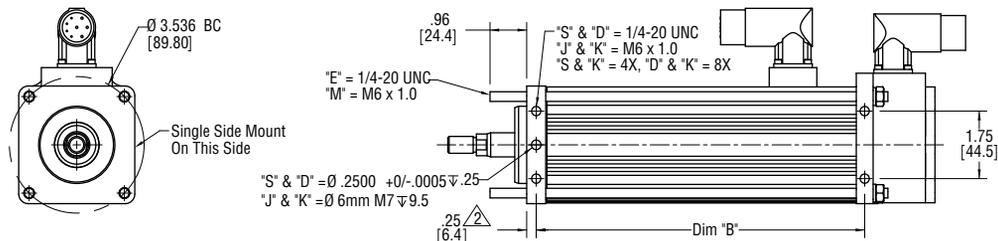
GSM Series Linear Actuators with Integrated Motor

GSM30 (Base Actuator)

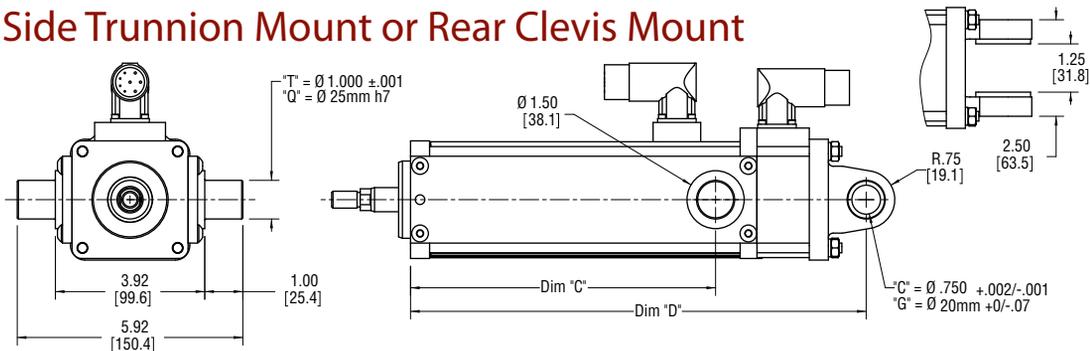
All Dimensions Shown in Inches (mm)



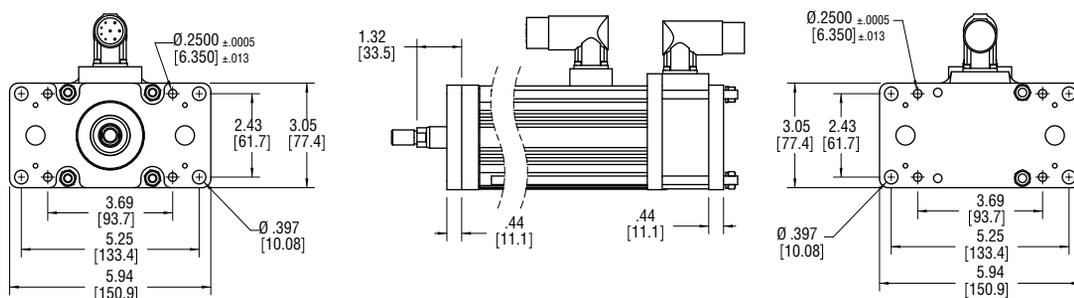
GSM30 Side Mounts or Extended Tie Rod Mount



GSM30 Side Trunnion Mount or Rear Clevis Mount



GSM30 Front or Rear Flange Mount



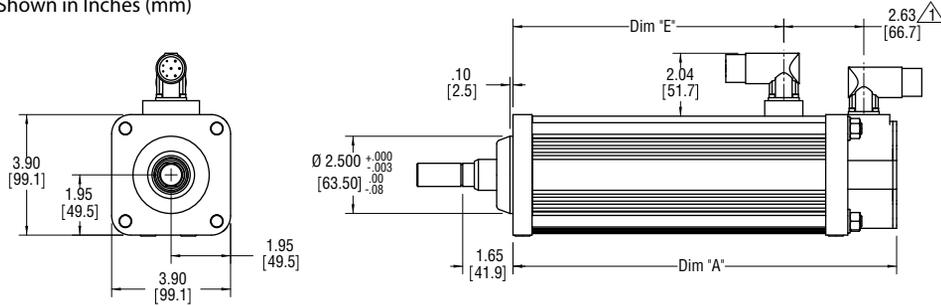
Dim	3" (76 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	14" (356 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	8.2 (209)	10.7 (272)	15.2 (387)	17.2 (437)	19.2 (539)	23.2 (590)
B	6.1 (156)	8.6 (219)	13.1 (333)	15.1 (384)	17.1 (485)	21.1 (536)
C	5.4 (137)	8.0 (203)	10.0 (254)	12.0 (305)	14.0 (406)	18.0 (457)
D	9.5 (241)	12.0 (304)	16.5 (418)	18.5 (469)	20.5 (570)	24.5 (621)
E	4.5 (114)	7.0 (178)	11.5 (292)	13.5 (343)	15.5 (394)	19.5 (495)

Notes:

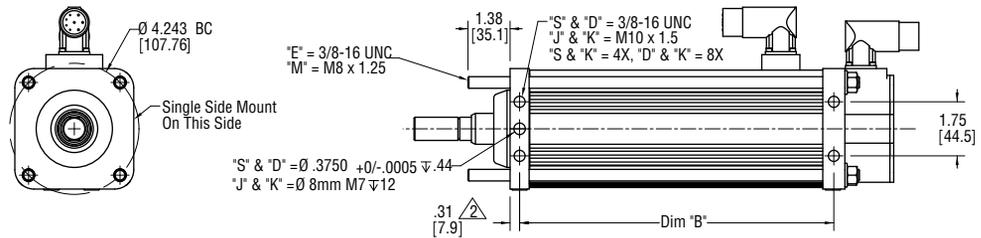
1. Add 1.6 Inches to Dims A & D and to Dim Δ if ordering a brake.
2. Add 1.20 Inches to Dims A, C, D, E and to Dim Δ if ordering a splined main rod.
3. Models are shown with Exlar standard M23 style connectors (option "I"). See ordering guide for other connector options.
4. Depending on connector and feedback options selected, dimensions may vary. Consult Exlar for details, or refer to the drawings provided after receipt of order.
5. Drawings subject to change.

GSM40 (Base Actuator)

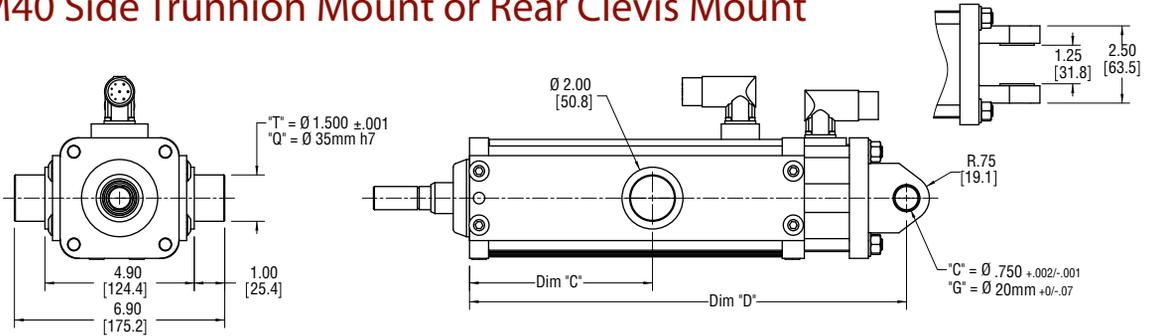
All Dimensions Shown in Inches (mm)



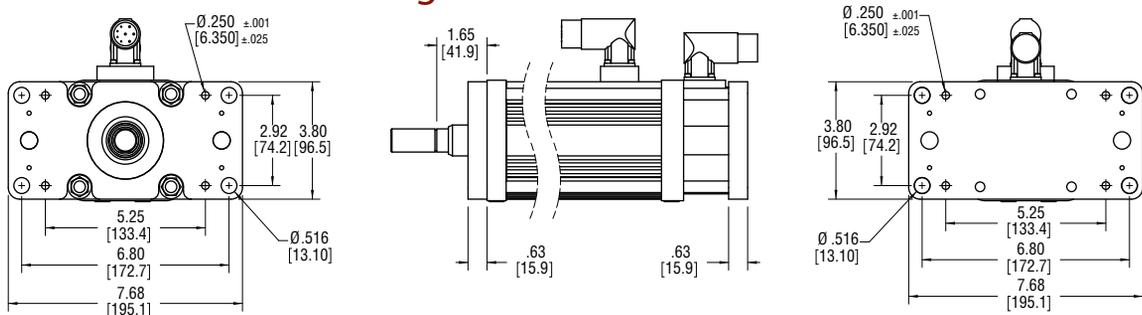
GSM40 Side Mounts or Extended Tie Rod Mount



GSM40 Side Trunnion Mount or Rear Clevis Mount



GSM40 Front or Rear Flange Mount



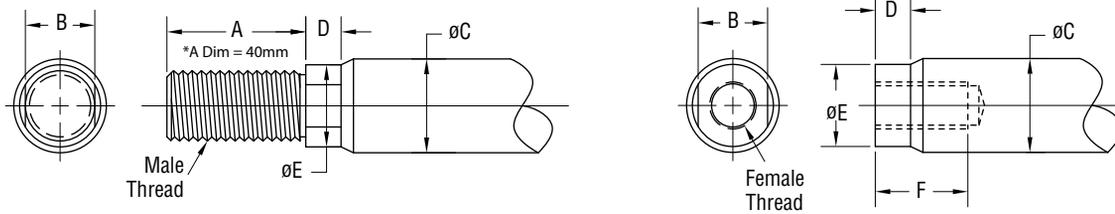
Dim	4" (102 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	8" (203 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	10.6 (269)	12.6 (320)	14.6 (370)	16.6 (421)	18.6 (472)	24.6 (624)
B	8.3 (211)	10.3 (262)	12.3 (313)	14.3 (364)	16.3 (414)	22.3 (567)
C	4.0 (102)	6.0 (152)	8.0 (203)	10.0 (254)	12.0 (305)	18.0 (457)
D	12.3 (312)	14.3 (363)	16.3 (415)	18.3 (466)	20.3 (516)	26.3 (669)
E	6.9 (175)	8.9 (226)	10.9 (277)	12.9 (328)	14.9 (378)	20.9 (531)

Notes:

1. Add 2.33 Inches to Dims A & D and to Dim Δ if ordering a brake.
2. Add 1.77 Inches to Dims A, C, D, E and to Dim Δ if ordering a splined main rod.
3. Models are shown with Exlar standard M23 style connectors (option "I"). See ordering guide for other connector options.
4. Depending on connector and feedback options selected, dimensions may vary. Consult Exlar for details, or refer to the drawings provided after receipt of order.
5. Drawings subject to change.

GSM Series Linear Actuators with Integrated Motor

Actuator Rod End Options



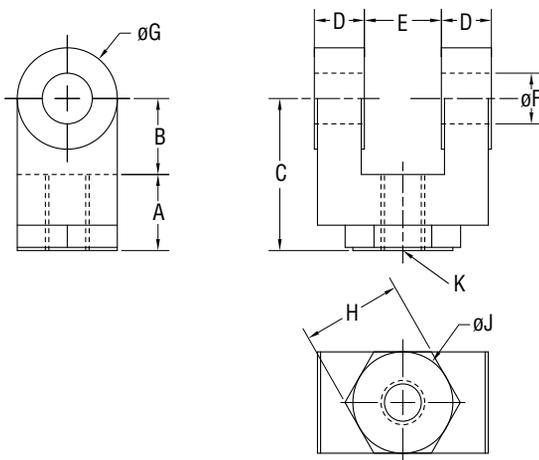
Standard Rod Ends

	A	B	$\varnothing C$	D	$\varnothing E$	F	Male U.S.	Male Metric	Female U.S.	Female Metric
GSM20 in (mm)	0.813 (20.7)	0.375 (9.5)	0.500 (12.7)	0.200 (5.1)	0.440 (11.2)	0.750 (19.1)	3/8 – 24 UNF – 2A	M8 x 1.6g	5/16 – 24 UNF – 2B	M8 x 1.6h
GSM30 in (mm)	0.750 (19.1)	0.500 (12.7)	0.625 (15.9)	0.281 (7.1)	0.562 (14.3)	0.750 (19.1)	7/16 – 20 UNF – 2A	M12 x 1.75* 6g	7/16 – 20 UNF – 2B	M10 x 1.5 6h
GSM40 in (mm)	1.500 (38.1)	0.750 (19.1)	1.000 (25.4)	0.381 (9.7)	0.875 (22.2)	1.000 (25.4)	3/4 – 16 UNF – 2A	M16 x 1.5 6g	5/8 – 18 UNF – 2B	M16 x 1.5 6h

Part numbers for rod attachment options indicate the through hole size or pin diameter. Before selecting a spherical rod eye for use with a GSM series actuator, please consult the information on the anti-rotation option for the GSM actuators. Spherical rod eyes will allow the rod to rotate if the load is not held.

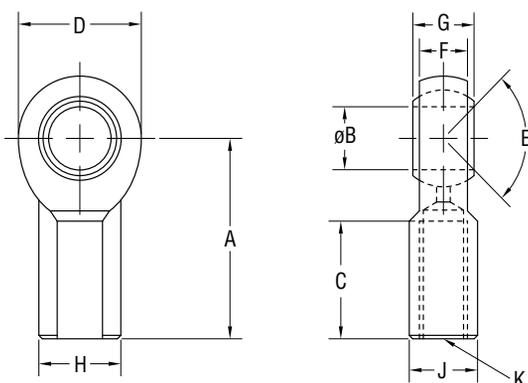
For Rod End with Splined Main Rod, see pg 36

Rod Clevis Dimensions



in (mm)	GSM20 RC038	GSM30 RC050	GSM40 RC075
A	0.810 (20.6)	0.75 (19.1)	1.125 (28.58)
B	0.785 (19.9)	0.75 (19.1)	1.25 (31.75)
C	1.595 (40.5)	1.50 (38.1)	2.375 (60.3)
D	0.182 (4.6)	0.50 (12.7)	0.625 (15.88)
E	0.386 (9.8)	0.765 (19.43)	1.265 (32.13)
$\varnothing F$	0.373 (9.5)	0.50 (12.7)	0.75 (19.1)
$\varnothing G$	0.951 (24.2)	1.00 (25.4)	1.50 (38.1)
H	NA	1.00 (25.4)	1.25 (31.75)
$\varnothing J$	NA	1.00 (25.4)	1.25 (31.75)
K	3/8-24	7/16-20	3/4-16

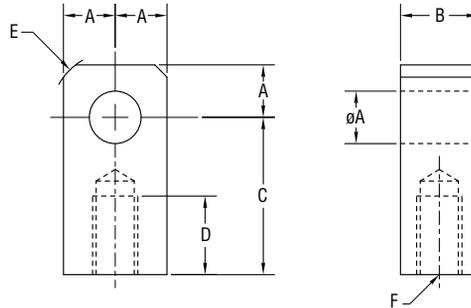
Spherical Rod Eye Dimensions



in (mm)	GSM20 SRM038	GSM30 SRM044	GSM40 SRM075
A	1.625 (41.3)	1.81 (46.0)	2.88 (73.2)
$\varnothing B$.375 (9.525)	0.438 (11.13)	0.75 (19.1)
C	.906 (23.0)	1.06 (26.9)	1.72 (43.7)
D	1.0 (25.4)	1.13 (28.7)	1.75 (44.5)
E	6 deg	14 deg	14 deg
F	.406 (10.3)	0.44 (11.1)	0.69 (17.5)
G	.500 (12.7)	0.56 (14.2)	0.88 (22.3)
H	.688 (17.4)	0.75 (19.1)	1.13 (28.7)
J	.562 (14.3)	0.63 (16.0)	1.00 (25.4)
K	3/8-24	7/16-20	3/4-1

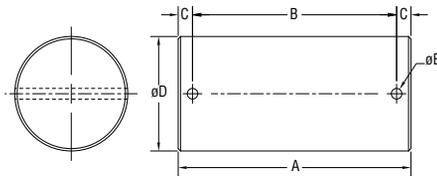
Drawings subject to change. Consult Exlar for certified drawings.

Rod Eye Dimensions



in (mm)	GSM20 RE038	GSM30 RE050	GSM40 RE075
ØA	0.50 (12.7)	0.50 (12.7)	0.75 (19.1)
B	0.560 (14.2)	0.75 (19.1)	1.25 (31.8)
C	1.00 (25.4)	1.50 (38.1)	2.06 (52.3)
D	0.50 (12.7)	0.75 (19.1)	1.13 (28.7)
E	0.25 x 45°	0.63 (16.0)	0.88 (22.3)
F	3/8 - 24	7/16 - 20	3/4 - 16

Rod Clevis Pin Dimensions



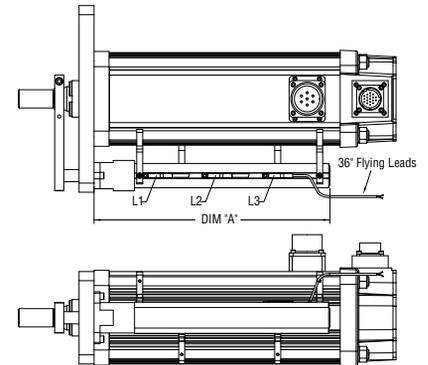
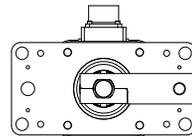
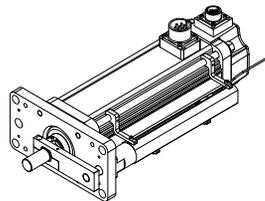
in (mm)	A	B	C	ØD	ØE
CP050 ¹	2.28 (57.9)	1.94 (49.28)	0.17 (4.32)	0.50" +0.000/-0.002 (12.7 mm +0.00/-0.05)	0.106 (2.69)
CP075 ²	3.09 (78.5)	2.72 (69.1)	0.19 (4.82)	0.75" +0.000/-0.002 (19.1 mm +0.00/-0.05)	0.14 (3.56)

¹ Fits GSM30 rear clevis, RC050 and RE050

² Fits GSM30, 40 and RC075, RE075 and SRM075

GSM20, GSM30 and GSM40 External Limit Switch Extension Options

Dim A	3" (76 mm) stroke in (mm)	6" (152 mm) stroke in (mm)	8" (203 mm) stroke in (mm)	10" (254 mm) stroke in (mm)	12" (305 mm) stroke in (mm)	18" (457 mm) stroke in (mm)
GSM20	5.515 (140.1)	8.515 (216.3)	NA	12.5 (317.5)	14.515 (368.7)	NA
GSM30	6.932 (176.1)	9.832 (249.7)	NA	13.832 (351.3)	15.832 (402.1)	21.832 (554.5)
GSM40	NA	9.832 (249.7)	11.83 (300.5)	13.832 (351.3)	15.832 (402.1)	21.832 (554.5)



* Dimensions for Anti rotate option can be seen on page 26.

The external limit switch option (requires anti-rotate option) for the GSM Series of linear actuators provides the user with 1, 2 or 3 externally mounted adjustable switches for use as the end of travel limit switches or home position sensors.

The number of switches desired is selected by ordering the L1, L2 or L3 option, in which 1, 2 or 3 switches will be provided, respectively.

The switches are 9-30 VDC powered, PNP output, with either normally open or normally closed logic operation depending on the switch configuration ordered. Switches are supplied with 1 meter, 3 wire embedded cable. Below is a diagram which logic operation will be provided for each switch, based on the option ordered.

Option	SW1	SW2	SW3
L1	Not Supplied	Normally Open	Not Supplied
L2	Normally Closed	Not Supplied	Normally Closed
L3	Normally Closed	Normally Open	Normally Closed

Switch Type	Exlar Part Number	Turck Part Number
Normally Closed Switch	43404	BIM-UNT-RP6X
Normally Open Switch	43403	BIM-UNT-AP6X

Drawings subject to change. Consult Exlar for certified drawings.

AA = GSM Actuator Size (nominal)

- 20 = 2 in (60 mm) frame
- 30 = 3 in (80 mm) frame
- 40 = 4 in (100 mm) frame

BB = Stroke Length

- 03 = 3 in (76 mm) GSM20 and GSM30
- 04 = 4 in (102 mm) GSM40
- 06 = 6 in (152 mm) all models
5.9 in (150 mm) GSM30
- 08 = 8 in (203 mm) GSM40
- 10 = 10 in (254 mm) GSM20, GSM30 and GSM40
- 12 = 12 in (305 mm) GSM20, GSM30 and GSM40
- 14 = 14 in (356 mm) GSM30
- 18 = 18 in (457 mm) GSM30 and GSM40
- 24 = 24 in (610 mm) GSM30

CC = Lead

- 01 = 0.1 in (2.54 mm) (all models)
- 02 = 0.2 in (5.08 mm) (all models)
- 04 = 0.4 in (10.16 mm) (GSM20)
- 05 = 0.5 in (12.7 mm) (GSM30 and GSM40)
- 08 = 0.75 in (19.05 mm) (GSM40)³

D = Connections

- I = Exlar standard M23 style
- M = Manufacturer's connector¹
- A = MS style (anodized)
- D = MS style (electroless nickel)
- B = Embedded leads 3 ft. std.
- P = Embedded leads w/plug 3 ft. standard w/"A" plug
- J = Embedded leads w/"I" plug, 3 ft. std
- X = Special (please specify)

E = Mounting

- B = Front and rear flange
- C = Rear clevis
- F = Front flange
- R = Rear flange
- S = Side mount
- D = Double side mount
- T = Side trunnion
- E = Extended tie rods
- J = Metric side mount
- K = Metric double side mount
- Q = Metric side trunnion
- M = Metric extended tie rods
- G = Metric rear clevis
- Z = Clevis mount with same pin to pin as SR Series
- X = Special (please specify)

F = Rod End Thread/Rod Material

- M = Male, US std. thread
- A = Male, metric thread
- F = Female, US std. thread
- B = Female, metric thread
- W = Male, US std. thread SS¹⁶
- R = Male metric thread SS¹⁶
- V = Female, US std. thread SS¹⁶
- L = Female, metric thread SS¹⁶
- X = Special (please specify)

GGG = Feedback Type (Also specify the Amplifier/Drive Model being used when ordering)

- Standard Incremental Encoder – 2048 line (8192 cts) per rev. index pulse, Hall commutation, 5vdc
- Standard Resolver – Size 15, 1024 line (2048 cts) per rev. two pole resolver
- Motor files for use with select Emerson/CT, Rockwell /AB and Danaher/Kollmorgen Drives are available at www.exlar.com
- Custom Feedback: contact your local sales representative:**
- XX1 = Wiring and feedback device information must be provided and new feedback callout will be created

Allen-Bradley/Rockwell: (Actuators used with Kinetix and/or Sercos based control systems require a .cmf file from AB/Rockwell. Please contact your AB/Rockwell representative for support.)

- AB8 = Standard Incremental Encoder – MPL Circular (Speedtec) DIN connectors for 'M' option
- AB9 = Hiperface Stegmann SRM050 absolute encoder – 40 Frame Size. MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option¹²
- ABB = Hiperface Stegmann SKM036 multi-turn absolute encoder. 20-30 Frame Size. MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option¹²

AMKASYN:

- AK1 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 40 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option
- AK2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 20-30 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option

Advanced Motion Control:

- AM1 = Standard Incremental Encoder
- AM2 = Encoder 1000 line, w/commutation, 5 VDC
- AM3 = Standard Resolver
- AM5 = Encoder 5000 line, w/commutation, 5 VDC

API Controls:

- AP1 = Standard Resolver
- AP2 = Standard Incremental Encoder

Aerotech:

- AR1 = Encoder 5000 line, w/commutation, 5 VDC
- AR2 = Standard Incremental Encoder

ABB Robot:

- BB1 = LTN Resolver

Baldor:

- BD2 = Std Resolver – BSM motor wiring w/M23 connectors for 'M' option
- BD3 = Std Incremental Encoder – BSM motor wiring w/M23 connectors for 'M' option

Beckhoff:

- BE2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AM5XX motor wiring w/M23 euro connectors for 'M' option

Baumüller:

- BM2 = Standard Resolver

B&R Automation:

- BR1 = Standard Resolver
- BR2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 8LS/8LM motor wiring w/M23 euro connectors for 'M' option

Comau Robot:

- CM1 = Standard Resolver

Copley Controls:

- CO1 = Standard Incremental Encoder
- CO2 = Standard Resolver

Control Techniques/Emerson:

- CT1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 40 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT3 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 20-30 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT4 = Standard Incremental Encoder – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT5 = Standard Resolver – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT7 = Encoder 5000 line, w/commutation, 5 VDC – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

Delta Tau Data Systems:

- DT1 = Encoder 1000 line, w/commutation, 5 VDC
- DT2 = Standard Resolver

Elmo Motion Control:

- EL1 = Standard Resolver
- EL2 = Standard Incremental Encoder
- EL3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

Emerson/Control Techniques:

- EM2 = Std Incremental Encoder – NT motor wiring w/MS connectors for 'M' option
- EM5 = Encoder 5000 line, with commutation, 5 VDC – NT motor wiring w/MS connectors for 'M' option

Elau:

- EU1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 40 Frame Size. SH motor wiring w/MS connectors for 'M' option
- EU4 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 20-30 Frame Size. SH motor wiring w/MS connectors for 'M' option

Exlar:

- EX4 = Standard Resolver

Fanuc Pulsecoder: Consult Exlar¹⁷

G&L Motion Control/Danaher Motion:

- GL1 = Std Incremental Encoder – HSM motor wiring w/ MS connectors for 'M' option
- GL2 = Std Incremental Encoder – LSM-MSM motor wiring w/M23 euro connectors for 'M' option
- GL3 = Std Incremental Encoder – NSM motor wiring w/MS connectors for 'M' option
- GL4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

Infranor:

IF1 = Standard Resolver

Indramat/Bosch-Rexroth:

IN6 = Std Resolver – MKD/MHD motor wiring w/M23 euro connectors for 'M' option

IN7 = Hiperface Stegmann SKM036 multi-turn absolute encoder – MSK motor wiring w/M23 euro connectors for 'M' option – plug & play option

Jetter Technologies:

JT1 = Standard Resolver – JH/JL motor wiring w/M23 euro connectors for 'M' option

Kollmorgen/Danaher:.06

KM4 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

KM5 = Standard Resolver – AKM motor wiring w/M23 euro connectors for 'M' option

KM6 = Standard Incremental Encoder – AKM motor wiring w/M23 euro connectors for 'M' option

Kuka Robot:

KU1 = Tyco Size 21 Resolver¹⁷

Kawasaki Robot:

KW1 = Kawasaki Special Encoder¹⁷

Lenze/AC Tech:

LZ1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MCS motor wiring w/M23 euro connectors for 'M' option

LZ5 = Std Resolver – MCS motor wiring w/ M23 euro connectors for 'M' option

LZ6 = Std Incremental Encoder – MCS motor wiring w/ M23 euro connectors for 'M' option

Matuschek:

MC1 = LTN Resolver

Metronix:

MX1 = Standard Resolver

MX2 = Hiperface Stegmann SKM036 multi-turn absolute encoder

MX3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

Mitsubishi:

MT1 = Mitsubishi Absolute Encoder – HF-SP motor wiring with 'M' option

Modicon:

MD1 = Standard Resolver

Momentum:

MN1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MN motor wiring w/M23 connectors for 'M' option

MN2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – MN motor wiring connectors for 'M' option

MN3 = Std incremental encoder – MN motor wiring w/M23 connectors for 'M' option

MN4 = Std resolver – MN motor wiring w/M23 connectors for 'M' option

Moog:

MG1 = Standard Resolver

Motoman Robot:

MM1 = Yaskawa Serial Encoder¹⁷

Nachi Robot:

NC1 = Tamagawa Serial Encoder¹⁷

Ormec:

OR1 = Standard Resolver

OR2 = Std Incremental Encoder – G series motor wiring w/MS connectors for 'M' option

Parker Compumotor:

PC6 = Std Incremental Encoder – SMH motor wiring w/M23 connectors for 'M' option – European only

PC7 = Std Resolver – SMH motor wiring w/M23 connectors for 'M' option – European only

PC8 = Std Incremental Encoder – MPP series motor wiring w/PS connectors for 'M' option – US Only

PC9 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MPP motor wiring w/PS connectors for 'M' option – US Only

PC0 = Std Resolver – MPP motor wiring w/PS connectors for 'M' option – US Only

Pacific Scientific:

PS2 = Standard Incremental Encoder

PS3 = Standard Resolver – PMA motor wiring w/M23 connectors for 'M' option

Stober Drives:

SB3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – ED/EK motor wiring w/M23 euro connectors for 'M' option

SB4 = Standard Resolver ED/EK motor wiring w/M23 connector for 'M' option

Siemens:

SM2 = Standard Resolver – 1FK7 motor wiring w/M23 connectors for 'M' option

SM3 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 40 Frame Size.

1FK7 motor wiring w/M23 euro connectors for 'M' option

SM4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 20-30 Frame Size.

1FK7 motor wiring w/M23 euro connectors for 'M' option

SEW/Eurodrive:

SW1 = Standard Resolver – CM motor wiring w/ M23 euro connectors for 'M' option

SW2 = Standard Incremental Encoder

SW3 = Hiperface Stegmann SRM050 multi-turn absolute encoder – CM motor wiring w/ M23 euro connectors for 'M' option

Whedco:

WD1 = Standard Resolver

Yaskawa:

YS2 = Yaskawa Absolute Encoder – SGMGH motor wiring 40 Exlar Frame Size

YS3 = Yaskawa Absolute Encoder – SGMGH motor wiring 20/30 Exlar Frame Sizes

HHH = Motor Stator² – All 8 Pole¹⁴

118 = 1 stack	115	158 = 1 stack	400
218 = 2 stack	Vrms	258 = 2 stack	Vrms
138 = 1 stack	230	168 = 1 stack	460
238 = 2 stack	Vrms	268 = 2 stack	Vrms

II = Motor Speed

30 = 3000 rpm, GSM30, GSM40

50 = 5000 rpm, GSM20

01- 99 = Customer specified base speed

XX .. XX = Travel and Housing Options (please list desired options)

Travel Options

AR = External anti-rotate¹³

HW = Manual drive, Handwheel with interlock switch^{10, 15}

PB = Protective bellows¹¹

SR = Splined main rod

RB = Rear brake

RD = Manual drive, Simple Rear^{9, 15}

SD = Manual drive, Side Hex¹⁵

PF = Preloaded follower⁴

L1/L2/L3 = External limit switch⁸

XT = Special travel options, high temperature bellows¹¹ or angular contact bearings

Housing Options

EN = Electroless nickel plating

XH = Special housing

P5 = IP65S sealing option⁵

HC = Type III hard coat anodized⁶

XL = Special lubrication, food grade or Mobilgrease 28, specify

XM = Special motor options

Absolute Linear Feedback

LT = ICT, including signal conditioner^{4, 7, 9}

= Part No. Designator for Specials

Optional 5 digit assigned part number to designate unique model numbers for specials.

Note:

- Available as described in Feedback Types.
- Stator voltage and pole options allow for catalog rated performance at varying amplifier bus voltages and pole configuration requirements.
- 0.75 lead not available over 12" stroke
- The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw. Preloaded follower is not available with absolute linear (LT) internal feedback option.
- Not available with splined main rod option.
- This housing option would typically be accompanied by the choice of the electroless nickel connectors if a connectorized unit were selected. This choice may also indicate the need for special material main rods or mounting.
- Linear feedback is not available in the GSM20 and not available in the GSM30, 14" and 18".
- Requires AR option
- Not available with absolute feedback.
- Not available on GSM20.
- Not available with extended tie rod mounting option.
- Not compatible with Kinetix 300 drives.
- A second anti-rotate arm is used on GSM 20, 30 & 40 for 10 inch and longer stroke.
- See page 52 for optimized stators.
- N/A with holding brake unless application details are discussed with your local sales representative.
- Consult with your local sales representative when ordering splined stainless steel main rod.
- Requires Robot Vendor Approval and Support.

FT Series Linear Actuators

Exlar FT Series force tube actuators use a planetary roller screw mounted inside a telescoping tube mechanism. The follower is attached to the moveable force tube, which then extends and retracts as the screw rotates. An external motor (supplied by Exlar or the customer) provides the rotational force.

High Performance

As with all of Exlar's roller screw products, the FT Series actuators deliver heavy load capacity, high speed capabilities, and exceptionally long life when compared to other linear actuator technologies.

Other comparably-sized screw actuator products on the market - specifically ball screw and acme screw actuators - have relatively low load capacities, short working lives and limited speed capabilities. At equivalent sizes, under moderate to heavy loads, it is reasonable to project that FT units will deliver up to 15 times the working life of those other designs. For OEM designers, this often means much more power and durability can be achieved from a much smaller footprint when Exlar FT units are used.

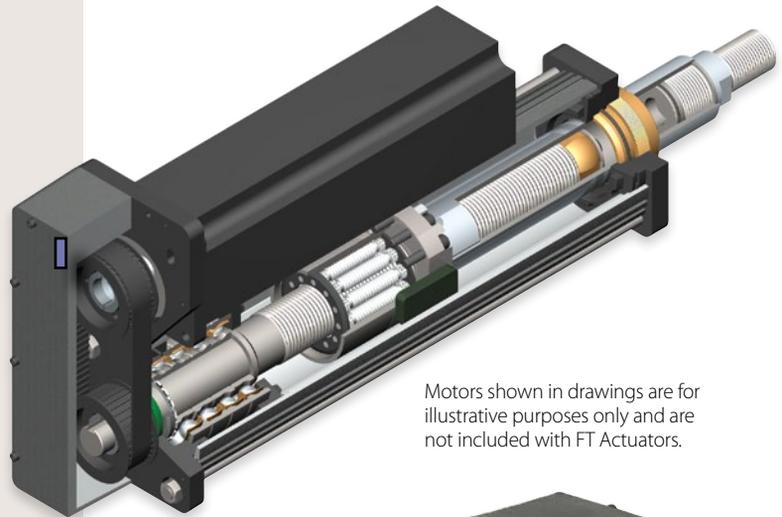
Contamination Protection

The FT Series design has all the contamination-isolation advantages of hydraulic cylinders without the limited load, life, and speed of designs built around ball or acme screws. The bearing and roller screw components in the Exlar FT Series force tubes are mounted within the sealed housing. This prevents abrasive particles and other contaminants from entering the actuator's critical mechanisms, and assures trouble-free operation even in the most severe environments.

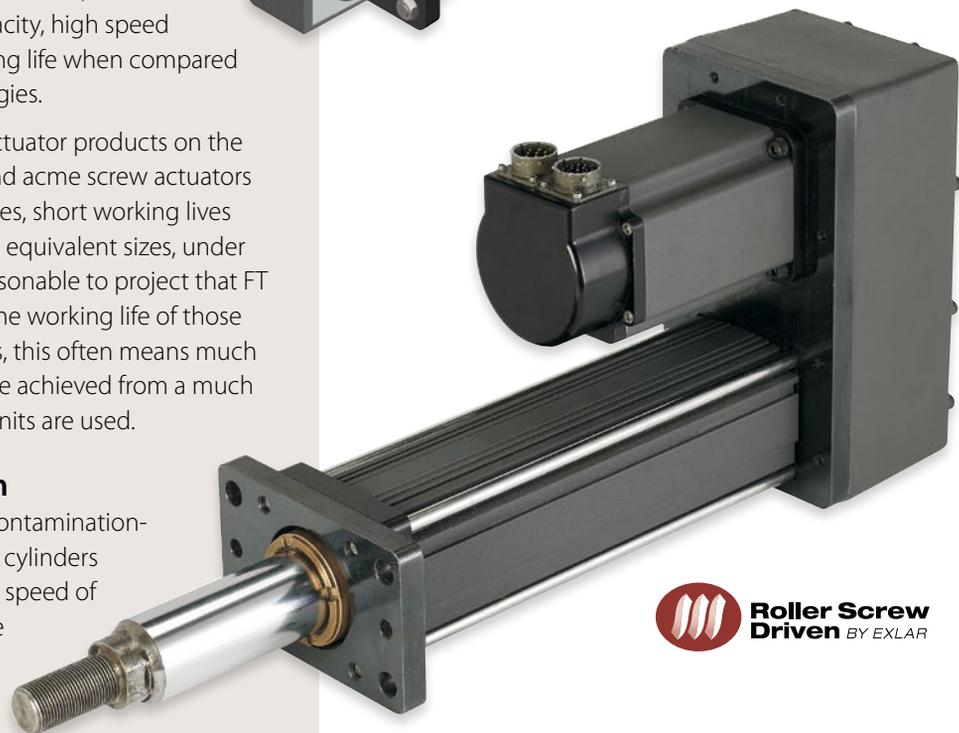
FT Series actuators are provided with standard grease lubrication. Custom provisions can be made for oil filled lubrication.

Engineered Compatibility

Exlar has removed much of the end-user-engineering burden by designing the FT series to be compatible with a wide variety of standard motors. Motor mounting, actuator mounting, and gearing configurations are available to meet nearly any application's requirements.



Motors shown in drawings are for illustrative purposes only and are not included with FT Actuators.



Feature	Standard	Optional
Long Strokes	6", 12", 18", 24", 36", and 48"	Intermediate Lengths up to 96"
Pre-Loaded Follower	No	Yes
External Limit Switches	No	One, two or three Adjustable Switches
Multiple Actuator Mountings	Side Mount, Side Lug, Extended Tie Rods, Rear Clevis, Front Flange, Side Trunnion, Rear Flange, Front/Rear Flange	Specials Available
Multiple Motor Mounting Configurations	Inline Direct Drive, Parallel 1:1 Drive, Parallel, 2:1 Reduction	Specials Available

Special Sealing Options

The base unit of the FT actuators are sealed at the extending rod end by a rod seal, and on the drive end by a shaft seal (see base unit drawings on pages 66, 68 and 70). These rod and shaft seals, and o-ring sealing provides IP65S sealing for the FT actuator base units.

In standard units with inline or parallel motor mounting, the mounting surface between the actuator and the motor, and between the end cover, or inline cover of the actuator and the actuator housing are not sealed as a standard feature.

These areas of the FT actuators can be sealed as a special option if the environment in which the actuator will be mounted requires the actuator to be sealed. Because of the vast differences in the design of various brands of motors that are mounted to the FT Series actuators, sealing of these two areas may alter the design of the actuator. Please contact your local sales representative for details and quotations on special sealing of this type.



Stainless steel FT35 with stainless steel SLM115 motor



Food grade & stainless steel FT35 with food grade SLM90 motor



Food grade & stainless steel FT60 with food grade SLG90 motor

Exlar FT Series Actuators Applications Include:

Hydraulic cylinder replacement

Ball screw replacement

Pneumatic cylinder replacement

Chip and wafer handling

Automated flexible fixturing

Dispensers

Machine tool

Automated assembly

Parts clamping

Automatic tool changers

Volumetric pumps

Medical equipment

Conveyor diverters / gates

Plastics equipment

Cut-offs

Die cutters

Packaging machinery

Entertainment

Sawmill equipment

Open / close doors

Fillers

Formers

Precision grinders

Indexing stages

Lifts

Product sorting

Material cutting

Material handling

Riveting / fastening / joining

Molding

Volumetric pumps

Semiconductor

Pick and place systems

Robot manipulator arms

Simulators

Precision valve control

Ventilation control systems

Pressing

Process control

Tube bending

Welding

Stamping

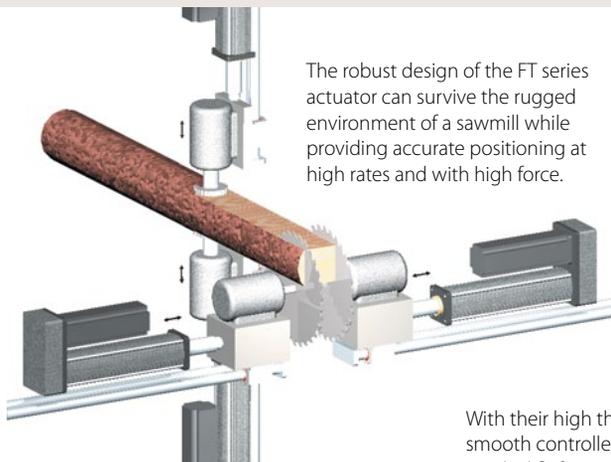
Test stands

Tension control

Web guidance

Wire winding

Food Processing

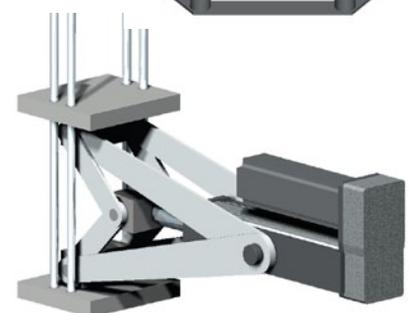


The robust design of the FT series actuator can survive the rugged environment of a sawmill while providing accurate positioning at high rates and with high force.

Motors shown in drawings are for illustrative purposes only and are not included with FT Actuators.

With their high thrust capability, compact size and smooth controlled motion, FT Series actuators are an ideal fit for replacing hydraulics or pneumatics on injection mold toggles. Control improvements from an electromechanical servo system offer less abuse of valuable molds and more consistent performance.

The smooth and accurate motion of Exlar's actuators combined with today's servo technology make multiple degree of freedom motion simulation applications easier to implement, cleaner and more efficient than hydraulic solutions.



FT Series Lifetime Curves

The L_{10} expected life of a roller screw linear actuator is expressed as the linear travel distance that 90% of properly maintained roller screws manufactured are expected to meet or exceed. For higher than 90% reliability, the result should be multiplied by the following factors: 95% x 0.62; 96% x 0.53; 97% x 0.44; 98% x 0.33; 99% x 0.21. This is not a guarantee and these charts should be used for estimation purposes only.

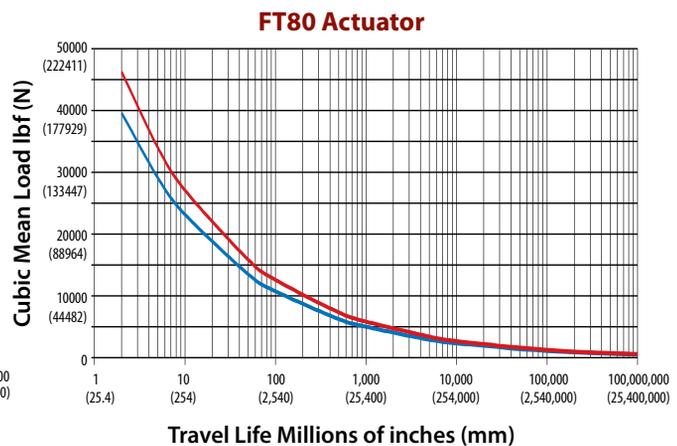
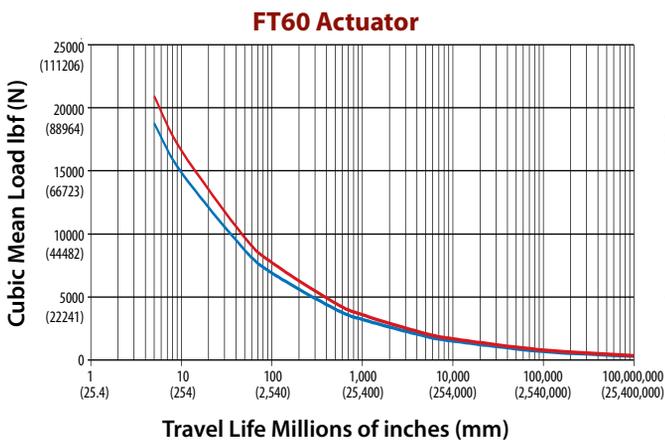
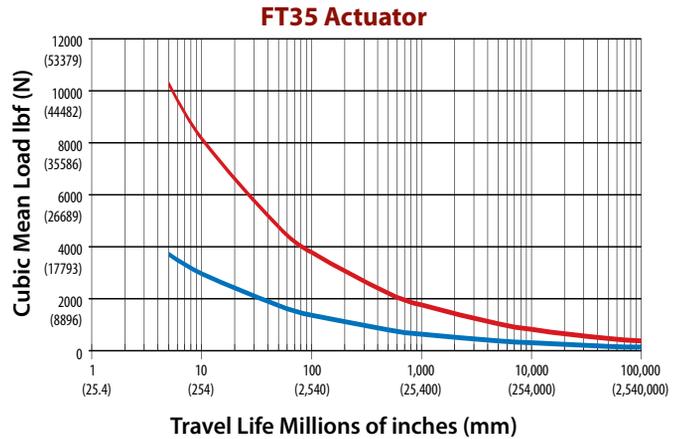
The underlying formula that defines this value is:

Travel life in millions of inches, where:

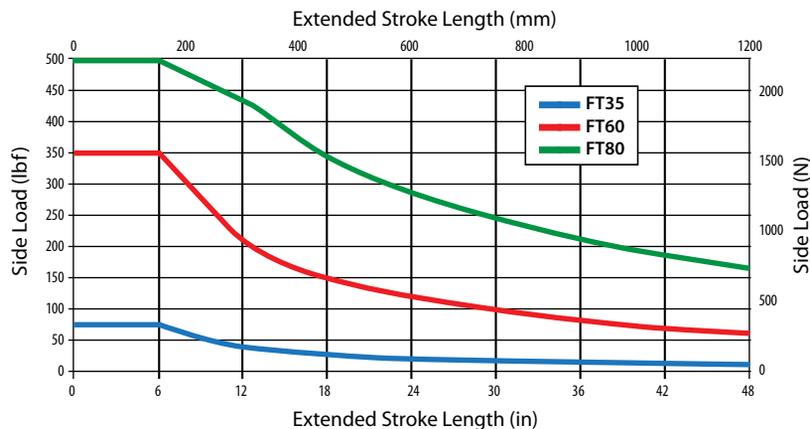
C = Dynamic load rating (lbf)
 F = Cubic mean applied load (lbf) $L_{10} = \left(\frac{C}{F}\right)^3 \times S$
 S = Roller screw's lead (inches)

All curves represent properly lubricated and maintained actuators.

█ FT35, 60 & 80 High Capacity
█ FT35, 60 & 80 Standard Capacity



FT Series Maximum Allowable Side Load



FT35 Series Performance Specifications

Model No.	Nominal Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Max Force lbf (kN)	Linear Speed at Max Rated RPM in/sec (mm/sec)	Dynamic Load Rating (Std capacity screw) lbf (kN)	Dynamic Load Rating (High capacity screw) lbf (kN)	Life at Max Force (Std capacity screw) 10 ⁶ in (Km)	Life at Max Force (High capacity screw) 10 ⁶ in (Km)	Max Input Torque lbf-in (Nm)	Max Rated Input rpm	Weight Base lb (kg)
FT35-0605	3.5 (89)	6 (152)	0.197 (5)	5,000 (22.2)	14.7 (373)	17,800 (79.2)	21,400 (95.2)	8.88 (225.6)	15.4 (392)	196 (22.1)	4,500	30 (14)
FT35-0610			0.394 (10)		29.5 (750)	16,500 (73.4)	19,850 (88.3)	14.15 (359.4)	24.6 (626)	392 (44.3)		
FT35-0620			0.787 (20)		59.3 (1500)	17,200 (76.5)	20,800 (92.5)	32.05 (814.2)	56.7 (1,440)	783 (88.5)		
FT35-1205	3.5 (89)	12 (305)	0.197 (5)	5,000 (22.2)	14.7 (373)	17,800 (79.2)	21,400 (95.2)	8.88 (225.6)	15.4 (392)	196 (22.1)	4,500	35 (16)
FT35-1210			0.394 (10)		29.5 (750)	16,500 (73.4)	19,850 (88.3)	14.15 (359.4)	24.6 (626)	392 (44.3)		
FT35-1220			0.787 (20)		59.3 (1500)	17,200 (76.5)	20,800 (92.5)	32.05 (814.2)	56.7 (1,440)	783 (88.5)		
FT35-1805	3.5 (89)	18 (457)	0.197 (5)	5,000 (22.2)	14.7 (373)	17,800 (79.2)	21,400 (95.2)	8.88 (225.6)	15.4 (392)	196 (22.1)	4,500	40 (18)
FT35-1810			0.394 (10)		29.5 (750)	16,500 (73.4)	19,850 (88.3)	14.15 (359.4)	24.6 (626)	392 (44.3)		
FT35-1820			0.787 (20)		59.3 (1500)	17,200 (76.5)	20,800 (92.5)	32.05 (814.2)	56.7 (1,440)	783 (88.5)		
FT35-2405	3.5 (89)	24 (610)	0.197 (5)	5,000 (22.2)	14.7 (373)	17,800 (79.2)	21,400 (95.2)	8.88 (225.6)	15.4 (392)	196 (22.1)	4,500	45 (21)
FT35-2410			0.394 (10)		29.5 (750)	16,500 (73.4)	19,850 (88.3)	14.15 (359.4)	24.6 (626)	392 (44.3)		
FT35-2420			0.787 (20)		59.3 (1500)	17,200 (76.5)	20,800 (92.5)	32.05 (814.2)	56.7 (1,440)	783 (88.5)		
FT35-3605	3.5 (89)	36 (914)	0.197 (5)	5,000 (22.2)	8.9 (226)	17,800 (79.2)	21,400 (95.2)	8.88 (225.6)	15.4 (392)	196 (22.1)	2,700	55 (25)
FT35-3610			0.394 (10)		17.8 (452)	16,500 (73.4)	19,850 (88.3)	14.15 (359.4)	24.6 (626)	392 (44.3)		
FT35-3620			0.787 (20)		35.6 (903)	17,200 (76.5)	20,800 (92.5)	32.05 (814.2)	56.7 (1,440)	783 (88.5)		
FT35-4805	3.5 (89)	48 (1219)	0.197 (5)	5,000 (22.2)	5.7 (145)	17,800 (79.2)	21,400 (95.2)	8.88 (225.6)	15.4 (392)	196 (22.1)	1,700	65 (30)
FT35-4810			0.394 (10)		11.4 (290)	16,500 (73.4)	19,850 (88.3)	14.15 (359.4)	24.6 (626)	392 (44.3)		
FT35-4820			0.787 (20)		22.4 (568)	17,200 (76.5)	20,800 (92.5)	32.05 (814.2)	56.7 (1,440)	783 (88.5)		

Intermediate and custom stroke lengths are available. Intermediate leads may also be available. Belt and pulley inertia varies with ratio & motor selection. Please contact your local sales representative. See page 64 for definition of terms.

¹ FT35 actuators with high capacity screw option are 20 mm longer. See dimensions page 66.

² The rated and max force on the FT series actuators are those forces derived from using typical servo motors of similar frame size to the actuator, at their rated continuous and peak torques. In many cases FT actuators can be configured with input torque sufficient to exceed these forces. Contact your local sales representative for further details.

Standard Inline Coupling Maximum Torque Ratings and Inertia

FT35	Torque Rating	Inertia
	354 lbf-in (40 N-m)	0.000104 kg-m ² (0.000920 lbf-in ²)

Shown below are pulley inertias reflected at motor including typical pulleys, belt and standard bushings. Because of differences in belt and pulley selection due to particular motor choices, please contact your local sales representative if these values are critical to your application.

FT35 Reflective Inertias

	5 mm Lead	10 mm Lead	20 mm Lead	
NMT Unit - J (0)	0.0004087	0.0004121	0.0004259	kg-m ² (at input shaft)
NMT Unit - J (Stroke)	0.0000159	0.0000162	0.0000171	kg-m ² /inch of stroke
Inline w/ Coupler - J (0)	0.0005127	0.0005161	0.0005299	kg-m ² (at motor shaft)
Inline w/ Coupler - J (Stroke)	0.0000159	0.0000162	0.0000171	
Parallel 1:1 - J (0)	0.0011042	0.0011855	0.0014480	kg-m ² /inch of stroke
Parallel 1:1 - J (Stroke)	0.0000159	0.0000162	0.0000171	
Parallel 2:1 - J (0)	0.0014029	0.0014038	0.0015345	kg-m ² /inch of stroke
Parallel 2:1 - J (Stroke)	0.0000040	0.0000040	0.0000043	

*Pulleys for parallel mount match actuator max performance ratings

FT60 Series Performance Specifications

Model No.	Nominal Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Max Force lbf (kN)	Linear Speed at Max Rated RPM in/sec (mm/sec)	Dynamic Load Rating (Std capacity screw) lbf (kN)	Dynamic Load Rating (High capacity screw) lbf (kN)	Life at Max Force (Std capacity screw) 10 ⁶ in (Km)	Life at Max Force (High capacity screw) 10 ⁶ in (Km)	Max Input Torque lbf-in (Nm)	Max Rated Input rpm	Weight Base lb (kg)
FT60-1206	6.0 (152)	12 (305)	0.236 (6)	20,000 (89.0)	7.9 (201)	51,900 (230.9)	57,933 (257.7)	4.1 (104.8)	5.7 (145.8)	940 (106)	2000	100 (45)
FT60-1212			0.472 (12)		15.8 (401)	44,600 (198.4)	49,750 (221.3)	5.2 (133.1)	7.3 (184.7)	1880 (212)		
FT60-1230			1.181 (30)		39.0 (1000)	41,700 (185.5)	63,958 (284.5)	10.7 (271.9)	38.6 (981.1)	4699 (531)		
FT60-2406	6.0 (152)	24 (610)	0.236 (6)	20,000 (89.0)	7.9 (201)	51,900 (230.9)	57,933 (257.7)	4.1 (104.8)	5.7 (145.8)	940 (106)	2000	130 (59)
FT60-2412			0.472 (12)		15.8 (401)	44,600 (198.4)	49,750 (221.3)	5.2 (133.1)	7.3 (184.7)	1880 (212)		
FT60-2430			1.181 (30)		39.0 (1000)	41,700 (185.5)	63,958 (284.5)	10.7 (271.9)	38.6 (981.1)	4699 (531)		
FT60-3606	6.0 (152)	36 (914)	0.236 (6)	20,000 (89.0)	7.9 (201)	51,900 (230.9)	57,933 (257.7)	4.1 (104.8)	5.7 (145.8)	940 (106)	2000	160 (72)
FT60-3612			0.472 (12)		15.8 (401)	44,600 (198.4)	49,750 (221.3)	5.2 (133.1)	7.3 (184.7)	1880 (212)		
FT60-3630			1.181 (30)		39.0 (1000)	41,700 (185.5)	63,958 (284.5)	10.7 (271.9)	38.6 (981.1)	4699 (531)		
FT60-4806	6.0 (152)	48 (1219)	0.236 (6)	20,000 (89.0)	7.9 (201)	51,900 (230.9)	57,933 (257.7)	4.1 (104.8)	5.7 (145.8)	940 (106)	2000	190 (86)
FT60-4812			0.472 (12)		15.8 (401)	44,600 (198.4)	49,750 (221.3)	5.2 (133.1)	7.3 (184.7)	1880 (212)		
FT60-4830			1.181 (30)		39.0 (1000)	41,700 (185.5)	63,958 (284.5)	10.7 (271.9)	38.6 (981.1)	4699 (531)		

Intermediate and custom stroke lengths are also available. Intermediate leads may also be available. Belt and pulley inertia varies with ratio and motor selection.

*The rated and max force on the FT series actuators are those forces derived from using typical servo motors of similar frame size to the actuator, at their rated continuous and peak torques. In many cases FT actuators can be configured with input sufficient to exceed these forces. Contact your local sales representative for further details.

Standard Inline Coupling Maximum Torque Ratings and Inertia

FT60	Torque Rating	Inertia
	885 lbf-in (100 N-m)	0.000330 kg-m ² (0.002921 lbf-in s ²)

Shown below are pulley inertias reflected at motor including typical pulleys, belt and standard bushings. Because of differences in belt and pulley selection due to particular motor choices, please contact your local sales representative if these values are critical to your application.

FT60 Reflective Inertias

	6 mm Lead	12 mm Lead	30 mm Lead	
NMT Unit - J (0)	0.0078464	0.0078709	0.0080424	kg-m ² (at input shaft)
NMT Unit - J (Stroke)	0.0002539	0.0002547	0.0002600	kg-m ² /inch of stroke
Inline w/ Coupler - J (0)	0.0081764	0.0082009	0.0083724	kg-m ² (at motor shaft)
Inline w/ Coupler - J (Stroke)	0.0002539	0.0002547	0.0002600	
Parallel 1:1 - J (0)	0.0129357	0.0146113	0.0312682	kg-m ² /inch of stroke
Parallel 1:1 - J (Stroke)	0.0002539	0.0002547	0.0002600	
Parallel 2:1 - J (0)	0.0049158	0.0057202	0.0214777	
Parallel 2:1 - J (Stroke)	0.0000635	0.0000637	0.0000650	

*Pulleys for parallel mount match actuator max performance ratings

DEFINITIONS:

Max Linear Speed: The linear speed achieved by the actuator at a screw speed equal to the max rotational speed value.

Max Force: Values are derived from the design capacity of the FT actuator and should not be exceeded or relied upon for continuous operation.

Dynamic Load Rating: A design constant used in calculating the estimated travel life of the roller screw. The dynamic mean load is the mean load at which the device will perform one million revolutions.

Torque at Rated Force: The torque required at the screw to produce the force rating.

Screw Inertia: The rotary inertia of the planetary roller screw in the actuator.

Max. Rot. Speed: The maximum allowable rotational screw speed determined by the screw length or the rotational speed limit of the roller screw nut.

FT80 Series Performance Specifications

Model No.	Nominal Frame Size in (mm)	Stroke in (mm)	Screw Lead in (mm)	Max Force lbf (kN)	Linear Speed at Max Rated RPM in/sec (mm/sec)	Dynamic Load Rating (Std capacity screw) lbf (kN)	Dynamic Load Rating (High capacity screw) lbf (kN)	Life at Max Force (Std capacity screw) 10 ⁶ in (Km)	Life at Max Force (High capacity screw) 10 ⁶ in (Km)	Max Input Torque lbf-in (Nm)	Max Rated Input rpm	Weight Base lb (kg)
FT80-1206	8.0 (203)	12 (305)	0.236 (6)	40,000 (177.9)	6.9 (175)	80,700 (359)	94,330 (419.6)	1.94 (49.3)	3.1 (78.7)	1,880 (212)	1750	190 (86)
FT80-1212			0.472 (12)		13.8 (351)	70,200 (312.2)	84,079 (374)	2.55 (64.9)	4.4 (111.4)	3,760 (425)		
FT80-1230			1.181 (30)		34.4 (875)	64,700 (287.8)	95,971 (426.9)	5.00 (127)	16.3 (414.3)	9,399 (1,062)		
FT80-2406	8.0 (203)	24 (610)	0.236 (6)	40,000 (177.9)	6.9 (175)	80,700 (359)	94,330 (419.6)	1.94 (49.3)	3.1 (78.7)	1,880 (212)	1750	265 (120)
FT80-2412			0.472 (12)		13.8 (351)	70,200 (312.2)	84,079 (374)	2.55 (64.9)	4.4 (111.4)	3,760 (425)		
FT80-2430			1.181 (30)		34.4 (875)	64,700 (287.8)	95,971 (426.9)	5.00 (127)	16.3 (414.3)	9,399 (1,062)		
FT80-3606	8.0 (203)	36 (914)	0.236 (6)	40,000 (177.9)	6.9 (175)	80,700 (359)	94,330 (419.6)	1.94 (49.3)	3.1 (78.7)	1,880 (212)	1750	340 (153)
FT80-3612			0.472 (12)		13.8 (351)	70,200 (312.2)	84,079 (374)	2.55 (64.9)	4.4 (111.4)	3,760 (425)		
FT80-3630			1.181 (30)		34.4 (875)	64,700 (287.8)	95,971 (426.9)	5.00 (127)	16.3 (414.3)	9,399 (1,062)		
FT80-4806	8.0 (203)	48 (1219)	0.236 (6)	40,000 (177.9)	6.9 (175)	80,700 (359)	94,330 (419.6)	1.94 (49.3)	3.1 (78.7)	1,880 (212)	1750	415 (187)
FT80-4812			0.472 (12)		13.8 (351)	70,200 (312.2)	84,079 (374)	2.55 (64.9)	4.4 (111.4)	3,760 (425)		
FT80-4830			1.181 (30)		34.4 (875)	64,700 (287.8)	95,971 (426.9)	5.00 (127)	16.3 (414.3)	9,399 (1,062)		

Intermediate and custom stroke lengths are also available. Intermediate leads may also be available. Belt and pulley inertia varies with ratio and motor selection. Please contact your local sales representative. See page 64 for definitions of terms.

* The rated and max force on the FT series actuators are those forces derived from using typical servo motors of similar frame size to the actuator, at their rated continuous and peak torques. In many cases FT actuators can be configured with input torque sufficient to exceed these forces. Contact your local sales representative for further details.

Standard Inline Coupling Maximum Torque Ratings and Inertia

FT80	Torque Rating	Inertia
	1770 lbf-in (200 N-m)	0.0001210 kg-m ² (0.010709 lbf-in s ²)

Shown below are pulley inertias reflected at motor including typical pulleys, belt and standard bushings. Because of differences in belt and pulley selection due to particular motor choices, please contact your local sales representative if these values are critical to your application.

FT80 Reflective Inertias

	6 mm Lead	12 mm Lead	30 mm Lead	
NMT Unit - J (0)	0.0302504	0.0303275	0.0308673	kg-m ² (at input shaft)
NMT Unit - J (Stroke)	0.0008022	0.0008035	0.0008124	kg-m ² /inch of stroke
Inline w/ Coupler - J (0)	0.0314604	0.0315375	0.0320773	kg-m ² (at motor shaft)
Inline w/ Coupler - J (Stroke)	0.0008022	0.0008035	0.0008124	
Parallel 1:1 - J (0)	0.0721056	0.0535533	0.1342578	
Parallel 1:1 - J (Stroke)	0.0008022	0.0008035	0.0008124	
Parallel 2:1 - J (0)	0.0198765	0.0270490	0.0753395	kg-m ² /inch of stroke
Parallel 2:1 - J (Stroke)	0.0002006	0.0002009	0.0002031	

*Pulleys for parallel mount match actuator max performance ratings

FT Series Mechanical Specifications

Model No.	FT35, FT60, FT80
Roller Screw Backlash <i>in (mm)</i>	0.0004 - 0.001 (0.01 - 0.03)
System Backlash* <i>in (mm)</i>	0.002 (0.06)
Standard Lead Accuracy** <i>in/ft (mm/mm)</i>	0.001 (.025/300)
Dynamic Torque Values <i>lbf in/krpm (nm/krpm)</i>	FT35: 6.0 (0.68) FT60: 11.0 (1.24) FT80: 20.0 (2.26)
Friction Torque Values <i>lbf in (nm)</i>	FT35: 7.0 (0.79) FT60: 14.0 (1.58) FT80: 35.0 (3.95)
Maximum Radial Load	See chart p 62
Environmental Rating (Base Unit Only)***	IP65S Standard
Case: Standard Optional	Epoxy-coated aluminum Food Grade Coating

* System backlash will be different with various types of motor mounting arrangements and couplings. Please discuss your particular configuration with your local sales representative.

** Optional lead accuracy – from 0.0002 in/ft (6 μm/300 mm) to 0.002 in/ft (200 μm/10000 mm) – are also available.

*** For IP65S scaling of unit with motor mounted, Please contact your local sales representative.

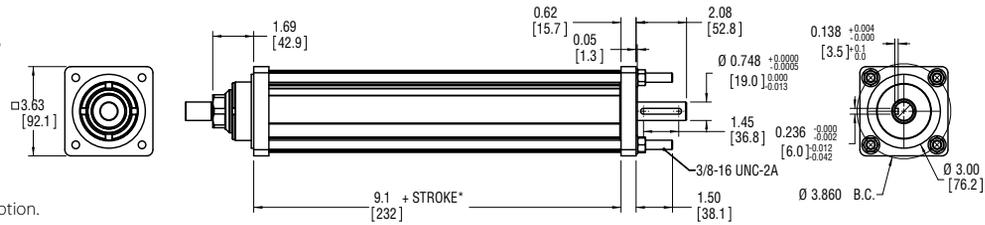
FT35 Series Linear Actuators

Base Unit

All dimensions shown in inches with millimeter equivalent in brackets.

See rod ends for rod end thread details.

*Add 20mm if choosing high capacity option.



Clevis Mount Unit

Parallel motor mount shown.

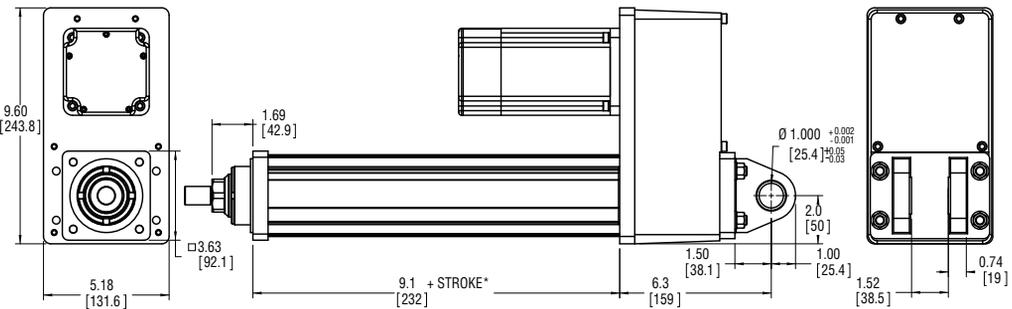
All dimensions shown in inches with millimeter equivalent in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.

*Add 20mm if choosing high capacity option.

*If "G" metric clevis option, Ø 27 mm + 0.00 / - 0.06



Front Flange Unit

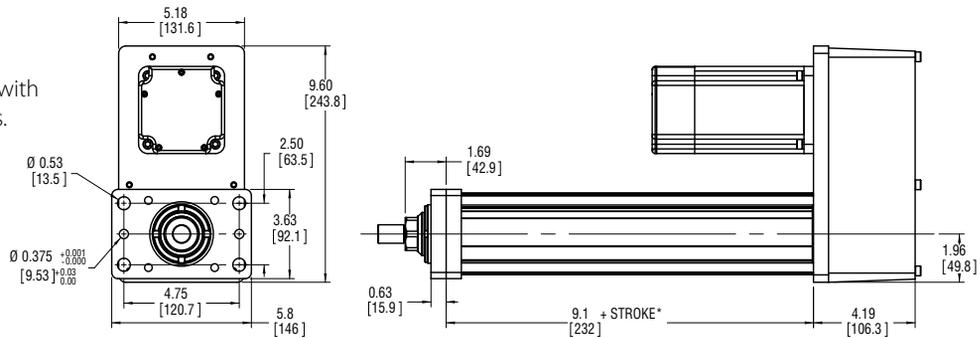
Parallel motor mount shown.

All dimensions shown in inches with millimeter equivalent in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.

*Add 20mm if choosing high capacity option.



Rear Flange Unit

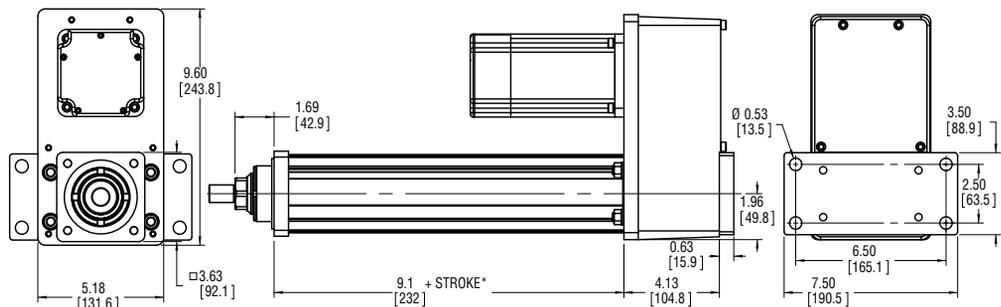
Parallel motor mount shown.

All dimensions shown in inches with millimeter equivalent in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.

*Add 20mm if choosing high capacity option.



Drawings subject to change. Consult Exlar for certified drawings.

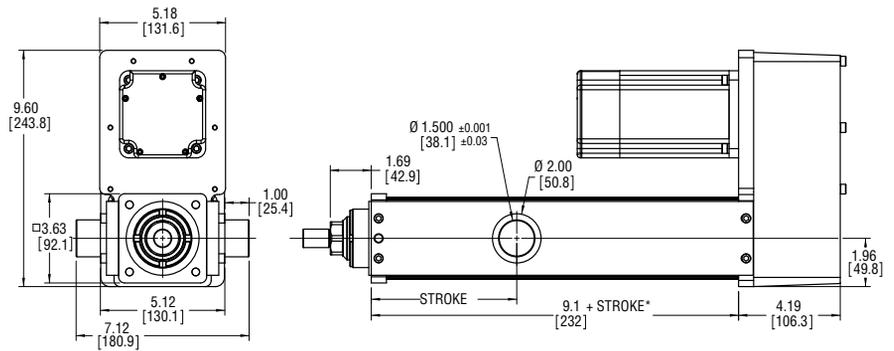
Trunnion Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



*Add 20mm if choosing high capacity option.

** If "Q" metric side trunnion option, Ø 35 mm h7

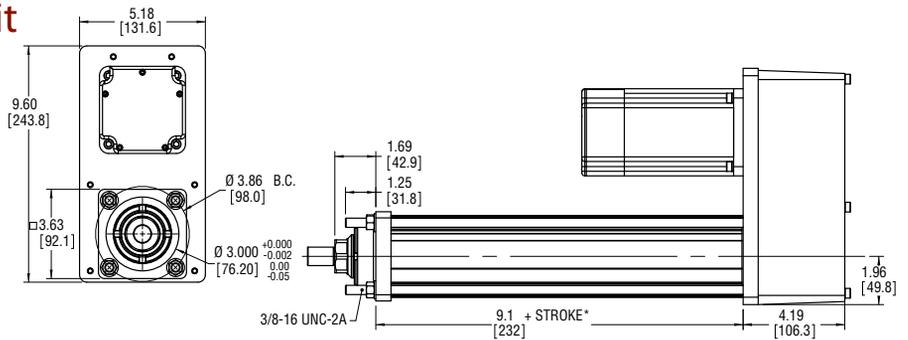
Extended Tie Rod Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



*Add 20mm if choosing high capacity option.

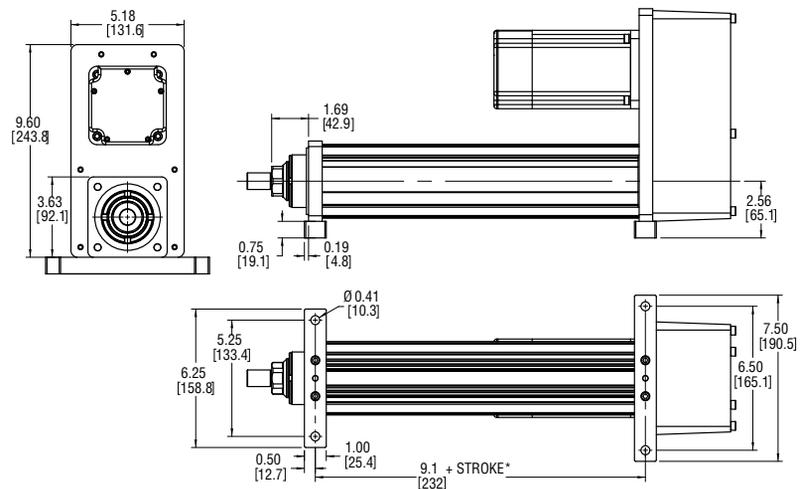
Side Lug Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



*Add 20mm if choosing high capacity option.

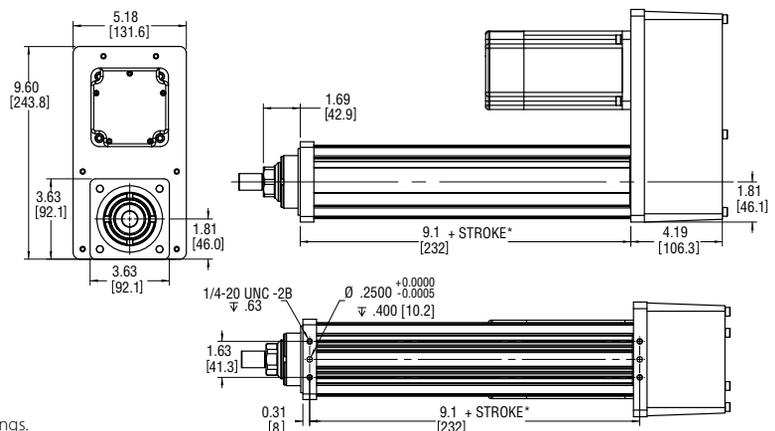
Side Mount Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



*Add 20mm if choosing high capacity option.

* If "J" or "K" metric side mount options, M6 x 1.0 ⚡ 9 mm with Ø 6 mm M7 ⚡ 9 mm Dowel Hole

Drawings subject to change. Consult Exlar for certified drawings.

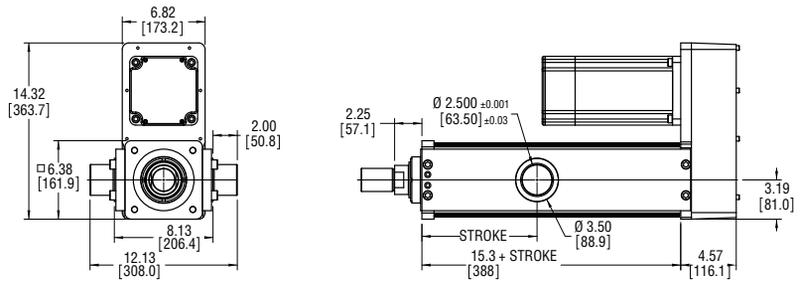
Trunnion Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



* If "Q" metric side trunnion option, $\varnothing 60$ mm h9

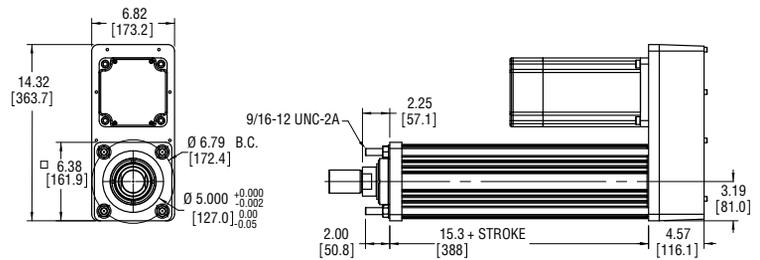
Extended Tie Rod Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



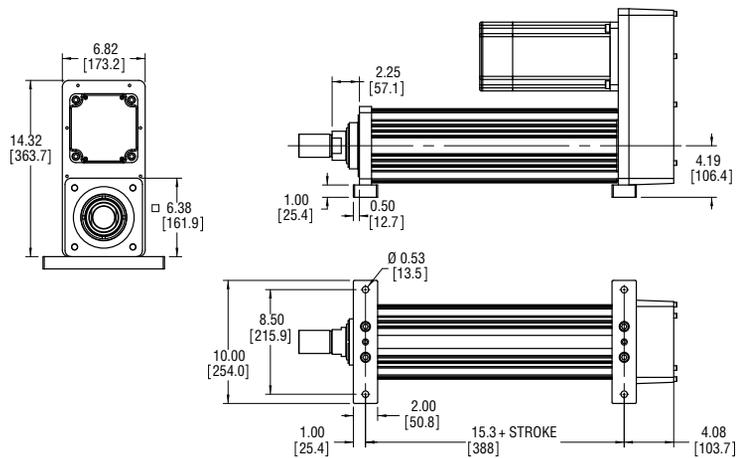
Side Lug Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



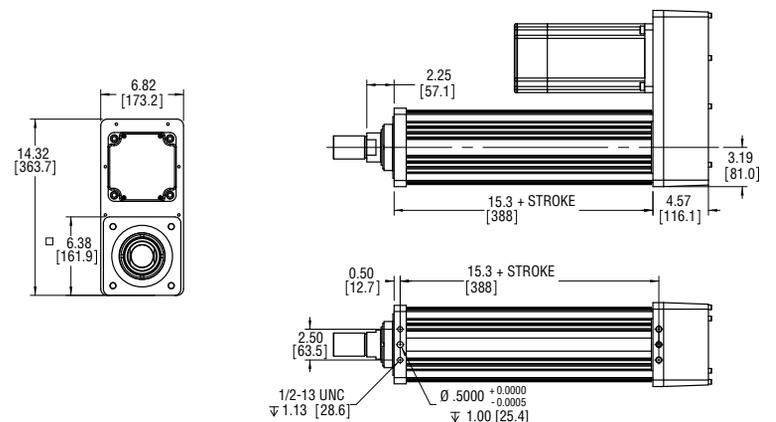
Side Mount Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



* If "J" or "K" metric side mount options, M12 x 1.75 ∇ 19 mm with $\varnothing 12$ mm M7 ∇ 12 mm Dowel Hole

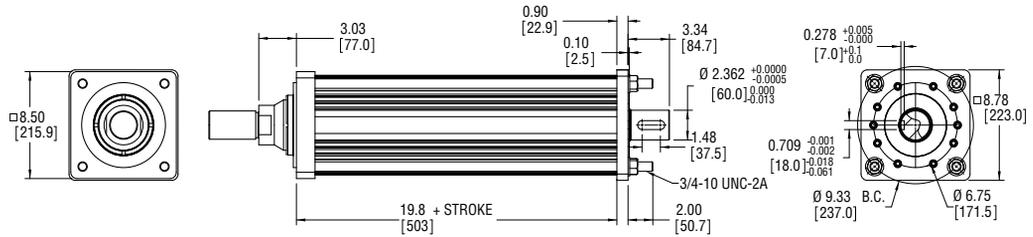
Drawings subject to change. Consult Exlar for certified drawings.

FT80 Series Linear Actuators

Base Unit

All dimensions shown in inches with millimeter equivalent in brackets.

See rod ends for rod end thread details.



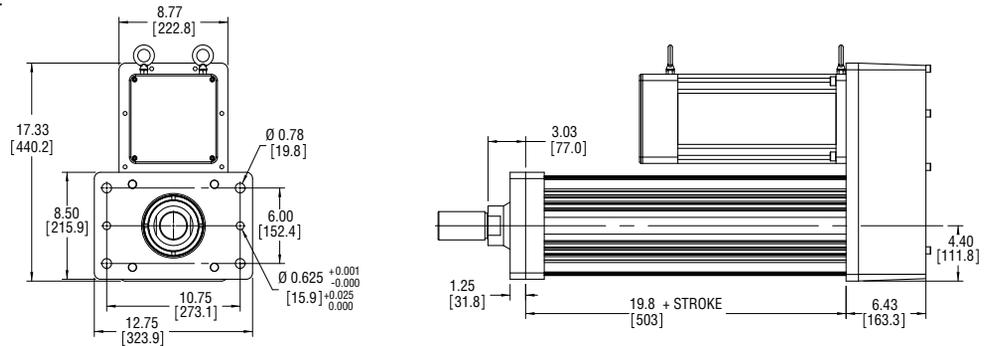
Front Flange Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeter equivalent in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



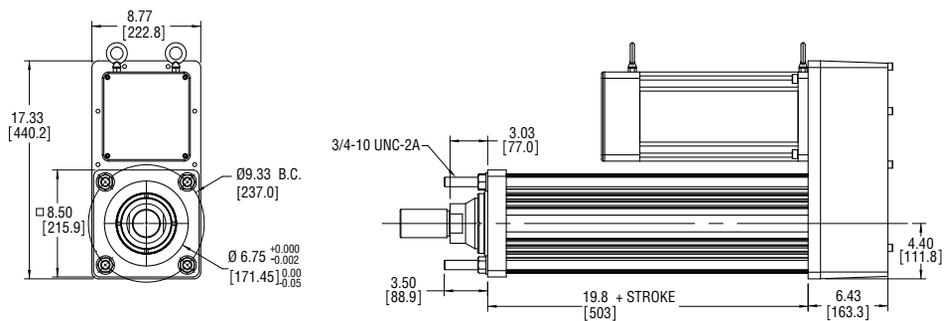
Extended Tie Rod Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeter equivalent in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



Drawings subject to change. Consult Exlar for certified drawings.

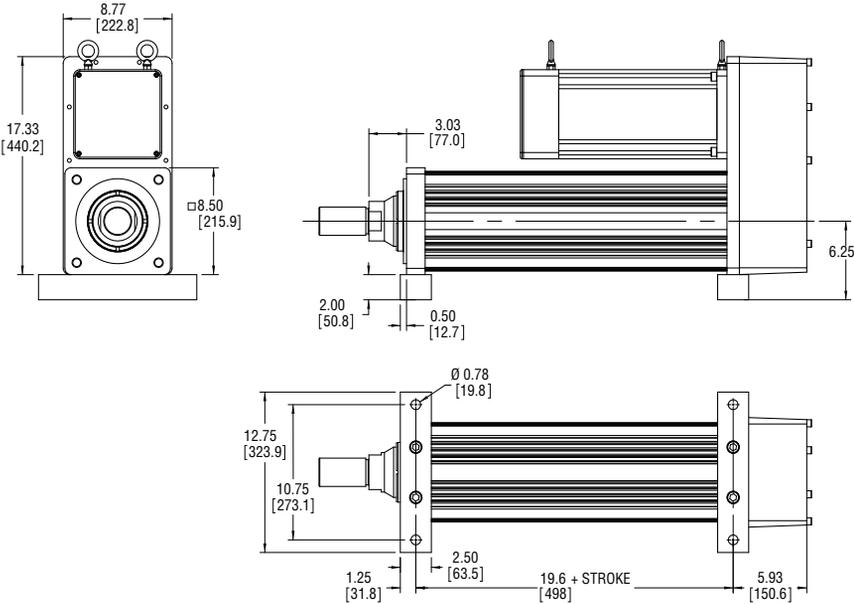
Side Lug Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



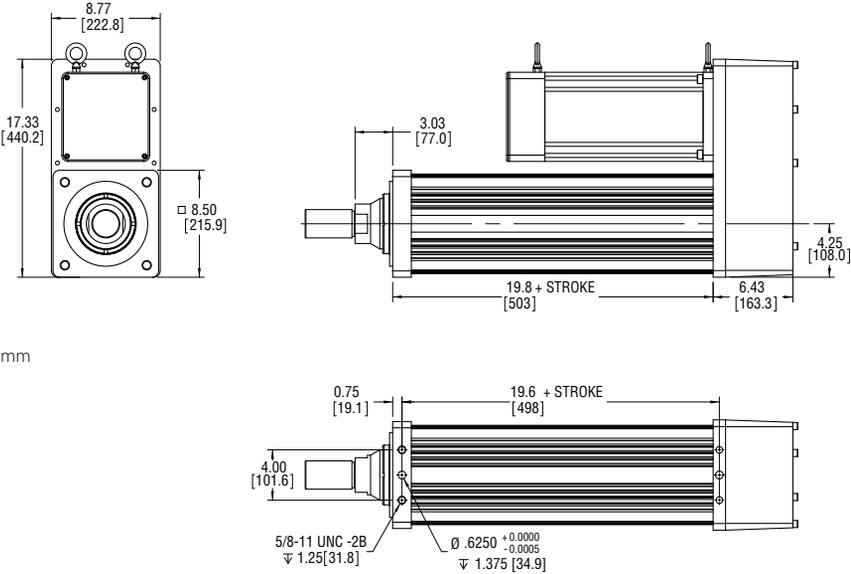
Side Mount Unit

Parallel motor mount shown.

All dimensions shown in inches with millimeters equivalents in brackets.

See rod ends for rod end thread details.

Motor plate and cover dimensions are subject to change depending on the motor and ratio selection.



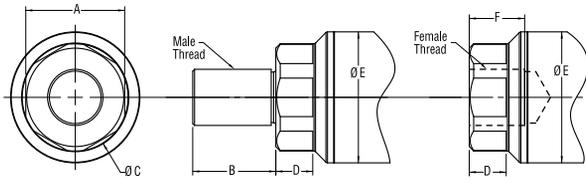
* If "J" or "K" metric side mount options, M16 x 2.0 ∇ 16 mm with \varnothing 12 mm M7 ∇ 12 mm Dowel Hole

NOTE: For Clevis, Trunnion or Rear Flange, Consult Exlar

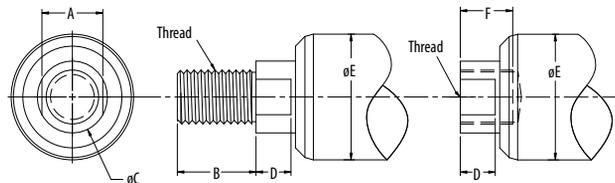
Drawings subject to change. Consult Exlar for certified drawings.

FT Series Linear Actuators

Rod Ends



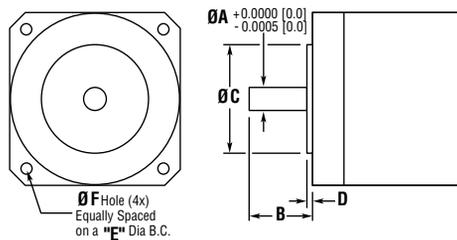
	A	B	ØC	D	ØE	F	Male U.S.	Male Metric	Female U.S.	Female Metric
	in (mm)	in (mm)	in (mm)	in (mm)	in (mm)	in (mm)				
FT35	1.34 (34)	1.125 (28.6)	1.434 (36.4)	0.50 (12.7)	1.750 (44.5)	0.750 (19.1)	3/4-16 UNF-2A	M16x1.5 6g	3/4-16 UNF-2B	M16x1.5 6h



	A	B	ØC	D	ØE	F	Male U.S.	Male Metric	Female U.S.	Female Metric
	in (mm)	in (mm)	in (mm)	in (mm)	in (mm)	in (mm)				
FT60	2.00 (50.8)	2.750 (69.9)	2.360 (59.9)	0.750 (19.1)	3.000 (76.2)	2.000 (50.8)	1 7/8-12 UN-2A	M42x4.5 6g	1 7/8-12 UN-2B	M42x4.5 6h
FT80	2.75 (69.9)	4.019 (102.1)	3.143 (79.8)	1.000 (25.4)	4.000 (101.6)	2.250 (57.2)	2 1/2-12 UN-2A	M56x5.5 6g	2 1/2-12 UN-2B	M56x5.5 6h

NEMA Standard Motor Dimensions

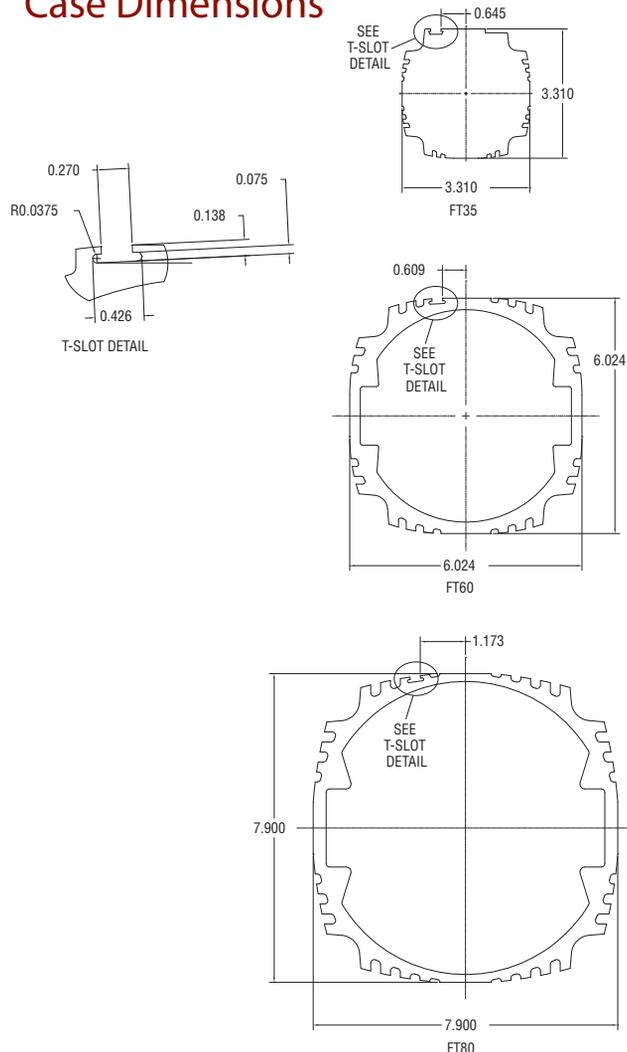
The FT Series actuators offer the selection for motor mounting provisions to be the various NEMA motor sizes. Because there are variations from brand to brand of motor as to what is called NEMA dimensions, we publish this table of NEMA dimensions that we use as the standards for the product line. If the motor that you choose differs from these dimensions, it would not be called out by the N23, N34, N42, N56 call outs but rather by the A## alpha numeric callout for specific motors.



Dimension (in)	NEMA 23	NEMA 34	NEMA 42	NEMA 56
"A" Motor Shaft Diameter	0.25	0.5	0.75	0.625
"B" Motor Shaft Length	0.81	1.19	2.19	2.0625
"C" Motor Pilot Diameter	1.5	2.875	2.186	4.5
"D" Pilot Depth	0.05	0.0625	0.0625	0.1 - 0.16
"E" Mounting Bolt Circle	2.625	3.875	4.95	5.875
"F" Mounting Bolt Hole Dia.	0.205	0.223	0.328	3/8-16 UNC tap

Drawings subject to change. Consult Exlar for certified drawings.

Case Dimensions



GGG = Motor Mount Provisions ^{3,4}

A## = Alpha numeric motor call out – Contact your local sales representative. Motor not included.

NMT = No motor mount – keyed shaft on base unit only

N23 = Nema 23 standard dimension

N34 = Nema 34 standard dimension

N42 = Nema 42 standard dimension

N56 = Nema 56 standard demension

M60 = Exlar 60 mm SLM. Motor not included.

M90 = Exlar 90 mm SLM. Motor not included.

M11 = Exlar 115 mm SLM and ER. Motor not included.

M14 = Exlar 142 mm SLM. Motor not included.

M18 = Exlar 180 mm SLM. Motor not included.

G60 = Exlar 60 mm SLG. Motor not included.

G90 = Exlar 90 mm SLG. Motor not included.

G11 = Exlar 115 mm SLG and ER. Motor not included.

AB3, 4, 6, 8 = Allen Bradley Ultra 3, 4, 6 and 8 inch motors

BD3, 4, 6, 8 = Baldor 3, 4, 6 & 8 inch motors

CM3, 4, 6, 8 = Parker (Custom Servo Motors) Metric 3, 4, 6 & 8 inch motors

EE3, 4 = Emerson EMC Imperial 3 & 4 inch

EM3, 4, 6, 8 = Emerson EMC Metric 3, 4, 6 & 8 inch

FA 4, 6, 8 = Fanuc 4, 6 & 8 inch motors

IN3, 4, 6, 8 = Bosch-Rexroth (Indramat) 3, 4, 6 and 8 inch motors

KM2, 4, 6, 8 = Kollmorgen B & M 20, 40, 60 and 80 Series

MT3, 4, 6, 8 = Mitsubishi 3, 4, 6 & 8 inch motors

PS3, 4, 6, 8 = Pacific Scientific PMA/PMB Series

PC2, 3, 4, 6 = Parker Compumotor Apex 2.7, 3.6, 4.5 and 5.6 inch

SM2 = Siemens 2 inch motor

SM3 = Siemens 3 inch motor

YS3, 4, 6, 8 = Yaskawa 3, 4, 6 and 8 inch motors

MXX = Unlisted or special motor mounting provisions

AA = FT Frame Size

35 = 3.5 inch (90 mm)

60 = 6.0 inch (150 mm)

80 = 8.0 inch (200 mm)

BB = Stroke Length

06 = 6 inch (152 mm) FT35

12 = 12 inch (305 mm) FT35, 60, 80

18 = 18 inch (457 mm) FT35

24 = 24 inch (610 mm) FT35, 60, 80

36 = 36 inch (914 mm) FT35, 60, 80

48 = 48 inch (1219 mm) FT35, 60, 80

CC = Screw Lead

05 = 0.2 inch, FT35

06 = 0.23 inch, FT60, 80

10 = 0.39 inch, FT35

12 = 0.47 inch, FT60, 80

20 = 0.79 inch, FT35

30 = 1.18 inch, FT60, 80

D = Mounting Style¹

L = Side lugs

B = Front/rear flange (5)

C = Rear clevis (5)

F = Front flange

R = Rear flange (5)

S = Side mount

D = Double side mount

T = Side trunnion mount (5)

E = Extended tie rods

J = Metric side mount

K = Metric double side mount

Q = Metric side trunnion

M = Metric extended tie rods

G = Metric rear clevis (5)

X = Special (please specify)

E = Motor Mounting Configurations

N = None

I = Inline direct drive (includes Exlar standard coupling)

P = Parallel, 1:1 belt reduction

Q = Parallel, 2:1 belt reduction

X = Special

F = Rod End

M = Male, US std. thread

A = Male, metric thread

F = Female, US std. thread

B = Female, metric thread

W = Male, US std. thread SS, rod end only

R = Male metric thread SS, rod end only

V = Female, US std. thread SS, rod end only

L = Female, metric thread SS, rod end only

X = Special (please specify)

XX .. XX = Options

Housing Options

XH = Special housing options

HC = Type III hard coat anodized, class I²

XT = High capacity roller screw

SS = Stainless steel²

FG = Smooth white epoxy²

(IP65S sealing of unit with motor mounted requires “XH” option.)²

Special Follower

PF = Preloaded follower. The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead non-preloaded screw for the same application.

FX = Special follower

End Switches (adjustable position throughout stroke)

L1 = One adjustable switch, (10-30 VDC, PNP, N.C., 1m. 3 wire embedded cable)

L2 = Two adjustable switches, (10-30 VDC, PNP, N.C., 1m. 3 wire embedded cable)

L3 = Three adjustable switches, (10-30 VDC, PNP, N.C., 1m. 3 wire embedded cable)

Please provide a drawing of motor dimensions with all orders to insure proper mounting compatibility.

= Part No. Designator for Specials Optional 5 digit assigned part number to designate unique model numbers for specials.

Note:

1. Mounting face size, shaft length and other details of particular motors may require special adapters or provisions for mounting. Always discuss your motor selection with your local sales representative.
2. These housing options may also indicate the need for special material main rods, faceplate and motor mounting provisions. Internal anti-rotate is not available with stainless steel options. Please contact your local sales representative.
3. NEMA callout must meet specifications on page 72 or use alpha-numeric callout.
4. MAX Std. motor size FT35: 4 inch/115 mm, FT60 & 80: 8 inch/200 mm. For oversized motors, contact your local sales representative.
5. Not available with inline motor mount, contact your local sales representative.

Contact your local sales representative regarding all special actuator components.

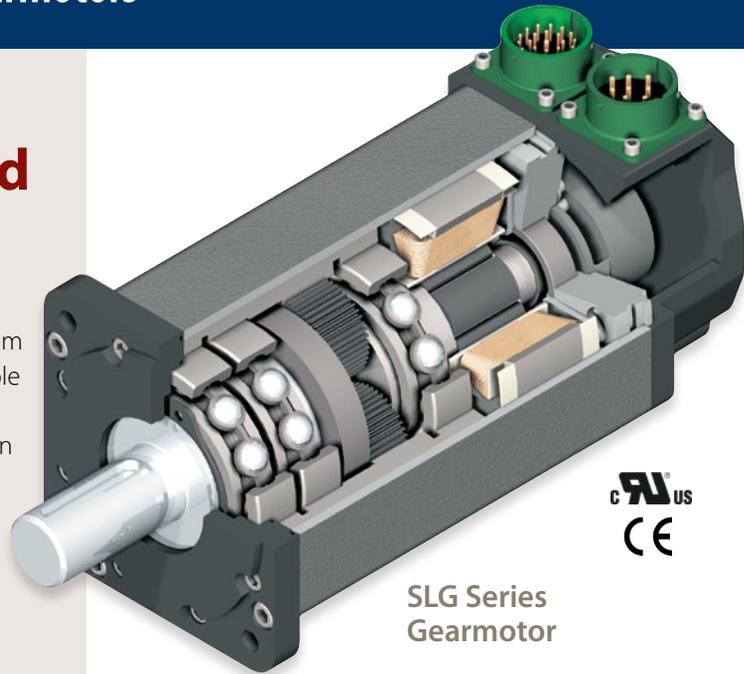
SLM Series Motors and SLG Series Integrated Gearmotors

Brushless servo motor and gearmotor technology from Exlar provides the highest torque-to-size ratio available in motion control today. Small size, outstanding performance specifications, quality and customization capabilities offer you the solution you need for your motion control application.

Very High Torque Density

Exlar's T-LAM technology produces an efficient and powerful motor in a very small package.

- **60 mm SLM060** offers continuous torque up to 15 lbf-in and base speed of 5000 rpm.
- **90 mm SLM090** offers continuous torque up to 56 lbf-in and base speed of 4000 rpm.
- **115 mm SLM115** offers continuous torque up to 176 lbf-in and base speed of 3000 rpm.
- **142 mm SLM142** offers continuous torque up to 237 lbf-in and base speed of 2400 rpm.
- **180 mm SLM180** offers continuous torque up to 612 lbf-in and base speed of 2400 rpm.



SLG Series Gearmotor



Standard Features	
SLM Motor	SLM Motor Standard Features
	UL recognized component IP65S sealing
	MS connectors embedded leads, or embedded leads with cable plugs
	Feedback configurations for nearly all servo amplifiers
	Anodized housings
	Class 180H insulation system
SLG Gearmotor	All features of SLM motor shown above plus...
	High side load bearing design
	Integrated armature and sun gear
	Higher stiffness than bolt-on gearhead and motor
	10 arc minute standard backlash, single stage; 13 arc minute standard backlash, dual stage
	Single and double reduction ratios: 4:1, 5:1, 10:1, 16:1, 20:1, 25:1, 40:1, 50:1, and 100:1

Unique T-LAM™ Stator Design Advantage

This innovative design offers several advantages over traditional motor winding for a more efficient and powerful motor.

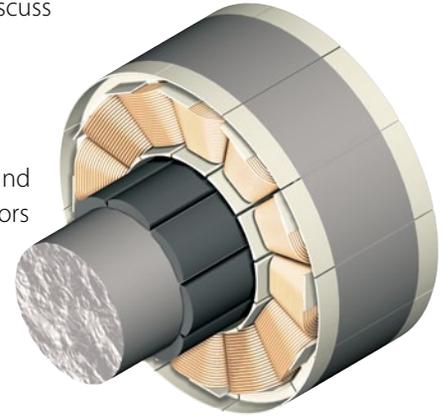
Built for durability, T-LAM segmented lamination stator technology consists of individual segments, each containing individual phase wiring for maximum motor performance. The robust insulation, high coercive strength magnets, and complete thermal potting all provide a more robust motor design – a design yielding a 35 to 70% torque increase in the same package size! T-LAM motor designs have Class 180-H insulation systems and UL recognition.

Customization to Suit Your Requirements

Exlar Corporation has capabilities allowing custom motors to be manufactured to meet your OEM requirements. Whatever your special requirements are... custom shafts, custom mountings, custom stators, custom housing materials... please contact Exlar or your local sales representative to discuss your needs.

Typical Applications

SLM Series Motors and SLG Series Gearmotors are perfectly suited for applications in any industry.



EXLAR SLM & SLG Series Motors applications include:

Semiconductor

Plastics Machinery

Tensioning

Web Feed

Fluid Handling

Stage Positioning

Medical Applications

Winding Machines

Glass Manufacturing

Food Processing

Conveyor Drives

Automotive Assembly

Parts Handling

Screw Drives

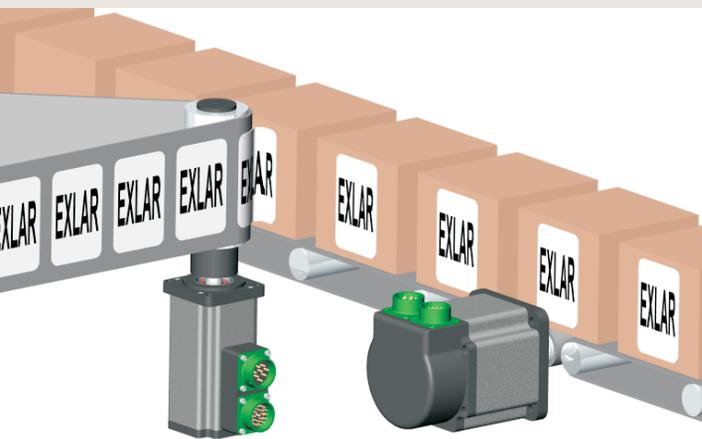
Labeling

Machine Tools

Simulation Robotics

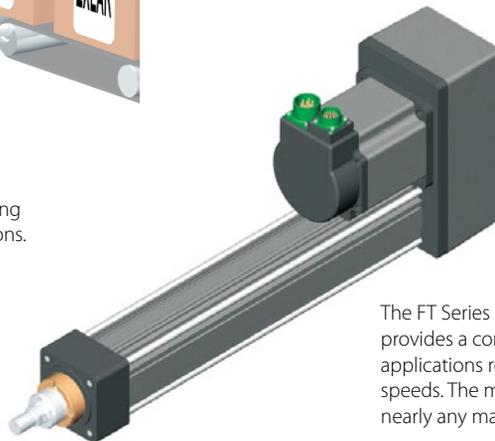
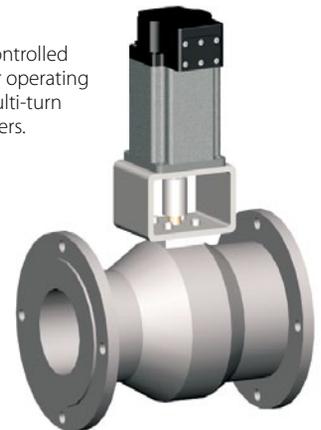
Packaging

SLM/SLG Series



Exlar's brushless motors are the highest performance with very compact size. This makes them perfect for high-speed labeling and demanding conveyor drive applications.

Exlar's closed-loop, servo-controlled rotary actuators are ideal for operating quarter-turn, full-turn, or multi-turn valves or shaft driven dampers.

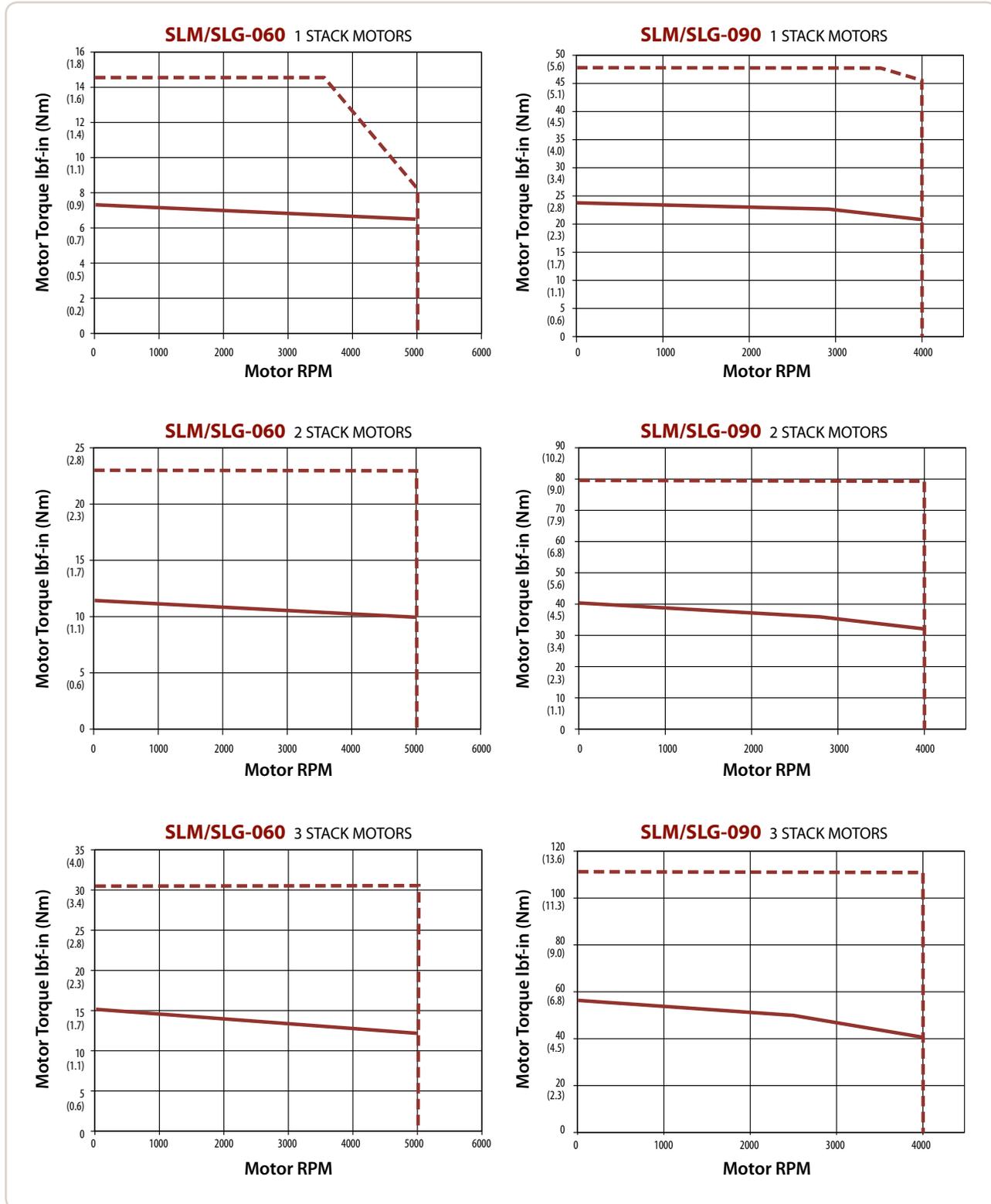


The FT Series combined with SLM/G Series motors provides a complete Exlar actuator solution for applications requiring heavy load capacity and high speeds. The motor can be configured to operate with nearly any manufacturer's servo amplifier.

SLM/SLG Speed/Torque Curves

These speed vs. torque curves represent approximate continuous torque ratings at indicated rpms. Different types of servo amplifiers will offer varying motor torque.

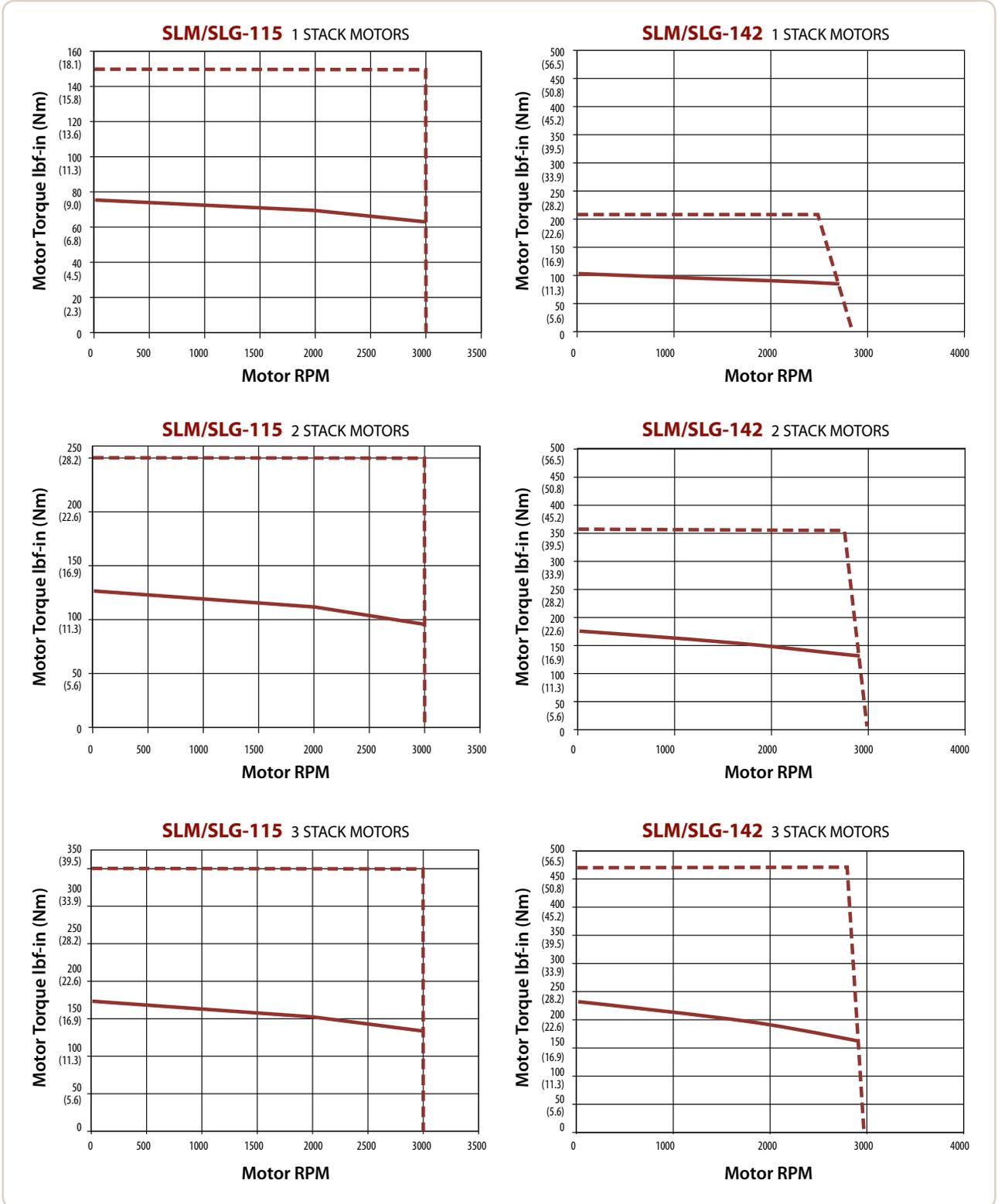
- - - Peak Torque
— Continuous Torque



Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4" on SLM/SLG060 and 10" x 10" x 3/8" on SLM/SLG090

SLM/SLG Speed/Torque Curves

- - - Peak Torque
— Continuous Torque



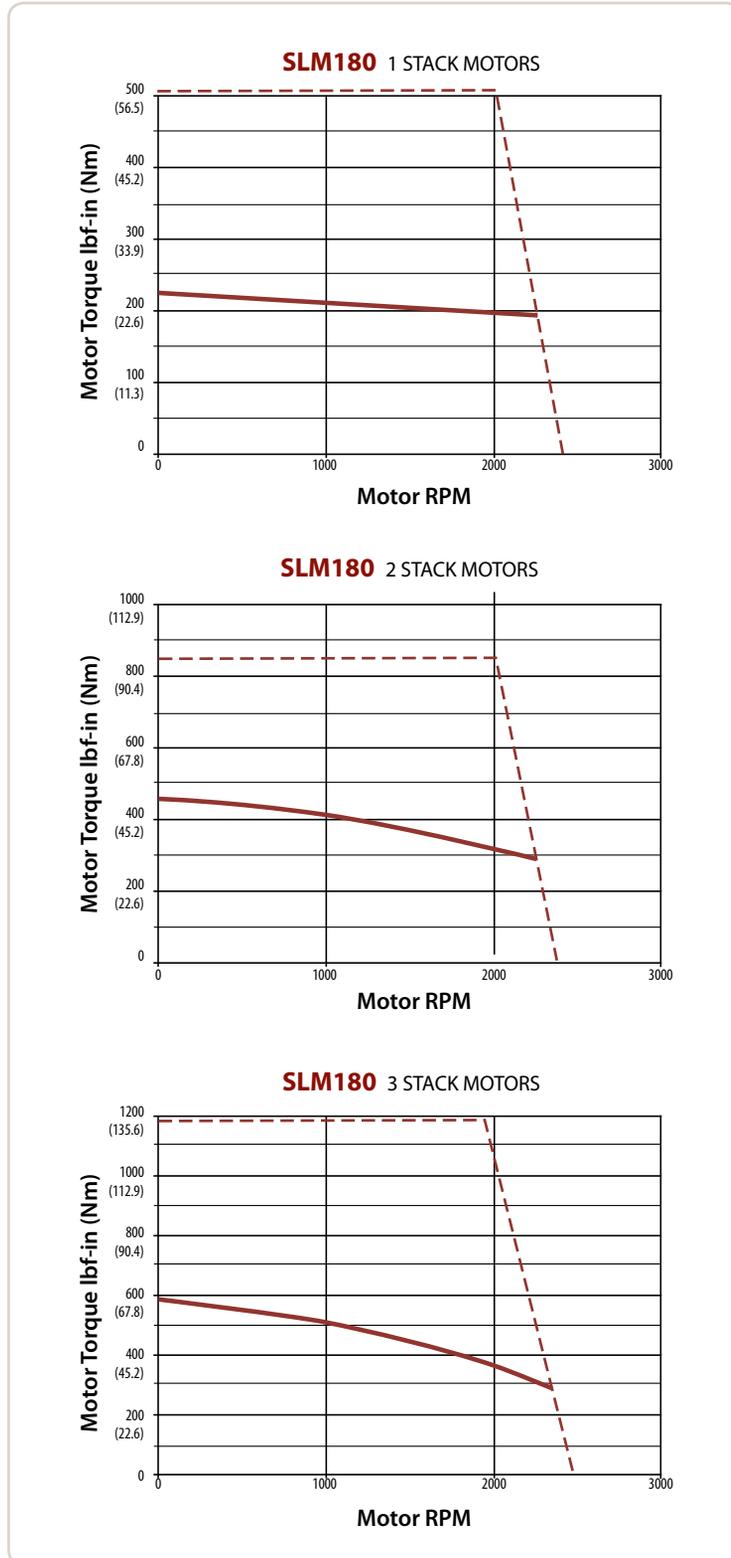
Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2" on SLM/SLG115 and 12" x 12" x 1/2" on SLM/SLG142

SLM/SLG Series

SLM Speed/Torque Curves

These speed vs. torque curves represent approximate continuous torque ratings at indicated rpms. Different types of servo amplifiers will offer varying motor torque.

- - - - - Peak Torque
- Continuous Torque



Test data derived using NEMA recommended aluminum heatsink 16" x 16" x 1"

SLM/SLG060 Electrical/Mechanical Specifications

SLM/G060 Stator Data		1 Stack Motor				2 Stack Motor				3 Stack Motor			
Sinusoidal Commutation Data		118	138	158	168	218	238	258	268	318	338	358	368
Continuous Motor Torque	lbf-in (Nm)	7.6 (0.86)	7.3 (0.83)	7.0 (0.79)	7.0 (0.79)	11.9 (1.34)	11.5 (1.30)	11.0 (1.25)	11.3 (1.28)	15.0 (1.70)	15.3 (1.73)	14.6 (1.65)	14.9 (1.69)
Peak Motor Torque	lbf-in (Nm)	15.2 (1.72)	14.7 (1.66)	14.0 (1.58)	14.0 (1.58)	23.8 (2.69)	23.0 (2.60)	22.1 (2.49)	22.6 (2.55)	30.0 (3.39)	30.6 (3.46)	29.2 (3.30)	29.9 (3.38)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	2.5 (0.28)	5.2 (0.6)	7.5 (0.9)	9.5 (1.1)	2.5 (0.3)	5.2 (0.6)	8.6 (1.0)	10.1 (1.1)	2.5 (0.3)	5.3 (0.6)	8.8 (1.0)	10.1 (1.1)
Continuous Current Rating	A	3.4	1.6	1.0	0.8	5.4	2.5	1.4	1.2	6.6	3.2	1.9	1.6
Peak Current Rating	A	6.9	3.1	2.0	1.6	10.8	4.9	2.9	2.5	13.2	6.5	3.7	3.3
O-PK SINUSOIDAL COMMUTATION DATA													
Continuous Motor Torque	lbf-in (Nm)	7.6 (0.86)	7.3 (0.83)	7.0 (0.79)	7.0 (0.79)	11.9 (1.34)	11.5 (1.30)	11.0 (1.25)	11.3 (1.28)	15.0 (1.70)	15.3 (1.73)	14.6 (1.65)	14.9 (1.69)
Peak Motor Torque	lbf-in (Nm)	15.2 (1.72)	14.7 (1.66)	14.0 (1.58)	14.0 (1.58)	23.8 (2.69)	23.0 (2.60)	22.1 (2.49)	22.6 (2.55)	30.0 (3.39)	30.6 (3.46)	29.2 (3.30)	29.9 (3.38)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	1.7 (0.20)	3.7 (0.4)	5.3 (0.6)	6.7 (0.8)	1.7 (0.2)	3.7 (0.4)	6.1 (0.7)	7.2 (0.8)	1.8 (0.2)	3.7 (0.4)	6.2 (0.7)	7.2 (0.8)
Continuous Current Rating	A	4.9	2.2	1.5	1.2	7.6	3.5	2.0	1.8	9.4	4.6	2.6	2.3
Peak Current Rating	A	9.7	4.5	2.9	2.3	15.2	7.0	4.1	3.5	18.7	9.2	5.3	4.7
MOTOR DATA													
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm Vpk/Krpm	16.9 23.9	35.5 50.2	51.5 72.8	64.8 91.7	16.9 23.9	35.5 50.2	58.6 82.9	69.3 98.0	17.3 24.5	36.0 50.9	59.9 84.8	69.3 98.0
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	2.6	12.52	28.82	45.79	1.11	5.26	15.51	20.69	0.76	3.14	9.57	12.22
Inductance (L-L)(+/- 15%)	mH	4.6	21.4	47.9	68.3	2.5	10.2	28.3	39.5	1.7	7.4	18.5	27.4
SLM Armature Inertia (+/- 5%)	lbf-in-sec ² (Kg-cm ²)	0.000237 (0.268)				0.000413 (0.466)				0.000589 (0.665)			
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00012 (0.135)				0.000120 (0.135)				0.000120 (0.135)			
Brake Current @ 24VDC	A	.33				.33				.33			
Brake Holding Torque	lbf-in (Nm)	19 (2.2)				19 (2.2)				19 (2.2)			
Brake Engage/Disengage Time	ms	14/28				14/28				14/28			
Mechanical Time Constant (tm)	ms	2.20	2.38	2.60	2.61	1.62	1.74	1.89	1.80	1.50	1.45	1.59	1.52
Electrical Time Constant (te)	ms	1.76	1.71	1.66	1.49	2.24	1.95	1.82	1.91	2.27	2.36	1.93	2.24
Friction Torque	lbf-in (Nm)	0.27 (0.031)				0.34 (0.038)				0.38 (0.043)			
Voltage Rating	Vrms	115	230	400	460	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	5000											
Insulation Class		180 (H)											
Insulation System Volt Rating	Vrms	460											
Environmental Rating		IP65S											

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

SLG060 Gearmotor Data

	1 Stack Motor			2 Stack Motor			3 Stack Motor		
SLG Armature Inertia* lbf-in-sec ² (Kg-cm ²)	0.000226 (0.255)			0.000401 (0.453)			0.000576 (0.651)		
GEARING REFLECTED INERTIA	SINGLE REDUCTION						DOUBLE REDUCTION		
	Gear Stages	lbf-in-sec ²	(Kg-cm ²)	Gear Stages	lbf-in-sec ²	(Kg-cm ²)			
	4:1	0.0000132	(0.0149)	16:1	0.0000121	(0.0137)			
	5:1	0.0000087	(0.00984)	20:1, 25:1	0.0000080	(0.00906)			
	10:1	0.0000023	(0.00261)	40:1, 50:1, 100:1	0.0000021	(0.00242)			
Backlash at 1% rated torque:	10 Arc minutes Efficiency: Single reduction 91%						13 Arc minutes Double Reduction: 86%		

* Add armature inertia to gearing inertia for total SLG system inertia
Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4"

SLM/SLG090 Electrical/Mechanical Specifications

SLM/SLG090 Stator Data		1 Stack Motor				2 Stack Motor				3 Stack Motor		
Sinusoidal Commutation Data		118	138	158	168	218	238	258	268	338	358	368
Continuous Motor Torque	lbf-in (Nm)	23.8 (2.68)	24.0 (2.71)	23.7 (2.67)	24.7 (2.79)	39.6 (4.47)	40.0 (4.52)	39.5 (4.46)	39.9 (4.51)	55.7 (6.30)	55.4 (6.26)	55.7 (6.30)
Peak Motor Torque	lbf-in (Nm)	47.5 (5.37)	48.0 (5.42)	47.3 (5.35)	49.4 (5.58)	79.1 (8.94)	80.0 (9.04)	79.0 (8.93)	79.9 (9.02)	111.5 (12.59)	110.9 (12.52)	111.5 (12.59)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	3.2 (0.37)	6.6 (0.7)	11.6 (1.3)	13.2 (1.5)	3.2 (0.4)	6.6 (0.7)	11.6 (1.3)	13.2 (1.5)	6.6 (0.7)	11.6 (1.3)	13.1 (1.5)
Continuous Current Rating	A	8.2	4.0	2.3	2.1	13.6	6.8	3.8	3.4	9.5	5.3	4.8
Peak Current Rating	A	16.4	8.1	4.6	4.2	27.3	13.5	7.6	6.7	19.0	10.7	9.5
O-PK SINUSOIDAL COMMUTATION DATA												
Continuous Motor Torque	lbf-in (Nm)	23.8 (2.68)	24.0 (2.71)	23.7 (2.67)	24.7 (2.79)	39.6 (4.47)	40.0 (4.52)	39.5 (4.46)	39.9 (4.51)	55.7 (6.30)	55.4 (6.26)	55.7 (6.30)
Peak Motor Torque	lbf-in (Nm)	47.5 (5.37)	48.0 (5.42)	47.3 (5.35)	49.4 (5.58)	79.1 (8.94)	80.0 (9.04)	79.0 (8.93)	79.9 (9.02)	111.5 (12.59)	110.9 (12.52)	111.5 (12.59)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	2.3 (0.26)	4.7 (0.5)	8.2 (0.9)	9.4 (1.1)	2.3 (0.3)	4.7 (0.5)	8.2 (0.9)	9.4 (1.1)	4.6 (0.5)	8.2 (0.9)	9.3 (1.0)
Continuous Current Rating	A	11.6	5.7	3.2	2.9	19.3	9.5	5.4	4.8	13.4	7.5	6.7
Peak Current Rating	A	23.2	11.4	6.5	5.9	38.6	19.1	10.8	9.5	26.9	15.1	13.4
MOTOR DATA												
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm (Vpk/Krpm)	22.1	45.2	78.9	90.4	22.1	45.2	78.9	90.4	44.7	79.4	89.5
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	0.75	3.06	9.57	11.55	0.30	1.21	3.78	4.86	0.69	2.19	2.75
Inductance (L-L)(+/- 15%)	mH	6.1	25.6	78.0	88.6	2.9	10.5	37.2	43.1	6.6	24.7	31.4
SLM Armature Inertia (+/- 5%)	lbf-in-sec ² (Kg-cm ²)	0.00054 (0.609)				0.00097 (1.09)				0.00140 (1.58)		
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00096 (1.08)				0.00096 (1.08)				0.00096 (1.08)		
Brake Current @ 24 VDC	A	.67				.67				.67		
Brake Holding Torque	lbf-in (Nm)	97 (11)				97 (11)				97 (11)		
Brake Engage/Disengage Time	ms	20/29				20/29				20/29		
Mechanical Time Constant (tm)	ms	0.83	0.82	0.84	0.77	0.59	0.58	0.59	0.58	0.48	0.49	0.48
Electrical Time Constant (te)	ms	8.21	7.31	8.14	7.67	9.88	8.66	9.85	8.88	9.57	11.30	11.43
Friction Torque	lbf-in (Nm)	0.68 (0.077)				0.85 (0.095)				1.06 (0.119)		
Voltage Rating	Vrms	115	230	400	460	115	230	400	460	230	400	460
Speed @ Bus Voltage	rpm	4000										
Insulation Class		180 (H)										
Insulation System Volt Rating	Vrms	460										
Environmental Rating		IP65S										

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

SLG090 Gearmotor Data

	1 Stack Motor			2 Stack Motor			3 Stack Motor		
SLG Armature Inertia* lbf-in-sec ² (Kg-cm ²)	0.00114 (1.29)			0.00157 (1.77)			0.00200 (2.26)		
GEARING REFLECTED INERTIA	SINGLE REDUCTION						DOUBLE REDUCTION		
	Gear Stages	lbf-in-sec ²	(Kg-cm ²)	Gear Stages	lbf-in-sec ²	(Kg-cm ²)			
	4:1	0.000154	(0.174)	16:1	0.000115	(0.130)			
	5:1	0.000100	(0.113)	20:1, 25:1	0.0000756	(0.0854)			
	10:1	0.0000265	(0.0300)	40:1, 50:1, 100:1	0.0000203	(0.0230)			
Backlash at 1% rated torque:	10 Arc minutes						13 Arc minutes		
	Efficiency: Single reduction 91%						Double Reduction: 86%		

* Add armature inertia to gearing inertia for total SLG system inertia
Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 3/8"

SLM/SLG115 Electrical/Mechanical Specifications

SLM/SLG115 Stator Data		1 Stack Motor				2 Stack Motor			3 Stack Motor		
Sinusoidal Commutation Data		118	138	158	168	238	258	268	338	358	368
Continuous Motor Torque	lbf-in (Nm)	74.1 (8.37)	74.1 (8.37)	74.3 (8.39)	74.1 (8.37)	123.6 (13.96)	121.4 (13.72)	123.8 (13.96)	172.3 (19.46)	168.9 (19.09)	176.9 (19.98)
Peak Motor Torque	lbf-in (Nm)	148.2 (16.74)	148.2 (16.74)	148.6 (16.79)	148.1 (16.74)	247.2 (27.93)	242.8 (27.43)	247.2 (27.93)	344.5 (38.93)	337.8 (38.17)	353.7 (39.96)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	4.3 (0.49)	8.7 (1.0)	15.7 (1.8)	17.3 (2.0)	8.7 (1.0)	15.8 (1.8)	17.3 (2.0)	8.5 (1.0)	15.8 (1.8)	17.5 (2.0)
Continuous Current Rating	A	19.1	9.5	5.3	4.8	15.9	8.6	8.0	22.7	11.9	11.3
Peak Current Rating	A	38.2	19.1	10.6	9.5	31.8	17.1	15.9	45.4	23.8	22.5
O-PK SINUSOIDAL COMMUTATION DATA											
Continuous Motor Torque	lbf-in (Nm)	74.1 (8.37)	74.1 (8.37)	74.3 (8.39)	74.1 (8.37)	123.6 (13.96)	121.4 (13.72)	123.6 (13.96)	172.3 (19.46)	168.9 (19.09)	176.9 (19.98)
Peak Motor Torque	lbf-in (Nm)	148.2 (16.74)	148.2 (16.74)	148.6 (16.79)	148.1 (16.74)	247.2 (27.93)	242.8 (27.43)	247.2 (27.93)	344.5 (38.93)	337.8 (38.17)	353.7 (39.96)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	3.1 (0.35)	6.1 (0.7)	11.1 (1.3)	12.3 (1.4)	6.1 (0.7)	11.2 (1.3)	12.3 (1.4)	6.0 (0.7)	11.2 (1.3)	12.4 (1.4)
Continuous Current Rating	A	27.0	13.5	7.5	6.7	22.5	12.1	11.3	32.1	16.9	15.9
Peak Current Rating	A	54.0	27.0	15.0	13.5	45.0	24.2	22.5	64.2	33.7	31.9
MOTOR DATA											
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm (Vpk/Krpm)	29.6	59.2	106.9	118.5	59.2	108.2	118.5	58.0	108.2	119.8
Pole Configuration		8	8	8	8	8	8	8	8	8	8
Resistance (L-L) (+/- 5% @ 25°C)	Ohms	0.20	0.80	2.60	3.21	0.34	1.17	1.35	0.20	0.72	0.81
Inductance (L-L) (+/- 15%)	mH	3.3	13.0	42.4	52.1	6.3	21.1	25.3	4.0	13.1	17.1
SLM Armature Inertia (+/- 5%)	lbf-in-sec ² (Kg-cm ²)	0.00344 (3.89)				0.00623 (7.036)			0.00901 (10.181)		
Brake Inertia	lbf-in-sec ² (Kg-cm ²)	0.00327 (3.70)				0.00327 (3.70)			0.00327 (3.70)		
Brake Current @ 24VDC	A	.75				.75			.75		
Brake Holding Torque	lbf-in (Nm)	195 (22)				195 (22)			195 (22)		
Brake Engage/Disengage Time	ms	25/50				25/50			25/50		
Mechanical Time Constant (tm)	ms	0.80	0.80	0.79	0.80	0.61	0.63	0.61	0.54	0.56	0.51
Electrical Time Constant (te)	ms	16.26	16.26	16.34	16.25	18.72	18.06	18.72	20.08	18.14	21.16
Friction Torque	lbf-in (Nm)	1.43 (0.16)				1.81 (0.204)			2.32 (0.262)		
Voltage Rating	Vrms	115	230	400	460	230	400	460	230	400	460
Speed @ Bus Voltage	rpm	3000									
Insulation Class		180 (H)									
Insulation System Volt Rating	Vrms	460									
Environmental Rating		IP65S									

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

SLG115 Gearmotor Data

	1 Stack Motor			2 Stack Motor			3 Stack Motor			
SLG Armature Inertia* lbf-in-sec ² (Kg-cm ²)	0.00538 (6.08)			0.00816 (9.22)			0.0109 (12.31)			
GEARING REFLECTED INERTIA	SINGLE REDUCTION						DOUBLE REDUCTION			
	Gear Stages	lbf-in-sec ²		(Kg-cm ²)		Gear Stages	lbf-in-sec ²		(Kg-cm ²)	
	4:1	0.000635		(0.717)		16:1	0.000513		(0.580)	
	5:1	0.000428		(0.484)		20:1, 25:1	0.000350		(0.396)	
	10:1	0.000111		(0.125)		40:1, 50:1, 100:1	0.0000911		(0.103)	
Backlash at 1% rated torque:	10 Arc minutes						13 Arc minutes			
	Efficiency: Single reduction 91%						Double Reduction: 86%			

* Add armature inertia to gearing inertia for total SLG system inertia
Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2"

SLM142 Electrical/Mechanical Specifications

SLM142 Stator Data		1 Stack Motor				2 Stack Motor			3 Stack Motor	
Sinusoidal Commutation Data		118	138	158	168	238	258	268	358	368
Continuous Motor Torque	lbf-in (Nm)	108.5 (12.25)	107.2 (12.12)	104.8 (11.84)	109.4 (12.36)	179.9 (20.32)	178.8 (20.20)	177.8 (20.09)	237.2 (26.80)	238.3 (26.93)
Peak Motor Torque	lbf-in (Nm)	216.9 (24.51)	214.5 (24.23)	209.5 (23.67)	218.8 (24.72)	359.8 (40.65)	357.6 (40.40)	355.7 (40.19)	474.4 (53.60)	476.7 (53.85)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	5.9 (0.67)	11.8 (1.3)	20.2 (2.3)	23.6 (2.7)	11.8 (1.3)	20.2 (2.3)	23.6 (2.7)	20.2 (2.3)	24.0 (2.7)
Continuous Current Rating	A	20.5	10.2	5.8	5.2	17.0	9.9	8.4	13.1	11.1
Peak Current Rating	A	41.1	20.3	11.6	10.4	34.1	19.8	16.8	26.2	22.2
0-PK SINUSOIDAL COMMUTATION DATA										
Continuous Motor Torque	lbf-in (Nm)	108.5 (12.25)	107.2 (12.12)	104.8 (11.84)	109.4 (12.36)	179.9 (20.32)	178.8 (20.20)	177.8 (20.09)	237.2 (26.80)	238.3 (26.93)
Peak Motor Torque	lbf-in (Nm)	216.9 (24.51)	214.5 (24.23)	209.5 (23.67)	218.8 (24.72)	359.8 (40.65)	357.6 (40.40)	355.7 (40.19)	474.4 (53.60)	476.7 (53.85)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	4.2 (0.47)	8.3 (0.9)	14.3 (1.6)	16.7 (1.9)	8.3 (0.9)	14.3 (1.6)	16.7 (1.9)	14.3 (1.6)	17.0 (1.9)
Continuous Current Rating	A	29.1	14.4	8.2	7.3	24.1	14.0	11.9	18.5	15.7
Peak Current Rating	A	58.1	28.7	16.4	14.7	48.2	27.9	23.8	37.1	31.4
MOTOR DATA										
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm (Vpk/Krpm)	40.3	80.6	138.1	161.1	80.6	138.1	161.1	138.1	164.0
Pole Configuration		8	8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	0.21	0.87	2.68	3.34	0.339	1.01	1.39	0.61	0.858
Inductance (L-L)(+/- 15%)	mH	5.4	21.7	63.9	78.3	10.4	27.6	41.5	20.0	28.2
Armature Inertia (+/- 5%)	lb-in-sec ² (Kg-cm ²)	0.00927 (10.47)				0.01537 (17.363)			0.02146 (24.249)	
Brake Inertia	lb-in-sec ² (Kg-cm ²)	0.008408 (9.5)				0.008408 (9.5)			0.008408 (9.5)	
Brake Current @ 24 VDC	A	1.0				1.0			1.0	
Brake Holding Torque	lbf-in (Nm)	354 (39.99)				354 (39.99)			354 (39.99)	
Brake Engage/Disengage Time	ms	25/73				25/73			25/73	
Mechanical Time Constant (tm)	ms	1.23	1.26	1.32	1.21	0.81	0.82	0.83	0.70	0.69
Electrical Time Constant (te)	ms	25.59	25.02	23.88	23.43	30.58	27.30	29.89	32.60	32.90
Friction Torque	lbf-in (Nm)	2.07 (0.234)				2.65 (0.299)			3.32 (0.375)	
Bus Voltage	Vrms	115	230	400	460	230	400	460	400	460
Speed @ Bus Voltage	RPM	2400								
Insulation Class		180 (H)								
Insulation System Volt Rating	Vrms	460								
Environmental Rating		IP65S								

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

Gearmotor not available on 142 frame motor.

Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2"

SLM180 Electrical/Mechanical Specifications

SLM180 Motor Stator		1 Stack Motor			2 Stack Motor			3 Stack Motor	
RMS Sinusoidal Commutation Data		138	158	168	238	258	268	358	368
Continuous Motor Torque	lbf-in (Nm)	254.2 (28.72)	249.9 (28.23)	261.9 (29.59)	424.8 (47.99)	423.0 (47.79)	427.5 (48.30)	595.6 (67.29)	611.6 (69.10)
Peak Motor Torque	lbf-in (Nm)	508.4 (57.44)	499.8 (56.47)	523.8 (59.18)	849.6 (95.99)	846.0 (95.59)	855.1 (96.61)	1,191.2 (134.58)	1223.2 (138.19)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	12.6 (1.4)	21.8 (2.5)	25.2 (2.8)	12.6 (1.4)	21.8 (2.5)	25.2 (2.8)	21.4 (2.4)	25.2 (2.8)
Continuous Current Rating (IG)	A	22.6	12.8	11.6	37.7	21.7	19.0	31.1	27.2
Peak Current Rating	A	45.2	25.6	23.3	75.5	43.4	38.0	62.2	54.3
O-PK SINUSOIDAL COMMUTATION DATA									
Continuous Motor Torque	lbf-in (Nm)	254.2 (28.72)	249.9 (28.23)	261.9 (29.59)	424.8 (47.99)	423.0 (47.79)	427.5 (48.30)	595.6 (67.29)	611.6 (69.10)
Peak Motor Torque	lbf-in (Nm)	508.4 (57.44)	499.8 (56.47)	523.8 (59.18)	849.6 (95.99)	846.0 (95.59)	855.1 (96.61)	1,191.2 (134.58)	1,223.2 (138.19)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	8.9 (1.0)	15.4 (1.7)	17.8 (2.0)	8.9 (1.0)	15.4 (1.7)	17.8 (2.0)	15.1 (1.7)	17.8 (2.0)
Continuous Current Rating	A	31.9	18.1	16.4	53.4	30.7	26.8	44.0	38.4
Peak Current Rating	A	63.9	36.2	32.9	106.7	61.3	53.7	88.0	76.8
MOTOR STATOR DATA									
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm (Vpk/Krpm)	85.9	148.9	171.8	85.9	148.9	171.8	146.1	171.8
Pole Configuration		8	8	8	8	8	8	8	8
Resistance (L-L) (+/- 5% @ 25°C)	Ohms	0.325	1.010	1.224	0.134	0.407	0.530	0.233	0.306
Inductance (L-L) (+/- 15%)	mH	8.3	24.8	29.4	3.9	11.8	15.8	7.5	10.3
Armature Inertia (+/- 5%)	lb-in-sec ² (Kg-cm ²)	0.05051 (57.071)			0.08599 (97.159)			0.12147 (137.246)	
Brake Inertia	lb-in-sec ² (Kg-cm ²)	0.02815 (31.8)							
Brake Current @ 24VDC	A	1.45							
Brake Holding Torque	lbf-in (Nm)	708 (80)							
Brake Engage/Disengage Time	ms	53/97							
Mechanical Time Constant (tm)	ms	2.25	2.33	2.12	1.58	1.59	1.56	1.34	1.27
Electrical Time Constant (te)	ms	25.44	24.58	24.03	29.38	29.14	29.76	32.07	33.81
Friction Torque	lbf-in (Nm)	5.07 (0.573)			7.80 (0.881)			11.52 (1.302)	
Bus Voltage	Vrms	230	400	460	230	400	460	400	460
Speed @ Bus Voltage	RPM	2400							
Insulation Class		180 (H)							
Insulation System Volt Rating	Vrms	460							
Thermal Switch, Case Temp	deg C	100							
Environmental Rating		IP655							

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.
 All temperature ratings ambient.
 Gearmotor not available on 180 frame.
 Test data derived using NEMA recommended aluminum heatsink 16" x 16" x 1"

SLG Series Gearmotor General Performance Specifications

Two torque ratings for the SLG Series Gearmotors are given in the table below. The left hand columns give the maximum (peak) allowable output torque for the indicated ratios of each size SLG Series Gearmotor. This is **NOT** the rated output torque of the motor multiplied by the ratio of the reducer.

It is possible to select a configuration of the motor selection and gear ratio such that the rated motor torque,

multiplied by the gear ratio exceeds these ratings. It is the responsibility of the user to ensure that the settings of the system, including the amplifier, do not allow these values to be exceeded.

The right hand columns give the output torque at the indicated speed which will result in 10,000 hour (L10). The setup of the system, including the amplifier, will determine the actual output torque and speed.

Output Torque Ratings–Mechanical

Model	Ratio	Maximum Allowable Output Torque – Set by User	Output Torque @ Speed for 10,000 Hour Life – lbf-in (Nm)		
			1000 RPM	3000 RPM	5000 RPM
SLG060	4:1	603 (68.1)	144 (16.2)	104 (11.7)	88 (9.9)
	5:1	522 (58.9)	170 (19.2)	125 (14.1)	105 (11.9)
	10:1	327 (36.9)	200 (22.6)	140 (15.8)	120 (13.6)
	16:1	603 (68.1)	224 (25.3)	160 (18.1)	136 (15.4)
	20:1	603 (68.1)	240 (27.1)	170 (19.2)	146 (16.5)
	25:1	522 (58.9)	275 (31.1)	200 (22.6)	180 (20.3)
	40:1	603 (68.1)	288 (32.5)	208 (23.5)	180 (20.3)
	50:1	522 (58.9)	340 (38.4)	245 (27.7)	210 (23.7)
	100:1	327 (36.9)	320 (36.1)	280 (31.6)	240 (27.1)
			1000 RPM	2500 RPM	4000 RPM
SLG090	4:1	2078 (234.8)	600 (67.8)	456 (51.5)	396 (44.7)
	5:1	1798 (203.1)	775 (87.6)	590 (66.7)	510 (57.6)
	10:1	1126 (127.2)	890 (100.6)	680 (76.8)	590 (66.7)
	16:1	2078 (234.8)	912 (103.4)	688 (77.7)	592 (66.9)
	20:1	2078 (234.8)	980 (110.7)	740 (83.6)	640 (72.3)
	25:1	1798 (203.1)	1250 (141.2)	950 (107.3)	825 (93.2)
	40:1	2078 (234.8)	1200 (135.6)	920 (103.9)	800 (90.4)
	50:1	1798 (203.1)	1550 (169.4)	1200 (135.6)	1000 (112.9)
	100:1	1126 (127.2)	1100 (124.3)	1100 (124.3)	1100 (124.3)
			1000 RPM	2000 RPM	3000 RPM
SLG115	4:1	4696(530.4)	1392 (157.3)	1132 (127.9)	1000 (112.9)
	5:1	4066 (459.4)	1445 (163.3)	1175 (132.8)	1040 (117.5)
	10:1	2545 (287.5)	1660 (187.6)	1350 (152.6)	1200 (135.6)
	16:1	4696 (530.4)	2112 (238.6)	1714 (193.0)	1518 (171.0)
	20:1	4696 (530.4)	2240 (253.1)	1840 (207.9)	1620 (183.0)
	25:1	4066 (459.4)	2350 (265.5)	1900 (214.7)	1675 (189.2)
	40:1	4696 (530.4)	2800 (316.4)	2240 (253.1)	2000 (225.9)
	50:1	4066 (459.4)	2900 (327.7)	2350 (265.5)	2100 (237.3)
	100:1	2545 (287.5)	2500 (282.5)	2500 (282.5)	2400 (271.2)

SLM Radial Load

	RPM	50	100	250	500	1000
SLM060 lbf (N)		250 (1112)	198 (881)	148 (658)	116 (516)	92 (409)
SLM090 lbf (N)		427 (1899)	340 (1512)	250 (1112)	198 (881)	158 (703)
SLM115 lbf (N)		579 (2576)	460 (2046)	339 (1508)	269 (1197)	214 (952)
SLM142 lbf (N)		1367 (6081)	1085 (4826)	800 (3559)	635 (2825)	504 (2242)
SLM180		2237 (9951)	1776 (7900)	1308 (5818)	1038 (4617)	824 (3665)

SLG Radial Load

	RPM	50	100	250	500	1000
SLG060 lbf (N)		189 (841)	150 (667)	110 (489)	88 (391)	70 (311)
SLG090 lbf (N)		350 (1557)	278 (1237)	205 (912)	163 (725)	129 (574)
SLG115 lbf (N)		858 (3817)	681 (3029)	502 (2233)	398 (1770)	316 (1406)

Side load ratings shown above are for 10,000 hour bearing life at 25mm from motor face at given rpm.

Motor and Gearmotor Weight

	SLM/G060			SLM/G090			SLM/G115			SLM142	SLM180
	Motor	1 Stage	2 Stage	Motor	1 Stage	2 Stage	Motor	1 Stage	2 Stage	(gear stages not available on SLM142 and SLM180)	
1 Stack lbs (kg)	3.0 (1.4)	7.5 (3.4)	9.3 (2.4)	5.4 (2.4)	12.8 (5.8)	14.8 (6.7)	14.2 (6.4)	28 (12.7)	34 (15.4)	31 (14.0)	60 (27.2)
2 Stack lbs (kg)	4.1 (1.9)	8.6 (3.9)	10.4 (4.7)	7.8 (3.5)	15.2 (6.9)	17.2 (7.8)	22.0 (9.9)	35.8 (16.2)	41.8 (18.9)	39 (17.7)	82 (37.2)
3 Stack lbs (kg)	5.2 (2.4)	9.7 (4.4)	11.5 (5.2)	10.2 (4.6)	17.6 (7.9)	19.6 (8.9)	29.8 (13.5)	43.6 (19.8)	49.6 (22.5)	47 (21.3)	104 (47.2)
Brake		1.8 (0.8)			2.7 (1.2)			4.1 (1.9)		6.0 (2.7)	12 (5.4)

Motor Speed Designators

All Exlar T-LAM motors and actuators carry a standard motor speed designator as defined below. This is representative of the standard base speed of the motor, for the selected bus voltage.

If the model number is created and the location for the motor speed designator is left blank, this is the base speed to which each motor will be manufactured. The model number can also be created including this standard speed designator.

Exlar also provides the flexibility to manufacture all of its "T-LAM" products with special base speeds to match the customer's exact application requirements. This may be a higher than standard speed motor, or lower base speed than standard which will allow the customer to get the required torque at a speed optimized to their application and use the minimum amount of current from their amplifier.

The call-out for a special speed is configured in the model number by using a two digit code from 01-99. These numbers represent the number, in hundreds, of RPM that will be the base speed for the particular motor.

For example, an SLG090-010-KCGS-AB1-138-40 motor that normally has a 4000 rpm standard winding can be changed to a 3300 rpm winding by changing the -40, to a -33. It can be changed to a 5000 rpm winding by changing the -40 to a -50.

Changing this speed designator will change the ratings of the motor, and these must be obtained from your local sales representative. Also, it is not possible to produce every possible speed from -01 to -99 for each motor at each voltage so please contact your local sales representative for confirmation of the speed that is desired for the application.

Designator	Base Speed	Motor Series
-50	5000 rpm	SLM/SLG060
-40	4000 rpm	SLM/SLG090
-30	3000 rpm	SLM/SLG115
-24	2400 rpm	SLM142, SLM180
01-99	Special Speed, consult your local sales representative	

Motor Options

SLM/SLG motor options are described with a 3 digit code. The first digit calls out the stack length, the second the rated bus voltage, and the third the number of poles of the motor. Refer to the mechanical/electrical specifications for motor torque and actuator rated force.

IP Ratings

Please see page 26 for full description of IP Ratings.

8 Pole, Class 180 H

1 Stack		2 Stack		3 Stack	
118	115 Vrms	218	115 Vrms	318	115 Vrms
138	230 Vrms	238	230 Vrms	338	230 Vrms
158	400 Vrms	258	400 Vrms	358	400 Vrms
168	460 Vrms	268	460 Vrms	368	460 Vrms
1A8*	24 VDC	2A8*	24 VDC	3A8*	24 VDC
1B8*	48 VDC	2B8*	48 VDC	3B8*	48 VDC
1C8*	120 VDC	2C8*	120 VDC	3C8*	120 VDC

Refer to specification pages 79-83 for availability of 115V stators by configuration.

* Low voltage stators may be limited to less than catalog rated torque and/or speed. Please contact your local sales representative when ordering this option.

Housing/Special Options

G = Anodized Aluminum

F = Smooth White Epoxy

This option provides for an actuator coated with FDA approved white epoxy.

E = Electroless Nickel Plating

This option provides for a motor with electroless nickel plating.

SS = Stainless Steel Housing

This option provides a motor with all stainless steel construction. Housing dimensions for this option are not equal to the standard housing. Force, torque and current ratings are reduced 25% with this option. Please inquire with your local sales representative for dimensions and ratings.

HC = Type III Hard Coat Anodized, Class I

This option provides an actuator with type III hard coat anodized coating. Class I, no dye.

XH = Special Housing Option

Any housing option that is not designated by the above codes should be listed as XH and described at time of order. All special options must be discussed with your local sales rep.

HW = Manual Drive, Handwheel

This option provides a manual drive handwheel on the side of the motor. The handwheel has an engage/disengage lever that is tied to an interrupt switch. Not available on SLM/G060. Also not available with holding brake unless application details have been discussed with your local sales representative.

RD = Manual Drive, Rear Hex

This option provides a hex shaft at the rear of the motor for manual operation. The hex shaft is directly coupled to the motor and can be turned by hand with a compatible wrench. The hex shaft is enclosed by a sealed cap

during operation. This option is not available w/absolute feedback. If the application requires a brake, discuss manual drive use with your local sales representative.

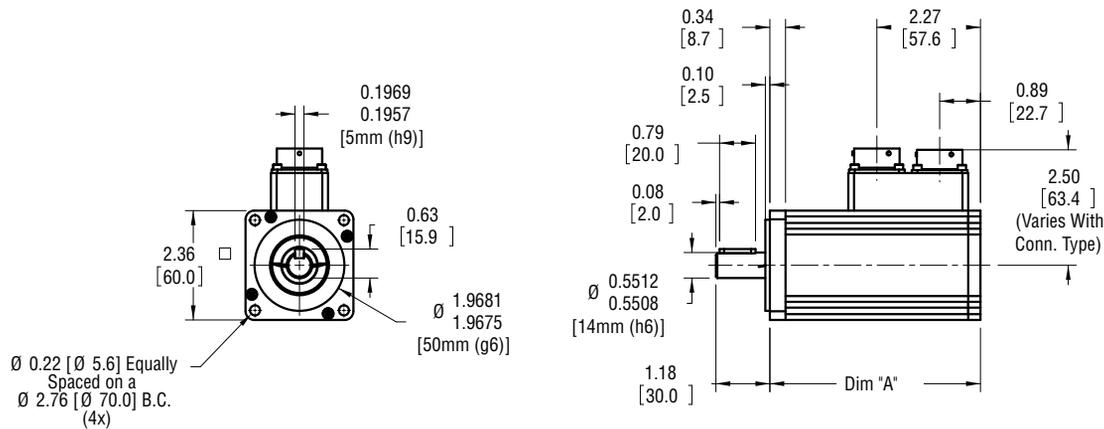
SD = Manual Drive, Side Hex

This option provides a hex manual drive on the side of the motor. The hex can be turned by hand with a wrench. Not available on SLM/G060. Also not available with holding brake unless application details have been discussed with your local sales representative.

XL = Non-Standard Lubrication

This option provides for indication in the model number that the customer has specified a lubrication other than the standard provided by Exlar, Mobilith SHC220. Specials include other greases including JAX FG-2 food grade, Mobilgrease 28, or other non-standard grease.

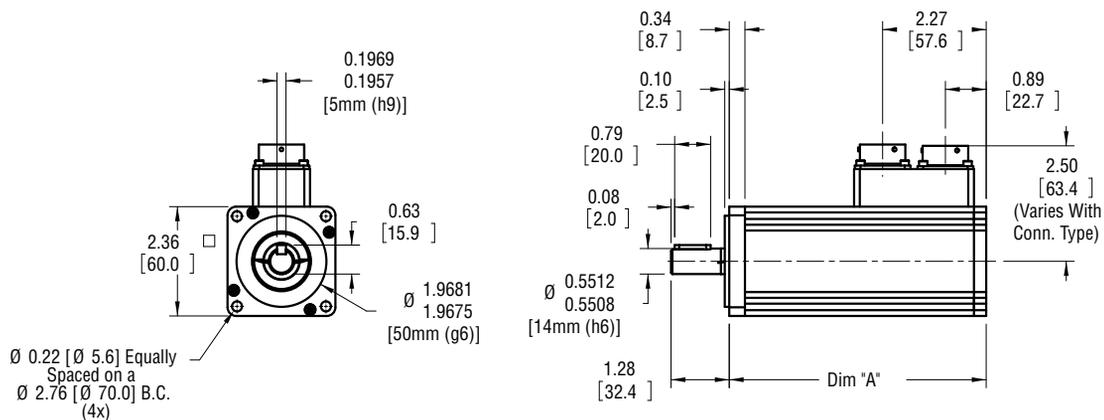
SLM060



DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	4.61 (117.1)	5.86 (149.9)	7.11 (180.6)

Face plate edge is not intended for alignment of shaft (use pilot)

SLM060 With Brake Option

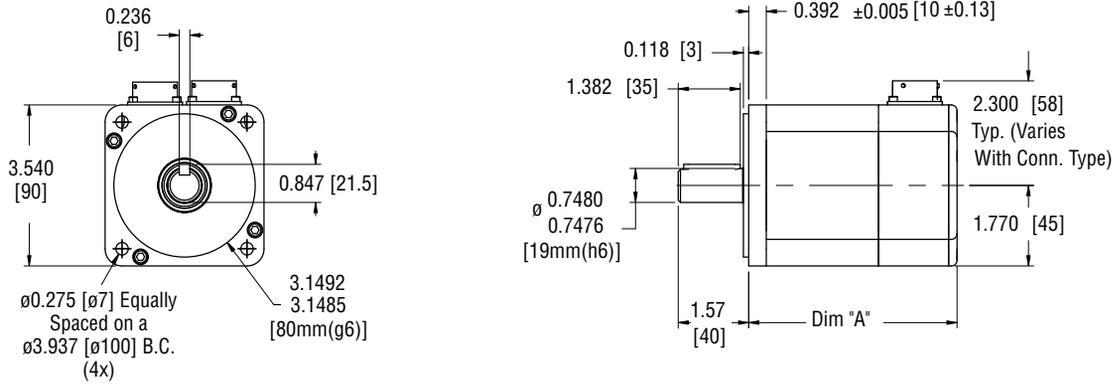


DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	5.63 (143.0)	6.88 (174.7)	8.13 (206.4)

Face plate edge is not intended for alignment of shaft (use pilot)

Drawings subject to change. Consult Exlar for certified drawings.

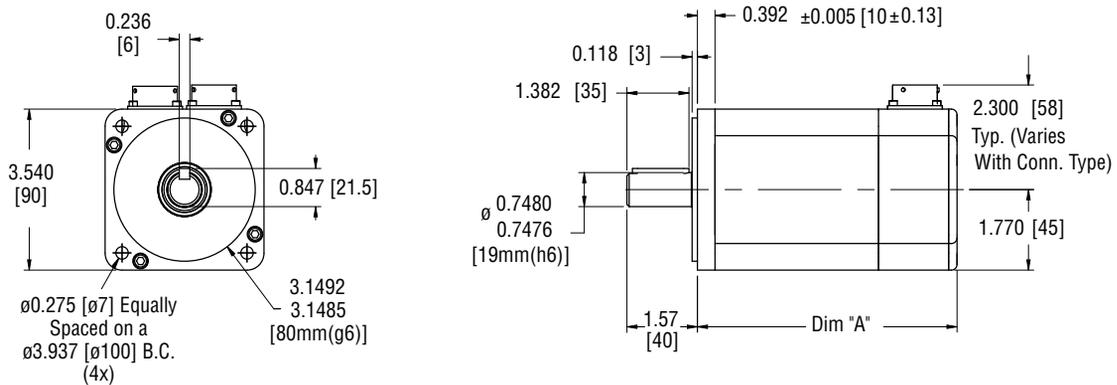
SLM090



DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	4.650 (118)	5.650 (144)	6.650 (169)

Face plate edge is not intended for alignment of shaft (use pilot)

SLM090 With Brake Option

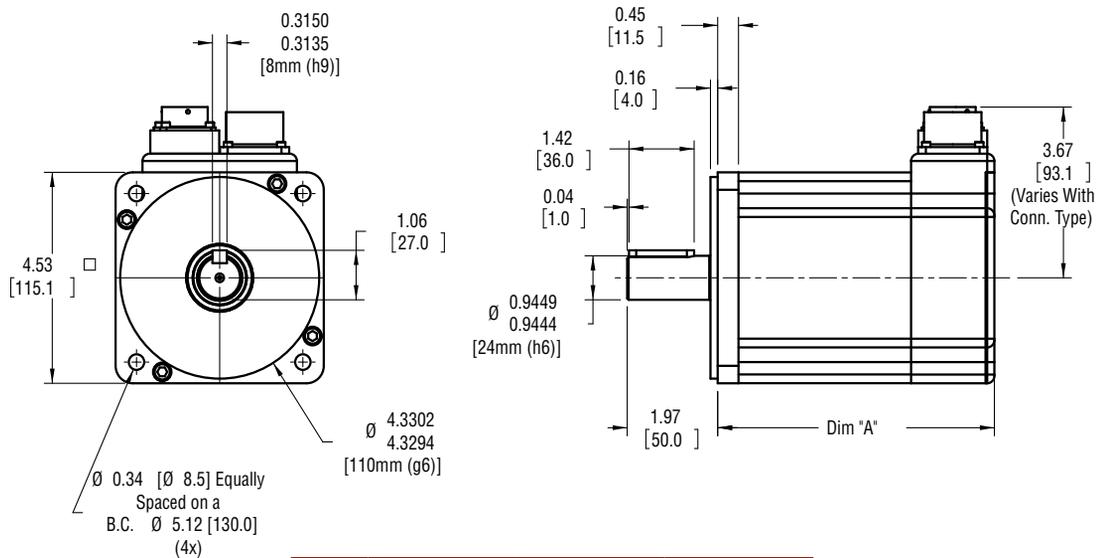


DIM	1 Stack Motor in (mm)	2 Stack Motor in (mm)	3 Stack Motor in (mm)
A	5.960 (151)	6.960 (177)	7.960 (202)

Face plate edge is not intended for alignment of shaft (use pilot)

Drawings subject to change. Consult Exlar for certified drawings.

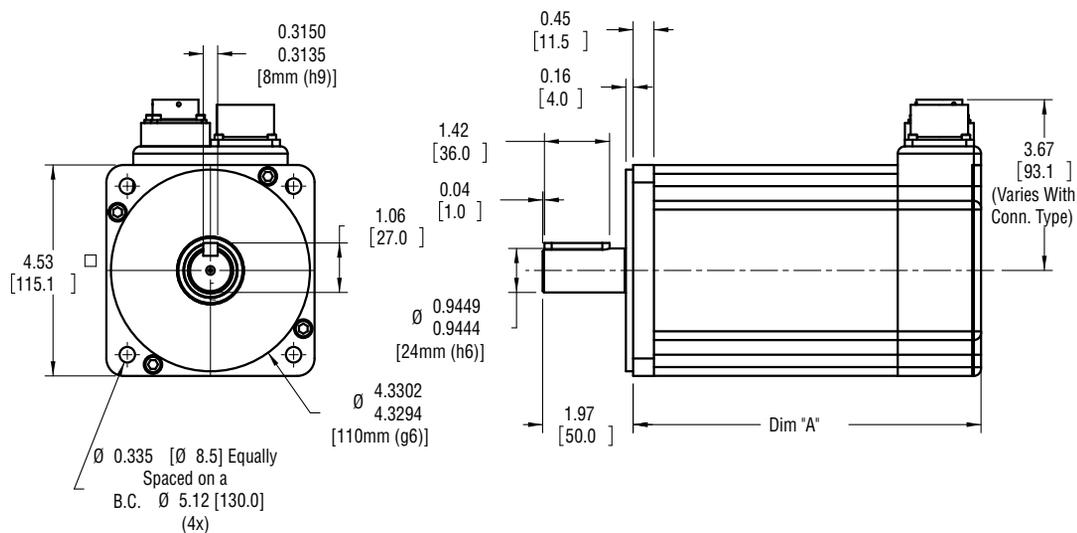
SLM115



DIM	1 Stack—no brake in (mm)	2 Stack—no brake in (mm)	3 Stack—no brake in (mm)
A	6.02 (153.0)	8.02 (203.7)	10.02 (254.5)

Face plate edge is not intended for alignment of shaft (use pilot)

SLM115 With Brake Option

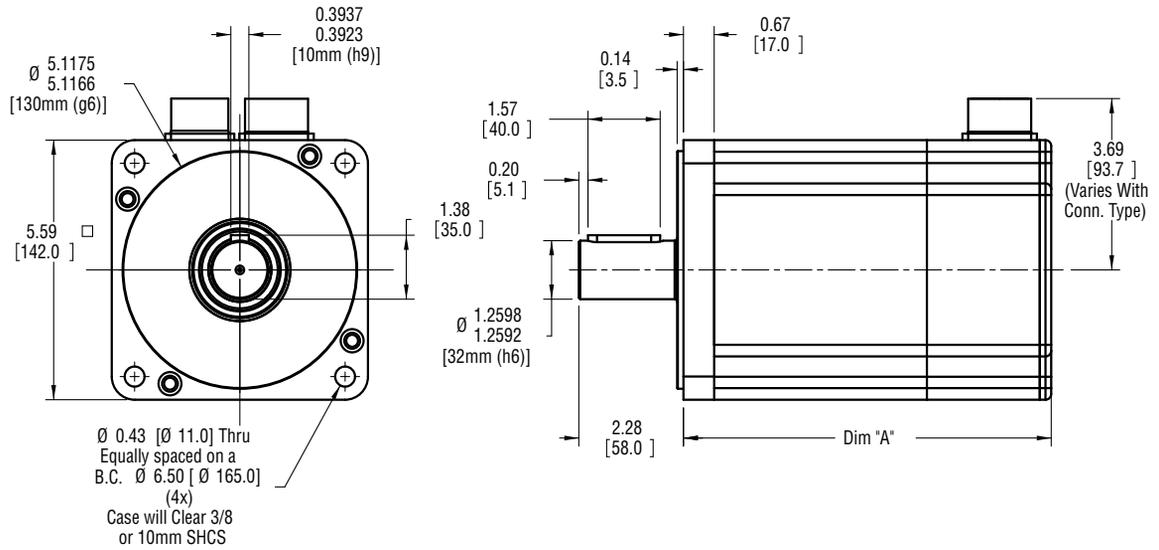


DIM	1 Stack—with brake in (mm)	2 Stack—with brake in (mm)	3 Stack—with brake in (mm)
A	7.75 (196.9)	9.75 (247.7)	11.75 (298.5)

Face plate edge is not intended for alignment of shaft (use pilot)

Drawings subject to change. Consult Exlar for certified drawings.

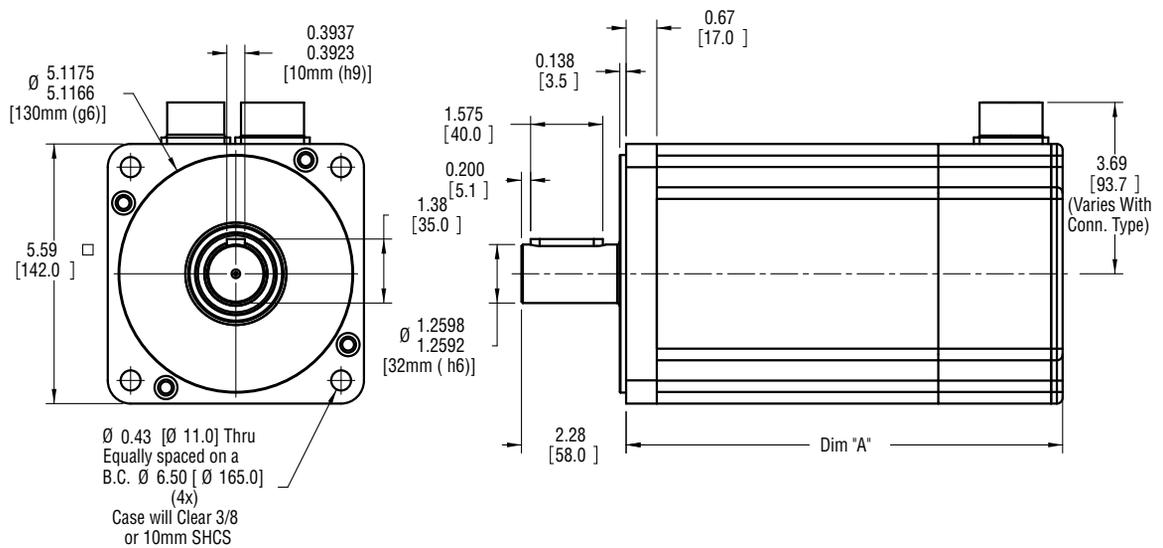
SLM142



DIM	1 Stack—no brake in (mm)	2 Stack—no brake in (mm)	3 Stack—no brake in (mm)
A	7.87 (199.8)	9.62 (244.2)	11.37 (288.7)

Face plate edge is not intended for alignment of shaft (use pilot)

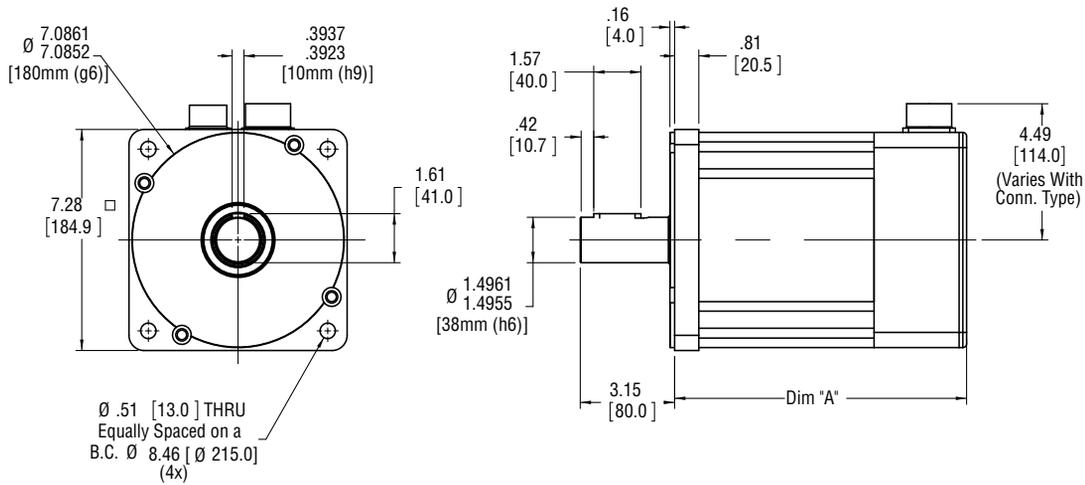
SLM142 With Brake Option



DIM	1 Stack—with brake in (mm)	2 Stack—with brake in (mm)	3 Stack—with brake in (mm)
A	9.53 (241.9)	11.28 (286.4)	13.03 (330.8)

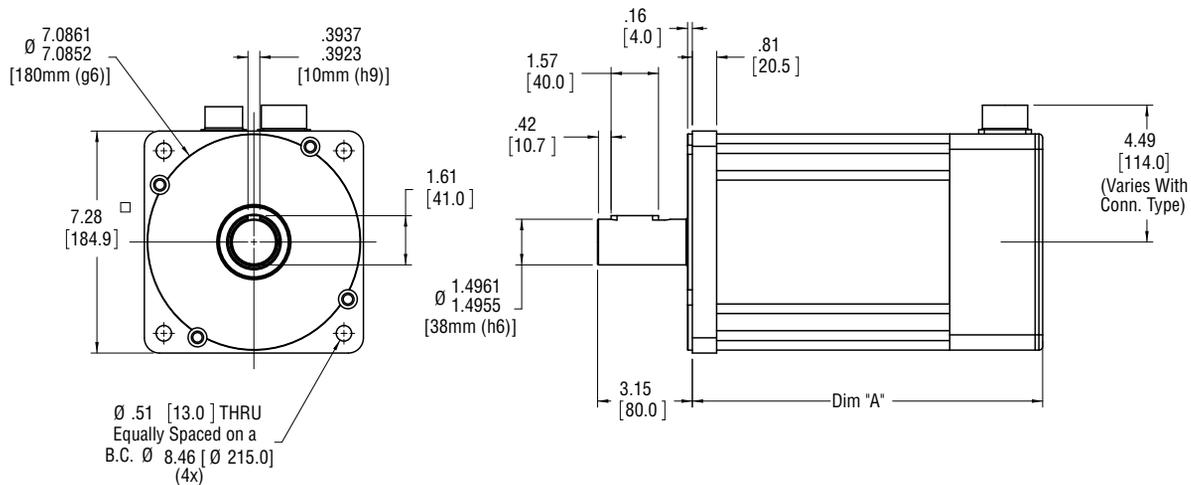
Face plate edge is not intended for alignment of shaft (use pilot)

SLM180



DIM	1 Stack-no Brake in (mm)	2 Stack-no Brake in (mm)	3 Stack-no Brake in (mm)
A	9.74 (247.5)	12.24 (310.9)	14.74 (374.4)

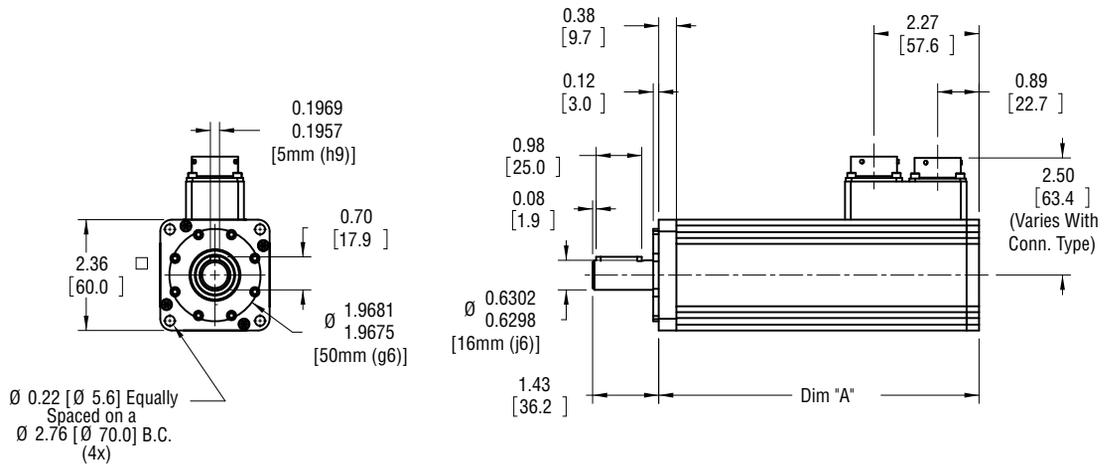
SLM180 With Brake Option



DIM	1 Stack-with Brake in (mm)	2 Stack-with Brake in (mm)	3 Stack-with Brake in (mm)
A	11.64 (295.7)	14.14 (359.2)	16.64 (422.7)

Drawings subject to change. Consult Exlar for certified drawings.

SLG060

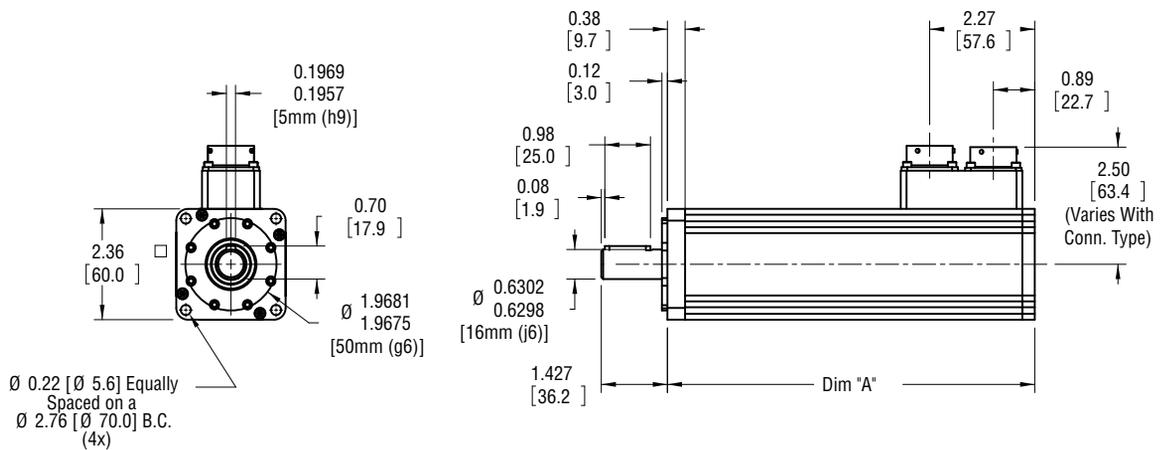


DIM	1 Stack Stator in (mm) 1 Stage Gearhead	2 Stack Stator in (mm) 1 Stage Gearhead	3 Stack Stator in (mm) 1 Stage Gearhead
A	6.915 (176)	8.165 (207)	9.415 (239)
	2 Stage Gearhead	2 Stage Gearhead	2 Stage Gearhead
	7.960 (202)	9.210 (234)	10.460 (266)

Face plate edge is not intended for alignment of shaft (use pilot)

SLM/SLG Series

SLG060 With Brake Option

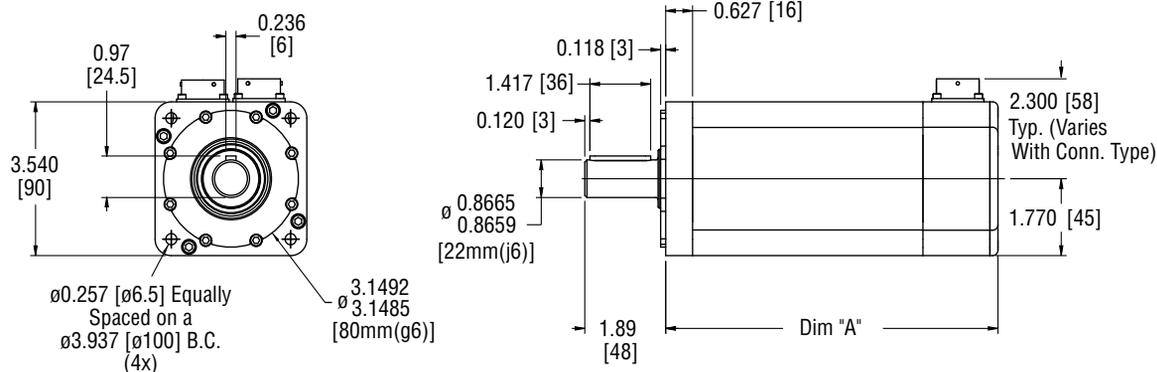


DIM	1 Stack Stator in (mm) 1 Stage Gearhead	2 Stack Stator in (mm) 1 Stage Gearhead	3 Stack Stator in (mm) 1 Stage Gearhead
A	7.930 (201)	9.180 (233)	10.430 (265)
	2 Stage Gearhead	2 Stage Gearhead	2 Stage Gearhead
	8.975 (228)	10.225 (260)	11.475 (291)

Face plate edge is not intended for alignment of shaft (use pilot)

Drawings subject to change. Consult Exlar for certified drawings.

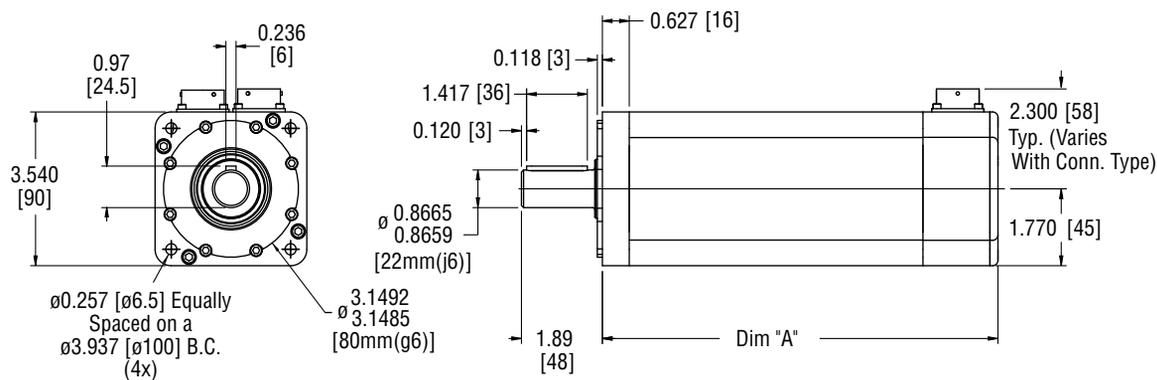
SLG090



DIM	1 Stack Stator in (mm) 1 Stage Gearhead	2 Stack Stator in (mm) 1 Stage Gearhead	3 Stack Stator in (mm) 1 Stage Gearhead
A	7.760 (197)	8.760 (223)	9.760 (248)
	2 Stage Gearhead 9.025 (229)	2 Stage Gearhead 10.025 (255)	2 Stage Gearhead 11.025 (280)

Face plate edge is not intended for alignment of shaft (use pilot)

SLG090 With Brake Option

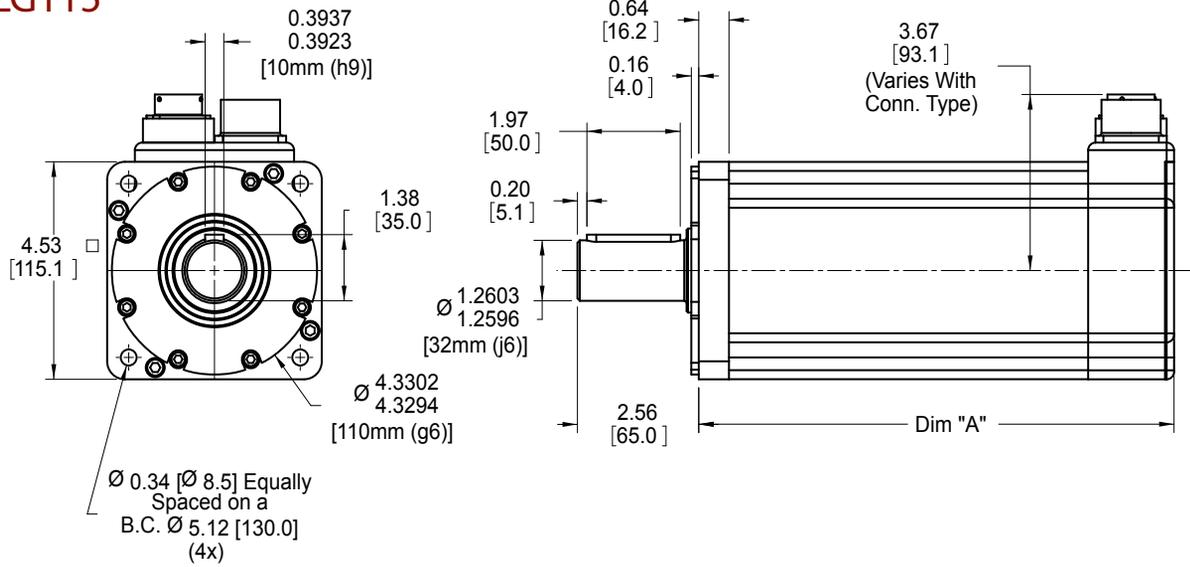


DIM	1 Stack Stator in (mm) 1 Stage Gearhead	2 Stack Stator in (mm) 1 Stage Gearhead	3 Stack Stator in (mm) 1 Stage Gearhead
A	9.070 (230)	10.070 (256)	11.070 (281)
	2 Stage Gearhead 10.335 (263)	2 Stage Gearhead 11.335 (288)	2 Stage Gearhead 12.335 (313)

Face plate edge is not intended for alignment of shaft (use pilot)

Drawings subject to change. Consult Exlar for certified drawings.

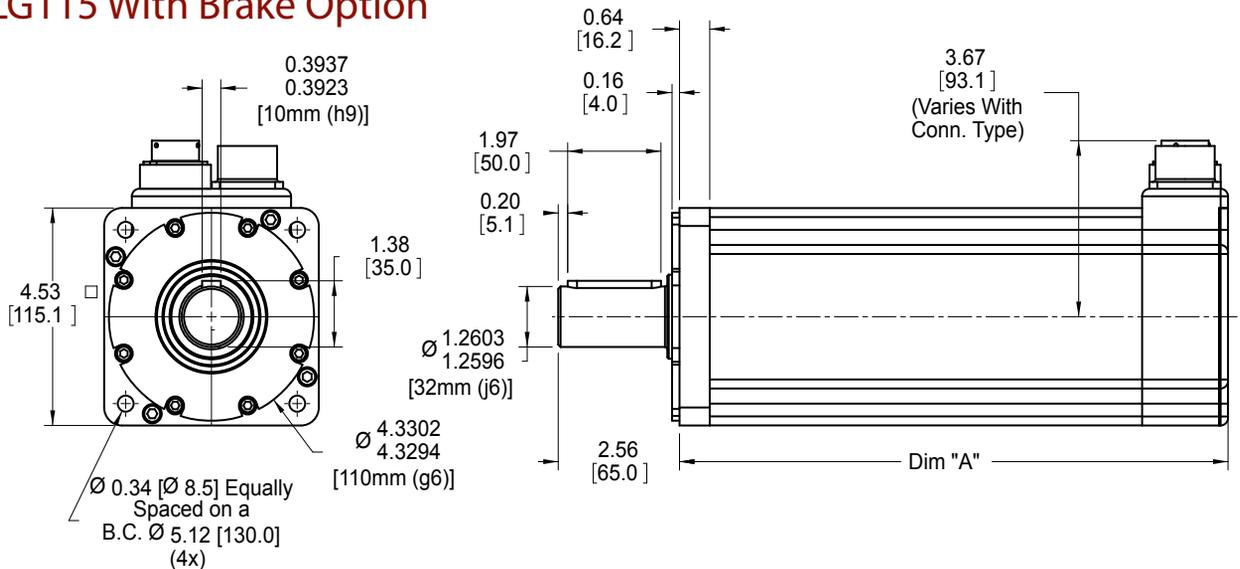
SLG115



DIM	1 Stack Stator in (mm) 1 Stage Gearhead	2 Stack Stator in (mm) 1 Stage Gearhead	3 Stack Stator in (mm) 1 Stage Gearhead
A	10.03 (254.8)	12.03 (305.6)	14.03 (356.4)
	11.64 (295.7)	13.64 (346.5)	15.64 (397.3)

NOTE: Dimension format = in. (mm)
Face plate edge is not intended for alignment of shaft (use pilot)

SLG115 With Brake Option



DIM	1 Stack Stator in (mm) 1 Stage Gearhead	2 Stack Stator in (mm) 1 Stage Gearhead	3 Stack Stator in (mm) 1 Stage Gearhead
A	11.58 (294.2)	13.58 (345.0)	15.58 (395.8)
	13.19 (335.1)	15.19 (385.9)	17.19 (436.7)

NOTE: Dimension format = in. (mm)
Face plate edge is not intended for alignment of shaft (use pilot)

Drawings subject to change. Consult Exlar for certified drawings.

SLM/G = Model Series

SLG = SLG Series Servo Gear Motor
SLM = SLM Series Servo Motor
(No Gear Reduction)

AAA = Frame Size

060 = 60 mm
090 = 90 mm
115 = 115 mm
142 = 142 mm
180 = 180 mm

BBB = Gear Reduction Ratio

Blank = SLM

Single reduction ratios

004 = 4:1
005 = 5:1
010 = 10:1

Double reduction ratios

016 = 16:1
020 = 20:1
025 = 25:1
040 = 40:1
050 = 50:1
100 = 100:1

CC = Shaft Type

K = Keyed
R = Smooth/round
X = Special shaft

D = Connections

I = Exlar standard M23 style
M = Manufacturer's connector²
A = MS style (anodized)
D = MS style (electroless nickel)
B = Embedded leads 3 ft. std.
P = Embedded leads w/plug
3 ft. std.w/"A" plug
J = Embedded leads w/"I" plug
3 ft. standard
X = Special (please specify)

E = Coating Options¹

G = Anodized Aluminum
E = Electroless nickel plated
F = Smooth white epoxy
X = Special coating

F = Brake Options

B = Brake
S = Standard no brake

GGG = Feedback Type (Also specify the Amplifier/Drive Model being used when ordering)

- Standard Incremental Encoder – 2048 line (8192 cts) per rev. index pulse, Hall commutation, 5vdc
- Standard Resolver – Size 15, 1024 line (2048 cts) per rev. two pole resolver
- Motor files for use with select Emerson/CT, Rockwell /AB and Danaher/Kollmorgen Drives are available at www.exlar.com

Custom Feedback - contact your local sales representative:

XX1 = Wiring and feedback device information must be provided and new feedback callout will be created

Allen-Bradley/Rockwell: (Actuators used with Kinetix and/or Sercos based control systems require a .cmf file from from AB/Rockwell.

Please contact your AB/Rockwell representative for support.)

AB8 = Standard Incremental Encoder – MPL Circular (Speedtec) DIN connectors for 'M' option

AB9 = Hiperface Stegmann SRM050 absolute encoder – 115, 142, 180 Frame Size – MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option⁷

ABB = Hiperface Stegmann SKM036 multi-turn absolute encoder. 60-90 Frame Size. MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option⁷

AMKASYN:

AK1 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 115, 142, 180 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option

AK2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 60-90 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option

Advanced Motion Control:

AM1 = Standard Incremental Encoder
AM2 = Encoder 1000 line, w/commutation, 5 VDC

AM3 = Standard Resolver

AM5 = Encoder 5000 line, w/commutation, 5 VDC

API Controls:

AP1 = Standard Resolver
AP2 = Standard Incremental Encoder

Aerotech:

AR1 = Encoder 5000 line, w/commutation, 5 VDC
AR2 = Standard Incremental Encoder

ABB Robot:

BB1 = LTN Resolver

Baldor:

BD2 = Std Resolver – BSM motor wiring w/M23 connectors for 'M' option
BD3 = Std Incremental Encoder – BSM motor wiring w/M23 connectors for 'M' option

Beckhoff:

BE2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AM5XX motor wiring w/M23 euro connectors for 'M' option

Baumuller:

BM2 = Standard Resolver

B&R Automation:

BR1 = Standard Resolver
BR2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 8LS/8LM motor wiring w/M23 euro connectors for 'M' option

Comau Robot:

CM1 = Standard Resolver

Copley Controls:

CO1 = Standard Incremental Encoder
CO2 = Standard Resolver

Control Techniques/Emerson:

CT1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 115, 142, 180 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

CT3 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 60-90 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

CT4 = Standard Incremental Encoder – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

CT5 = Std Resolver – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

CT7 = Encoder 5000 line, with commutation, 5 VDC – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

Delta Tau Data Systems:

DT1 = Encoder 1000 line, w/commutation, 5 VDC
DT2 = Standard Resolver

Elmo Motion Control:

EL1 = Standard Resolver
EL2 = Standard Incremental Encoder
EL3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

Emerson/Control Techniques:

EM2 = Std Incremental Encoder – NT motor wiring w/MS connectors for 'M' option
EM5 = Encoder 5000 line, with commutation, 5 VDC – NT motor wiring w/MS connectors for 'M' option

Elau:

EU1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 115, 142, 180 Frame Size. SH motor wiring w/MS connectors for 'M' option

EU4 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 60-90 Frame Size. SH motor wiring w/MS connectors for 'M' option

Exlar:

EX4 = Standard Resolver

Fanuc Pulsecoder: Consult Exlar⁹

G&L Motion Control/Danaher Motion:

GL1 = Std Incremental Encoder – HSM motor wiring w/ MS connectors for 'M' option
GL2 = Std Incremental Encoder – LSM-MSM motor wiring w/M23 euro connectors for 'M' option

GL3 = Std Incremental Encoder – NSM motor wiring w/MS connectors for 'M' option

GL4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

Infranor:

IF1 = Standard Resolver

Indramat/Bosch-Rexroth:

IN6 = Std Resolver – MKD/MHD motor wiring w/M23 euro connectors for 'M' option

IN7 = Hiperface Stegmann SKM036 multi-turn absolute encoder – MSK motor wiring w/M23 euro connectors for 'M' option – plug & play option

Jetter Technologies:

JT1 = Standard Resolver – JH/JL motor wiring w/M23 euro connectors for 'M' option

Kollmorgen/Danaher:

KM4 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

KM5 = Standard Resolver – AKM motor wiring w/M23 euro connectors for 'M' option

KM6 = Standard Incremental Encoder – AKM motor wiring w/ M23 euro connectors for 'M' option

Kuka Robot:

KU1 = Tyco Size 21 Resolver⁹

Kawasaki Robot:

KW1 = Kawasaki Special Encoder⁹

Lenze/AC Tech:

LZ1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MCS motor wiring w/M23 euro connectors for 'M' option

LZ5 = Standard Resolver – MCS motor wiring w/ M23 euro connectors for 'M' option

LZ6 = Standard Incremental Encoder – MCS motor wiring w/ M23 euro connectors for 'M' option

Matuschek:

MC1 = LTN Resolver

Metronix:

MX1 = Standard Resolver

MX2 = Hiperface Stegmann SKM036 multi-turn absolute encoder

MX3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

Mitsubishi:

MT1 = Mitsubishi Absolute Encoder – HF-SP motor wiring with 'M' option

Modicon:

MD1 = Standard Resolver

Momentum:

MN1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MN motor wiring w/M23 connectors for 'M' option

MN2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – MN motor wiring connectors for 'M' option

MN3 = Std incremental encoder – MN motor wiring w/M23 connectors for 'M' option

MN4 = Std resolver – MN motor wiring w/M23 connectors for 'M' option

Moog:

MG1 = Standard Resolver

Motoman Robot:

MM1 = Yaskawa Serial Encoder⁹

Nachi Robot:

NC1 = Tamagawa Serial Encoder⁹

Ormec:

OR1 = Standard Resolver

OR2 = Std Incremental Encoder – G series motor wiring w/MS connectors for 'M' option

Parker Compumotor:

PC6 = Std Incremental Encoder – SMH motor wiring w/M23 connectors for 'M' option – European only

PC7 = Std Resolver – SMH motor wiring w/M23 connectors for 'M' option – European only

PC8 = Std Incremental Encoder – MPP series motor wiring w/PS connectors for 'M' option – US Only

PC9 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MPP motor wiring w/PS connectors for 'M' option – US Only

PC0 = Std Resolver – MPP motor wiring w/PS connectors for 'M' option – US Only

Pacific Scientific:

PS2 = Standard Incremental Encoder

PS3 = Standard Resolver – PMA motor wiring w/M23 connectors for 'M' option

Stober Drives:

SB3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – ED/EK motor wiring w/M23 euro connectors for 'M' option

SB4 = Standard Resolver ED/EK motor wiring w/M23 connector for 'M' option

Siemens:

SM2 = Standard Resolver – 1FK7 motor wiring w/M23 connectors for 'M' option

SM3 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 115, 142, 180 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

SM4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 60-90 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

SEW/Eurodrive:

SW1 = Standard Resolver – CM motor wiring w/ M23 euro connectors for 'M' option

SW2 = Standard Incremental Encoder

SW3 = Hiperface Stegmann SRM050 multi-turn absolute encoder – CM motor wiring w/ M23 euro connectors for 'M' option

Whedco:

WD1 = Standard Resolver

HHH = Motor Stator – All 8 Pole³

118 = 1 stack	115 Vrms	158 = 1 stack	400 Vrms
218 = 2 stack		258 = 2 stack	
318 = 3 stack		358 = 3 stack	
138 = 1 stack	230 Vrms	168 = 1 stack	460 Vrms
238 = 2 stack		268 = 2 stack	
338 = 3 stack		368 = 3 stack	

II = Optional Speed and Mechanical Designations

24 = 2400 rpm, SLM142 & 180

30 = 3000 rpm, SLM/G115

40 = 4000 rpm, SLM/G090

50 = 5000 rpm, SLM/G060

01-99 = Special speed, consult your local sales representative

XX = Part Number Designator for specials

HC = Type III hard coat anodized, class I¹

HW = Manual drive, handwheel with Interlock switch⁵

RD = Manual drive, Simple Rear⁵

SD = Manual drive, Side Hex

SS = Stainless steel housing^{1,8}

XH = Special housing or mounting option^{1,4}

XM = Special motor options

XF = Special feedback option

XL = Special lubrication, food grade or Mobilgrease 28, specify

XT = Special option

= Part No. Designator for Specials

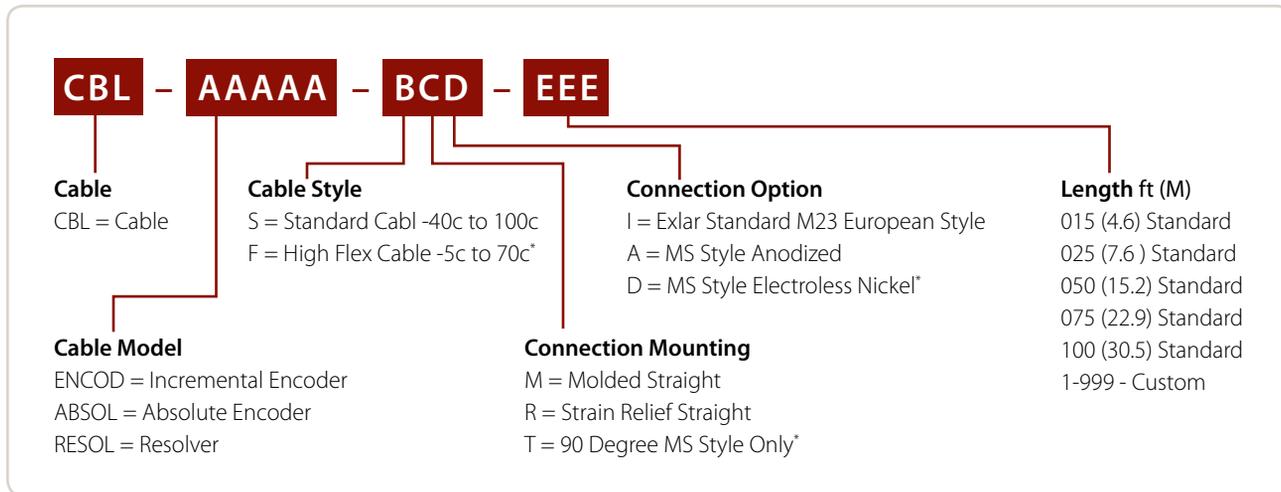
Optional 5 digit assigned part number to designate unique model numbers for specials.

Note:

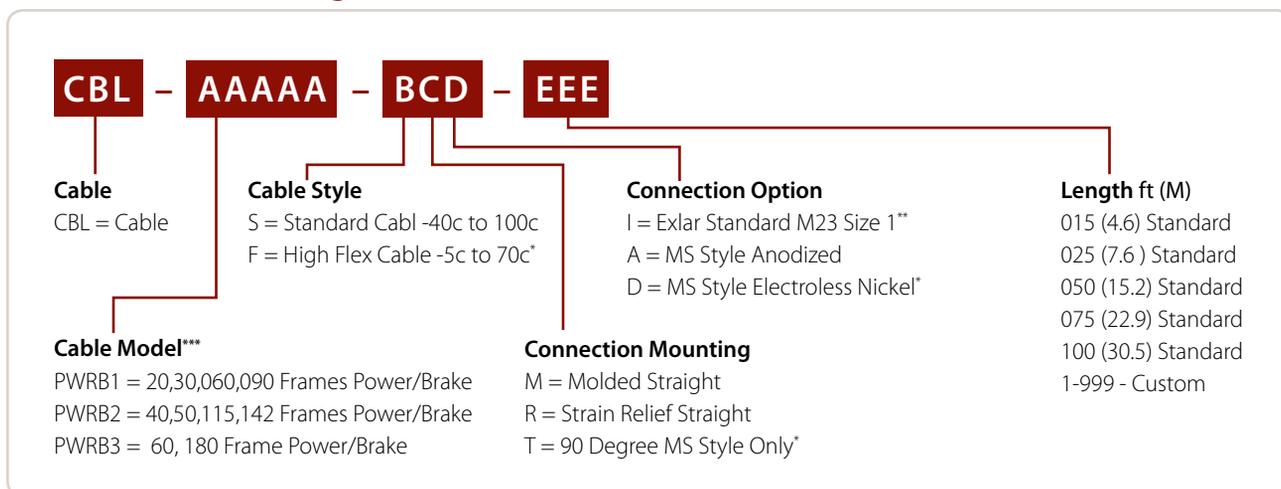
Any specials denoted by an X in the part number require definition and quotation from the factory.

1. These housing options would typically be accompanied by the choice of the electroless nickel connectors if a connectorized unit were selected. Please inquire with your local sales representative.
2. Available as described in Feedback Types.
3. See page 85 for explanation of voltage, speed, stack and optimized stator options.
4. When selecting special housing options, use "G" in this model mask location.
5. Not available with absolute feedback.
6. Not available on SLM/G060
7. Not compatible with Kinetix 300 drives.
8. Force, torque and current ratings are reduced 25% with this option.
9. Requires Robot Vendor Approval and Support.

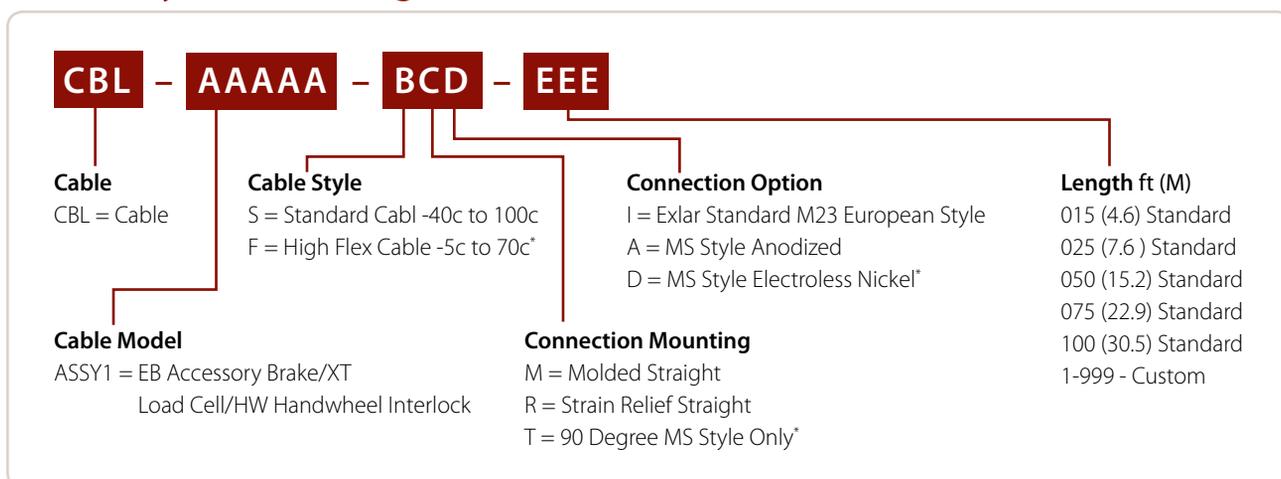
Feedback Cable Configuration - e.g. CBL-ENCOD-SMI-015



Power Cable Configuration - e.g. CBL-PWRB1-SMI-015



Accessory Cable Configuration - e.g. CBL-ASSY1-SMI-015



All Exlar cables rated IP65 when mated to actuator.

* Non-standard options – require longer lead times.

** PWRB3 uses M40 size 1.5.

*** Special stator winding may require a special power cable

Manufacturers Feedback Cable Selection Guide

Amplifier/Drive Selected	Feedback Selected	Manufacturers Part Number
Allen-Bradley/Rockwell: Ultra 3000/5000/Kinetix 6000	AB8/AB9/ABB	2090-CFBM7DF-CDAXyy
AMKASYN: All Drives	AK1/AK2	DS Series Absolute Encoder Cable
Beckhoff: All Drives	BE1	ZK4000-26yy-2zzz
B&R Automation: All Drives	BR1 BR2	8CRxxx.12-1 8CExxx.12-1
Emerson/Control Techniques: Unidrive SP/Epsilon EP	CT1/CT3 CT2/EM2/EM5 CT4/CT7 CT5	SSBAP/SSBAHC UFCS SIBAA/SIBAAA SRBAC/SRBABB
En/Epsilon/MDS	CT4/CT7 EM2/EM5	SIBAH/SIBAFA CFCS
Elau: All Drives	EU1/EU4	SH Series Absolute Encoder Cable
G&L Motion Control/Danaher Motion: MMC Smart Drive/ Digital MMC Control	GL1 GL2 GL3 GL4	ENC-H&F ENC-L&M ENC-NSM ENDAT-AKM
Indramat/Bosch-Rexroth: DKC Series/DIAX IndraDrive	IN1 IN5 IN6 IN7	IKS4001 IKS4001 IKS4374 RKG4200
Jetter Technologies: JetMove 2xx JetMove 6xx	JT1 JT1	JH/JL Series Resolver Cable Nr. 23 JH/JL Series Resolver Cable Nr. 423
Kollmorgen/Danaher: All Drives	KM4 KM5 KM6	AKM Series Absolute Encoder Cable AKM Series Resolver Cable AKM Series Incremental Encoder Cable
Lenze/AC Tech: All Drives	LZ1 LZ5 LZ6	MCS Series Absolute Encoder Cable MCS Series Resolver Cable MCS Series Incremental Encoder Cable
Mitsubishi: MR-J3	MT1	MR-J3ENSCBLxxM-H
Momentum: All Drives	MN1 MN2 MN3 MN4	SC-AE1-xxx SC-AE2-xxx SC-IE1-xxx SC-RS1-xxx
Ormec: All Drives	OR2	Consult Exlar
Parker Compumotor: All Drives	PC6 PC7 PC8 PC9/ PCØ	SMH Series Incremental Encoder Cable SMH Series Resolver Cable COMPAX3 F-2C1-xx or Aries F-1A1-xx F-2B1-xx
Pacific Scientific: All Drives	PS3	CEF-RO-XXX-900X
Stober Drives: FDS/MDS 5000	SB3	Stober Absolute Encoder Cable
Siemens: 611U/Masterdrives/SMC20	SM2 SM3/SM4 SM5	6FX5002-2CF02-.... 6FX5002-2EQ10-.... 6FX5002-2CA31-....
SEW/Eurodrive: All Drives	SW1 SW3	CMP Series Resolver Cable CMP Series Absolute Encoder Cable
Yaskawa: Sigma II Series	YS2/YS3	JZSP-CMP02-XX(B)

Manufacturers Power/Brake Cables

Models:		GSM/GSX20, GSM/GSX30, SLM/SLG060, SLM/SLG090		
Amplifier/Drive Selected	Feedback Selected	Power only 4 wire	Power + Brake/Therm	Brake Cable
Allen-Bradley/Rockwell: Ultra 3000/5000/Kinetix 6000	AB8/AB9/ABB	2090-CPWM7DF-16Axyy	2090-CPBM7DF-16Axyy	N/A
AMKASYN: All Drives	AK1/AK2	N/A	DS Series Power Cable Size 1	N/A
Beckhoff: All Drives	BE1	N/A	ZK4000-2xx1-2xxxx	N/A
B&R Automation: All Drives	BR1/BR2	N/A	8CMxxx.12-1	N/A
Emerson/Control Techniques: All Drives	CT1/CT3/CT4/CT5/CT7 CT2/EM2/EM5	PSBxA CMDS	PBBxA N/A	N/A CBMS
Elau: All Drives	EU1/EU4	N/A	E-MO-111	N/A
G&L Motion Control/ Danaher Motion: MMC Smart Drive/ Digital MMC Control	GL1 GL2 GL3 GL4	PWR-H&F...16AA N/A PWR-NSM...16AA N/A	N/A PWR-L&M...16-64 N/A PWR-AKM...16-64	Exlar CBL-ASSY1-xxA-xxx N/A Exlar CBL-ASSY1-xxA-xxx N/A
Indramat/Bosch-Rexroth: DKC Series/DIAX IndraDrive	IN1/IN5/IN6 IN7	N/A N/A	MKD/MHD Power Cable Size 1 MSK Power Cable Size 1	N/A N/A
Jetter Technologies: All Drives	JT1	N/A	JH/JL Power Cable Size 1 #24.1	N/A
Kollmorgen/Danaher: All Drives	KM4/KM5/KM6	N/A	AKM Power Cable Size 1	N/A
Lenze/AC Tech: All Drives	LZ1/LZ5/LZ6	N/A	MCS Power Cable Size 1	N/A
Mitsubishi: MR-J3	MT1	MR-J3P2-xM	N/A	MR-J3BRKS1-xM
Momentum: All Drives	MN1/MN2/MN3/MN4	PCBL1.5-MNT-xxx	PCBL1.5-MNB-xxx	N/A
Ormec: All Drives	OR2		Consult Exlar	
Parker Compumotor: All Drives	PC6/PC7 PC8/PC9/PC0	N/A N/A	SMH Power Cable Size 1 P-3B1-xx	N/A N/A
Pacific Scientific: All Drives	PS3	N/A	PMA Power Cable Size 1	N/A
Stober Drives: FDS/MDS 5000	SB3	N/A	Stober Power Cable Size 1	N/A
Siemens: All Drives with flying leads	SM2/SM3/SM4/SM5		6FX5002-5DA01-....	N/A
SEW/Eurodrive: All Drives	SW1/SW3	N/A	CMP Power Cable Size 1	N/A
Yaskawa: Sigma II Series	YS2 YS3	N/A B1E-xxA	N/A B1BE-xxA	N/A N/A

Manufacturers Power/Brake Cables

GSM/GSX40, GSX50, SLM/SLG115, SLM142			GSX60 & SLM180		
Power only 4 wire	Power + Brake/Therm	Brake Cable	Power only 4 wire	Power + Brake/Therm	Brake Cable
2090-CPWM7DF-14Axyy	2090-CPBM7DF-14Axyy	N/A	2090-CPWM7DF-10Axyy	2090-CPBM7DF-10Axyy	N/A
N/A	DS Series Power Cable Size 1	N/A	N/A	DS Series Power Cable Size 1.5	N/A
N/A	ZK4000-2xx1-2xxxx	N/A	N/A	Exlar CBL-PWRB3-xxl-xxx	N/A
N/A	8CMxxx.12-3	N/A	N/A	8CMxxx.12-5	N/A
PSBxA CMMS	PBBxA N/A	N/A CBMS	PSBxB CMLS	PBBxB N/A	N/A CBMS
N/A	E-M0-112	N/A	N/A	E-M0-114	N/A
PWR-H&F...14-AA N/A N/A N/A	N/A PWR-L&M...14-6H N/A PWR-AKM...14-6H	Exlar CBL-ASSY1-xxA-xxx N/A N/A N/A	PWR-H&F...10-AA N/A N/A N/A	N/A PWR-L&M...12-6H N/A PWR-AKM...12-6H	Exlar CBL-ASSY1-xxA-xxx N/A N/A N/A
N/A N/A	MKD/MHD Power Cable Size 1 MSK Power Cable Size 1	N/A N/A	N/A N/A	MKD/MHD Power Cable Size 1.5 MSK Power Cable Size 1.5	N/A N/A
N/A	JH/JL Power Cable Size 1 #24.1	N/A	N/A	Exlar CBL-PWRB3-xxl-xxx	N/A
N/A	AKM Power Cable Size 1	N/A	N/A	AKM Power Cable Size 1.5	N/A
N/A	MCS Power Cable Size 1	N/A	N/A	MCS Power Cable Size 1.5	N/A
MR-J3P6-xM	N/A	MR-J3BRK51-xM	MR-J3P7-xM	N/A	MR-J3BRK51-xM
PCBL2.5-MNT-xxx	PCBL2.5-MNB-xxx	N/A	PCBL4.0-MNT-xxx	PCBL4.0-MNB-xxx	N/A
	Consult Exlar			Consult Exlar	
N/A N/A	SMH Power Cable Size 1 P-4B1-xx	N/A N/A	N/A N/A	SMH Power Cable Size 1.5 P-6B2-xx	N/A N/A
N/A	PMA Power Cable Size 1	N/A	N/A	Exlar CBL-PWRB3-xxl-xxx	N/A
N/A	Stober Power Cable Size 1	N/A	N/A	Stober Power Cable Size 1.5	N/A
	6FX5002-5DA11-....	N/A		6FX5002-5DA61-....	N/A
N/A	CMP Power Cable Size 1	N/A	N/A	CM Power Cable Size 1.5	N/A
B1E-xxA N/A	B1BE-xxA N/A	N/A N/A	B2E-xxA N/A	B2BE-xxA N/A	N/A N/A

(Please note, Euro style connectors are size 1.5 M40 connectors. If Manufacturer does not offer a size 1.5 M40 power cable, an Exlar Power Cable must be purchased.

Hazardous Location EL Series Linear Actuators

EL Series Explosion-Proof Linear Actuators

This electromechanical system provides process engineers a clean, fast, simple and cost effective replacement for hydraulic actuation and a longer life alternative to pneumatic actuation. The roller screw technology manufactured by Exlar outperforms rival ball screws by 15 times in travel life, and can carry higher loads. The compact design allows users to effectively replace hydraulic or air cylinders with an electromechanical actuator, yet meet all required capabilities of the application. Reduced emissions, reduced energy consumption (80% system energy efficiency), increased position control and accuracy – all leading to reduced cost – are provided by servo electric actuation.

The EL30 explosion-proof linear actuator offers CSA Class I*, Division 1, Groups B, C, D, T4 and T3A rating.

The EL100 explosion-proof linear actuator offers a Class I, Division 1, Groups B, C, D & T3 rating. The EL100 linear actuators also meet ATEX essential requirements and are in conformance with the EU ATEX Directive 94/9/EC.

The EL Series linear actuators are compatible with nearly any Manufacturers' resolver-based amplifier.

**"Class I" means that flammable gases or vapors may be present in the air in quantities sufficient to produce explosive or ignitable mixtures. "Division 1" means that hazardous concentrations in the air may exist continuously, intermittently, or periodically under normal operating conditions. "Group B" allows for atmospheres containing hydrogen, or gases (or vapors) of equivalent hazard, such as manufactured gas. "Group C" allows for atmospheres containing ethyl-ether vapors, ethylene or cyclo propane. "Group D" allows for atmospheres containing gasoline, hexane, naphtha, benzene, butane, alcohol, acetone, benzol, lacquer solvent vapors or natural gas. EL Series actuators are not rated for operation in atmospheres containing acetylene*
Temperature classification defines the maximum surface temperature the product will reach at full load. T3 = 200°C, T3A = 180°C, T4 = 135°C

EL Series explosion-proof motors are well-suited to many applications:

Turbine fuel flow	Chemical process plants
Printing presses	Fuel distribution systems
Engine test stands	Shipbound fuel management
Valve control	Damper control
Paint booths	Fuel Skids



**EL30
Explosion-Proof
Linear Actuator**

Class I, Div 1,
Groups B, C, D, T4 and T3A



II 2G
SIRA 10ATEX1037X
Ex d II B T3 Gb IP66



163694
Class I, Div 1
Group B,C,D,T3



**EL100
Explosion-Proof
Linear Actuator**

Class I, Div 1, Groups B, C, D and T3

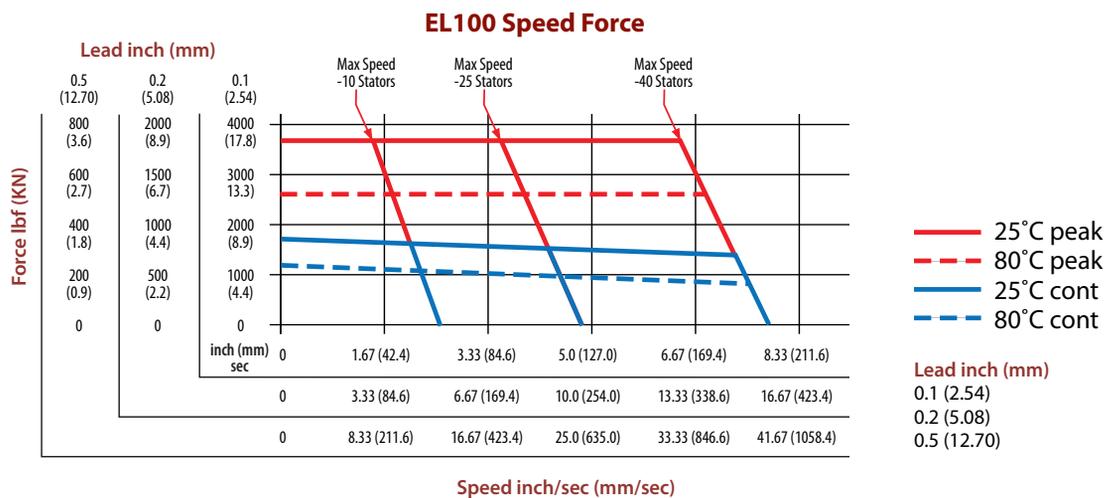
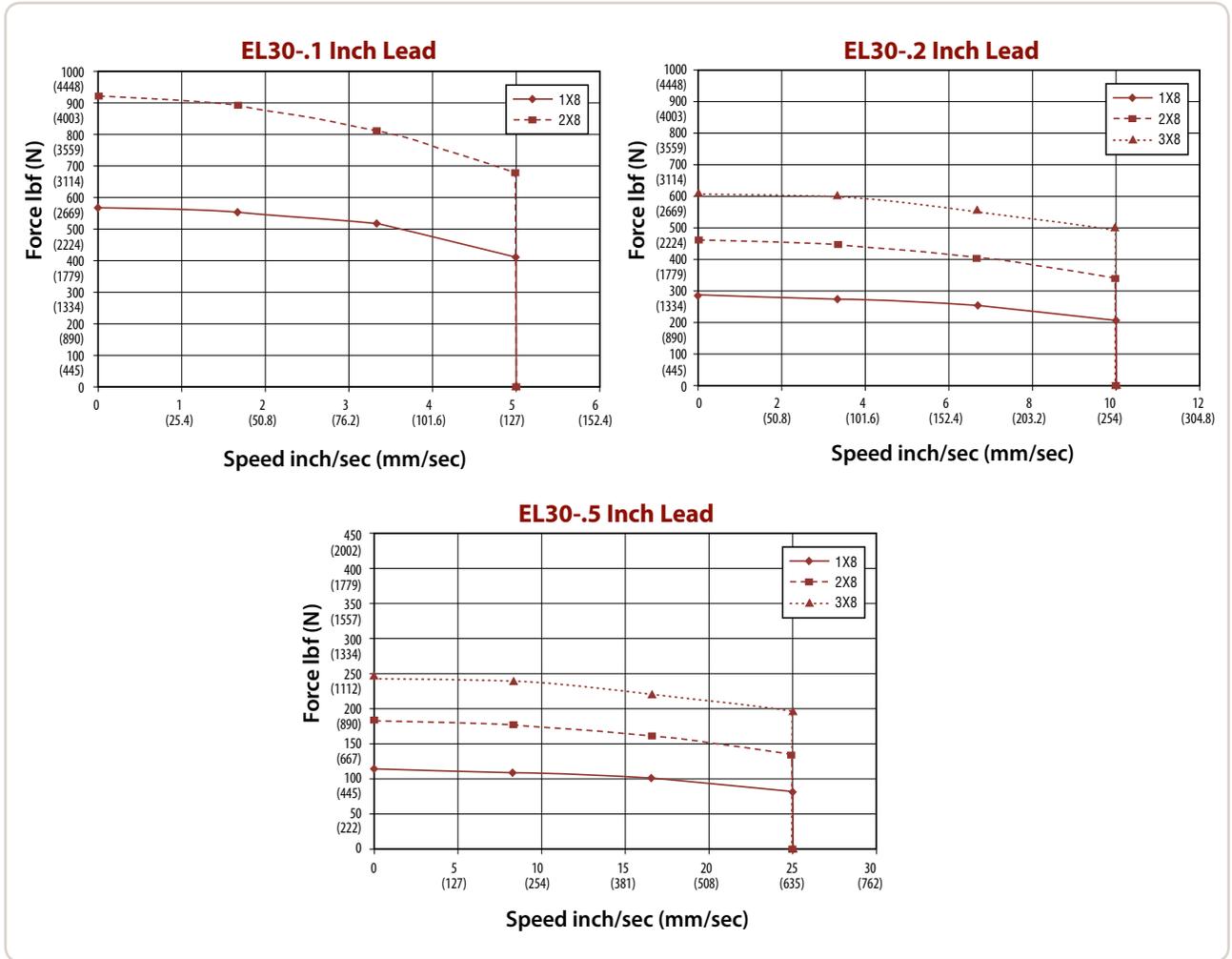
Features

- T-LAM technology yielding 35% increase in continuous motor torque over traditional windings
- Forces to 2000 lbs
- Speeds to 25 ips
- Resolver feedback
- Strokes up to 6 inches
- 8 pole motors
- Rod end options
- Several mounting configurations
- Potted NPT connectors
- Windings available from 24 VDC to 460 VAC rms
- Class 180H insulation
- IP65S Standard EL30, IP66S Standard EL100

EL Series Performance Curves

The below speed vs. force curves represent approximate continuous thrust ratings at indicated linear speed. Different types of servo amplifiers will offer varying motor

torque and thus actuator thrust. These values are at constant velocity and do not account for motor torque required for acceleration.



EL Series

Hazardous Location EL Series Linear Actuators

EL Performance Specifications

Model No.	Frame Size in (mm)	Stroke (nominal)* in (mm)	Stator	Screw Lead in (mm)	Force Rating lb (N) 1/2/3 Stack	Max Velocity in/sec (mm/sec)	Maximum Static Load lb (N)	Armature Inertia Rating** lb-in-s ² (Kg-m ²)	Dynamic Load lb (N)	Weight (approx.) lb (kg)
EL30-0301	3.125 (79.0)	3 (76)		0.1 (2.54)	543/885/NA (2415/3936/NA)	5 (127.0)	2700 (12010)	0.00319 (0.00036)	5516 (24536)	12 (5.4)
EL30-0302				0.2 (5.08)	271/442/NA (1205/1966/NA)	10 (254.0)			5800 (25798)	
EL30-0305				0.5 (12.7)	109/177/NA (485/787/NA)	25 (635.0)			4900 (21795)	
EL30-0601	3.125 (79.0)	6 (152)		0.1 (2.54)	543/885/NA (2415/3936/NA)	5 (127.0)	2700 (12010)	0.00361 (0.00041)	5516 (24536)	15 (6.8)
EL30-0602				0.2 (5.08)	271/442/626 (1205/1966/2785)	10 (254.0)			5800 (25798)	
EL30-0605				0.5 (12.7)	109/177/250 (485/787/1112)	25 (635.0)			4900 (21795)	

Model No.	Frame Size in (mm)	Stroke (nominal)* in (mm)	Stator	Screw Lead in (mm)	Force Rating lb (N) 25 °C/80 °C	Max Velocity in/sec (mm/sec)	Maximum Static Load lb (N)	Armature Inertia Rating** lb-in-s ² (Kg-m ²)	Dynamic Load lb (N)	Weight (approx.) lb (kg)	
EL100-0601	3.9 (100)	6 (152)		0.1 (2.54)	2A8-10	1,771/1,222 (7,876/5,435)	1.66 (4.16)	2700 (12010)	0.00361 (0.000408)	5516 (24536)	26.2 (11.9)
					2B8-25	1,806/1,246 (8,032/5,542)	41.66 (105.66)				
					2C8-40	1,834/1,266 (8,160/5,631)	6.66 (169.33)				
					218-40	1,989/1,373 (8,848/6,105)	6.66 (169.33)				
					238.40	2,011/1,387 (8,943/6,171)	6.66 (169.33)				
					258.40	1,986/1,371 (8,835/6,097)	6.66 (169.33)				
					268.40	2,008/1,385 (8,930/6,162)	6.66 (169.33)				
EL100-0602	3.9 (100)	6 (152)		0.2 (5.08)	2A8-10	885/611 (3,938/2,717)	3.33 (84.58)	2700 (12010)	0.00361 (0.000408)	5800 (25798)	26.2 (11.9)
					2B8-25	903/623 (4,016/2,771)	8.33 (211.58)				
					2C8-40	917/633 (4,080/2,815)	13.33 (338.58)				
					218-40	995/686 (4,424/3,053)	13.33 (338.58)				
					238.40	1,005/694 (4,472/3,086)	13.33 (338.58)				
					258.40	993/685 (4,417/3,048)	13.33 (338.58)				
					268.40	1,004/693 (4,465/3,081)	13.33 (338.58)				
EL100-0605	3.9 (100)	6 (152)		0.5 (12.70)	2A8-10	354/244 (1,575/1,087)	8.33 (211.58)	2700 (12010)	0.00361 (0.000408)	4900 (21795)	26.2 (11.9)
					2B8-25	361/249 (1,606/1,108)	20.83 (9529.08)				
					2C8-40	367/253 (1,632/1,126)	33.33 (846.58)				
					218-40	398/275 (1,770/1,221)	33.33 (846.58)				
					238.40	402/277 (1,789/1,234)	33.33 (846.58)				
					258.40	397/274 (1,767/1,219)	33.33 (846.58)				
					268.40	402/277 (1,786/1,232)	33.33 (846.58)				

* Please note that stroke mm are nominal dimensions. **Inertia +/- 5%
See page 13 for definition of terms.

Specifications subject to change without notice.

EL30 Series Mechanical/Electrical Specifications

Maximum Backlash (not preloaded)	in (mm)	0.004 (.10)																	
Maximum Backlash (preloaded)	in (mm)	0.0																	
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)																	
Maximum Radial Load	lb (N)	30 (134)																	
Environmental Rating:	Standard	IP65S																	
Motor Stator-T4 Ratings		1A8	1B8	118	138	158	168	2A8	2B8	218	238	258	268	318*	338*	358*	368*		
RMS SINUSOIDAL COMMUTATION																			
Continuous Motor Torque** (+/- 10% @ 80°C)	lbf-in (Nm)	10.8 (1.22)	10.8 (1.22)	11.1 (1.25)	11.0 (1.24)	10.7 (1.21)	10.5 (1.18)	17.4 (1.97)	17.4 (1.97)	17.7 (2.00)	17.8 (2.01)	17.5 (1.98)	17.5 (1.97)	25.2 (2.84)	24.9 (2.81)	23.6 (2.66)	22.5 (2.55)		
Torque Constant (Kt)** (+/- 10% @ 80°C)	lbf-in/ (Nm/A)	1.1 (0.13)	1.1 (0.13)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.97)	1.1 (0.13)	1.1 (0.13)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.97)	4.4 (0.50)	8.7 (0.98)	15.6 (1.77)	13.7 (1.54)		
Continuous Current Rating**	A	10.7	10.7	2.8	1.4	0.8	0.7	17.3	17.3	4.5	2.3	1.3	1.1	6.3	3.2	1.7	1.8		
Peak Current Rating	A	21.3	21.3	5.7	2.8	1.5	1.3	34.5	34.5	9.0	4.5	2.5	2.2	12.7	6.4	3.4	3.7		
0-PK SMUSOIDAL COMMUTATION																			
Continuous Motor Torque** (+/- 10% @ 80°C)	lbf-in (Nm)	10.8 (1.22)	10.8 (1.22)	11.1 (1.25)	11.0 (1.24)	10.7 (1.21)	10.5 (1.18)	17.4 (1.97)	17.4 (1.97)	17.7 (2.00)	17.8 (2.01)	17.5 (1.98)	17.5 (1.97)	25.2 (2.84)	24.9 (2.81)	23.6 (2.66)	23.6 (2.67)		
Torque Constant (Kt)** (+/- 10% @ 80°C)	lbf-in/A (Nm/A)	0.8 (0.09)	0.8 (0.09)	3.1 (0.35)	6.2 (0.70)	11.0 (1.24)	12.4 (1.40)	0.8 (0.09)	0.8 (0.09)	3.1 (0.35)	6.2 (0.70)	11.0 (1.24)	12.4 (1.40)	3.1 (0.35)	6.1 (0.69)	11.1 (1.25)	17.5 (1.98)		
Continuous Current Rating	A	15.1	15.1	4.0	2.0	1.1	0.9	24.4	24.4	6.4	3.2	1.8	1.6	9.0	4.5	2.4	1.5		
Peak Current Rating	A	30.2	30.2	8.0	4.0	2.2	1.9	48.8	48.8	12.8	6.4	3.6	3.2	17.9	9.1	4.8	3.0		
MOTOR STATOR DATA																			
Voltage Constant (Ke)** (+/- 10% @ 25°C)	Vrms/Krpm Vpk/Krpm	7.7 10.9	7.7 10.9	29.8 42.2	59.7 84.5	105.8 149.7	119.3 168.7	7.7 10.9	7.7 10.9	29.8 42.2	59.7 84.4	105.8 149.7	119.3 168.7	30.3 42.9	59.2 83.7	106.8 151.0	119.8 169.4		
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8	8	8	8	8		
Resistance (L-L)(+/- 5% @ 80°C)	Ohms	0.19	0.19	2.7	10.8	36.3	47.9	0.08	0.08	1.1	4.4	14.1	18.0	0.65	2.6	9.3	11.6		
Inductance (L-L)(+/- 5%)	mH	0.51	0.51	7.7	30.7	96.8	123.0	0.24	0.24	3.7	14.7	46.2	58.7	2.5	9.5	30.9	38.8		
Electrical Time Constant (te)	ms	2.7	2.7	2.9	2.8	2.7	2.6	3.2	3.2	3.3	3.4	3.3	3.3	3.8	3.7	3.3	3.3		
Friction Torque	lbf-in (Nm)	1.46 (0.17)						1.60 (0.18)						1.80 (0.20)					
Bus Voltage	Vrms	24VDC	48VDC	115	230	400	460	24VDC	48VDC	115	230	400	460	115	230	400	460		
Speed @ Bus Voltage	rpm	1500	3000	3000	3000	3000	3000	1500	3000	3000	3000	3000	3000	3000	3000	3000	3000		
Insulation Class		180 (H)																	
Temperature Class	°C							T4 = 135°C						T3A = 180°C					
Connectors		Potted NPT Connectors Only																	

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414. Specifications reflect 80°C test environment

Specifications subject to change without notice.

*Not available with 3" stroke

**For T3A Temperature Class multiply Kt & Ke ratings by 0.83; Continuous Current by 1.245; Continuous Torque by 1.095

Hazardous Location EL Series Linear Actuators

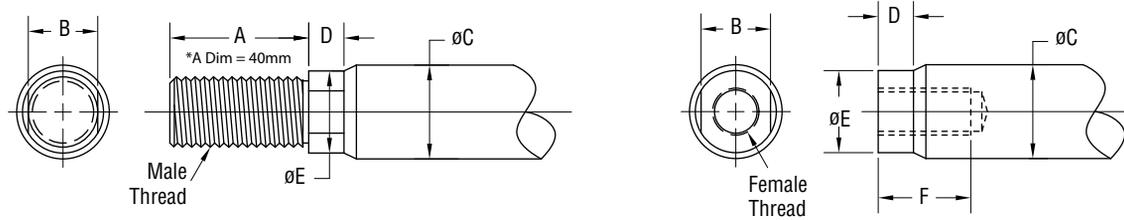
EL100 Series Mechanical/Electrical Specifications

Nominal Backlash	in (mm)	0.004 (.10)						
Maximum Backlash (preloaded)	in (mm)	0.0						
Lead Accuracy in/ft	(mm/300 mm)	0.001 (.025)						
Maximum Radial Load	lb (N)	40 (179)						
Environmental Rating	Standard	IP66S						
Motor Stator Ambient Temperature		2A8-10 25°/80° C	2B8-25 25°/80° C	2C8-40 25°/80° C	218-40 25°/80° C	238-40 25°/80° C	258-40 25°/80° C	268-40 25°/80° C
RMS SINUSOIDAL COMMUTATION DATA								
Continuous Motor Torque	lbf-in (N-m)	35.2/24.3 (3.98/2.75)	35.9/24.8 (4.06/2.80)	36.5/25.2 (4.12/2.85)	39.6/27.3 (4.47/3.09)	40.0/27.6 (4.52/3.12)	39.5/27.3 (4.46/3.08)	39.9/27.6 (4.51/3.11)
Torque Constant	lbf-in/A (N-m/A)	1.7/1.7 (0.19/0.19)	1.7/1.7 (0.19/0.19)	2.6/2.6 (0.30/0.30)	3.2/3.2 (0.37/0.37)	6.6/6.6 (0.75/0.75)	11.6/11.6 (1.31/1.31)	13.2/13.2 (1.50/1.50)
Continuous Current Rating	Greased (IG) A	23.1/15.9	23.6/16.3	15.6/10.7	13.6/9.4	6.8/4.7	3.8/2.6	3.4/2.3
Peak Current Rating	A	46.2/31.9	47.1/32.5	31.1/21.5	27.3/18.8	13.5/9.3	7.6/5.3	6.7/4.7
0-PK SMUSOIDAL COMMUTATION DATA								
Continuous Motor Torque	lbf-in (N-m)	35.2/24.3 (3.98/2.75)	35.9/24.8 (4.06/2.80)	36.5/25.2 (4.12/2.85)	39.6/27.3 (4.47/3.09)	40.0/27.6 (4.52/3.12)	39.5/27.3 (4.46/3.08)	39.9/27.6 (4.51/3.11)
Torque Constant	lbf-in/A (N-m/A)	1.2/1.2 (0.14/0.14)	1.2/1.2 (0.14/0.14)	1.9/1.9 (0.21/0.21)	2.3/2.3 (0.26/0.26)	4.7/4.7 (0.53/0.53)	8.2/8.2 (0.92/0.92)	9.4/9.4 (1.06/1.06)
Continuous Current Rating	Greased (IG) A	32.7/22.6	33.3/23.0	22.0/15.2	19.3/13.3	9.5/6.6	5.4/3.7	4.8/3.3
Peak Current Rating	A	65.4/45.1	66.7/46.0	44.0/30.4	38.6/26.6	19.1/13.2	10.8/7.5	9.5/6.6
MOTOR STATOR DATA								
Voltage Constant @ 25° C (Ke)	Vrms/Krpm	11.6/11.6	11.6/11.6	17.9/17.9	22.1/22.1	45.2/45.2	78.9/78.9	90.4/90.4
	Vpk/Krpm	16.5/16.5	16.5/16.5	25.3/25.3	31.3/31.3	64.0/64.0	111.6/111.6	127.9/127.9
Pole Configuration		8	8	8	8	8	8	8
Resistance (L-L)	Ohms	0.10/0.10	0.1/0.1	0.2/0.2	0.30/0.30	1.2/1.2	3.8/3.8	4.86/4.86
Inductance (L-L)	mH	0.75/0.75	0.8/0.8	1.9/1.9	2.93/2.93	12.2/12.2	37.2/37.2	48.9/48.9
Brake Inertia	lbf-in-sec ² (kg-cm ²)	0.00047 (.53)						
Brake Current @24 VDC +/- 10%	A	0.5						
Brake Holding Torque - Dry	lbf-in (Nm/A)	70 (8)						
Brake Engage/Disengage Time	ms	25/50						
Mechanical Time Constant (tm)	ms	1.4/1.4	1.3/1.3	1.3/1.3	1.1/1.1	1.1/1.1	1.1/1.1	1.1/1.1
Electrical Time Constant (te)	ms	7.2/7.2	7.9/7.9	8.2/8.2	9.9/9.9	10.1/10.1	9.9/9.9	10.1/10.1
Frictional Torque	lbf-in (N-m)	2.22/2.22 (0.25/0.25)	2.22/2.22 (0.25/0.25)	2.22/2.22 (0.25/0.25)	2.22/2.22 (0.25/0.25)	2.22/2.22 (0.25/0.25)	2.22/2.22 (0.25/0.25)	2.22/2.22 (0.25/0.25)
Bus Voltage	Vrms	24 VDC/24 VDC	48 VDC/48 VDC	120 VDC/120 VDC	115 VAC/115 VDC	230 VAC/230 VDC	400 VAC/400 VDC	460 VAC/460 VDC
Speed @ Bus Voltage	rpm	1,000	2,500	4,000	4,000	4,000	4,000	4,000
Insulation Class		180 (H)						
Ambient Temperature Rating		-29° C to 93° C						
CSA/ATEX Temperature Class		T3, 200° C Maximum Allowable Surface Temperature						

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by 0.707, and peak current by 1.414.
All temperature ratings ambient.

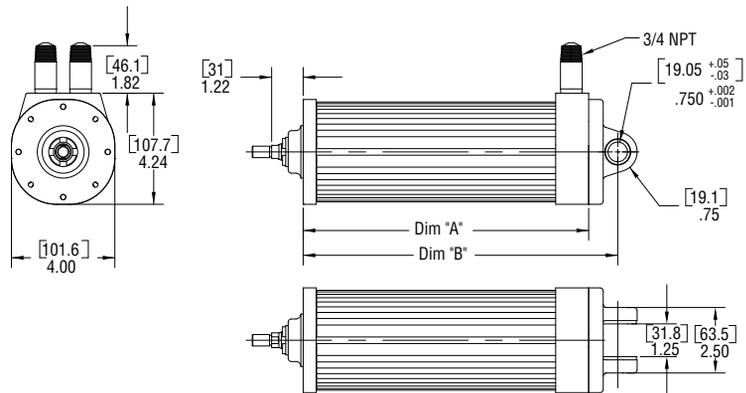
Specifications subject to change without notice.

Actuator Rod End Options

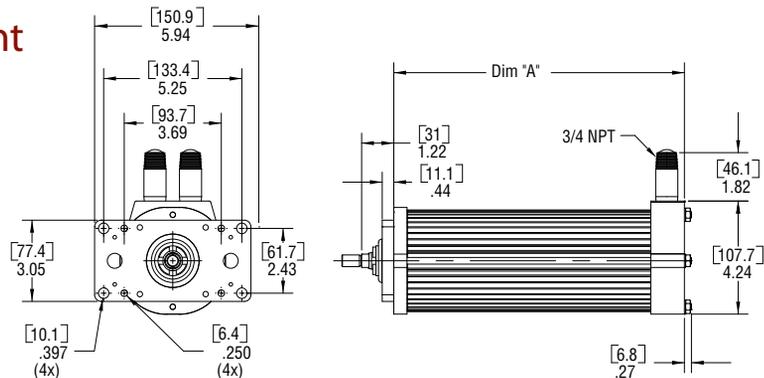


	A	B	øC	D	øE	F	Male U.S.	Male Metric	Female U.S.	Female Metric
EL30 in (mm)	0.750 (19.1)	0.500 (12.7)	0.625 (15.9)	0.281 (7.1)	0.562 (14.3)	0.750 (19.1)	7/16 - 20 UNF - 2A	M12 x 1.75* 6g	7/16 - 20 UNF - 2B	M10 x 1.5 6h

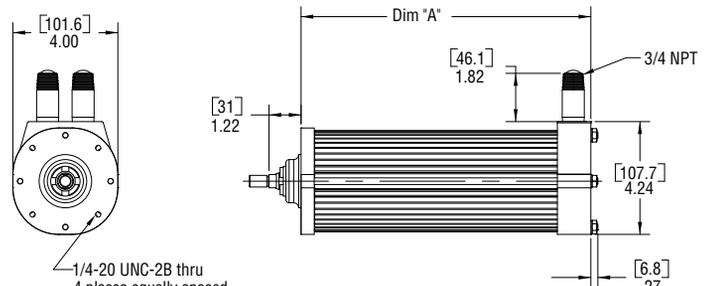
EL30 Clevis Mount



EL30 Front Flange Mount



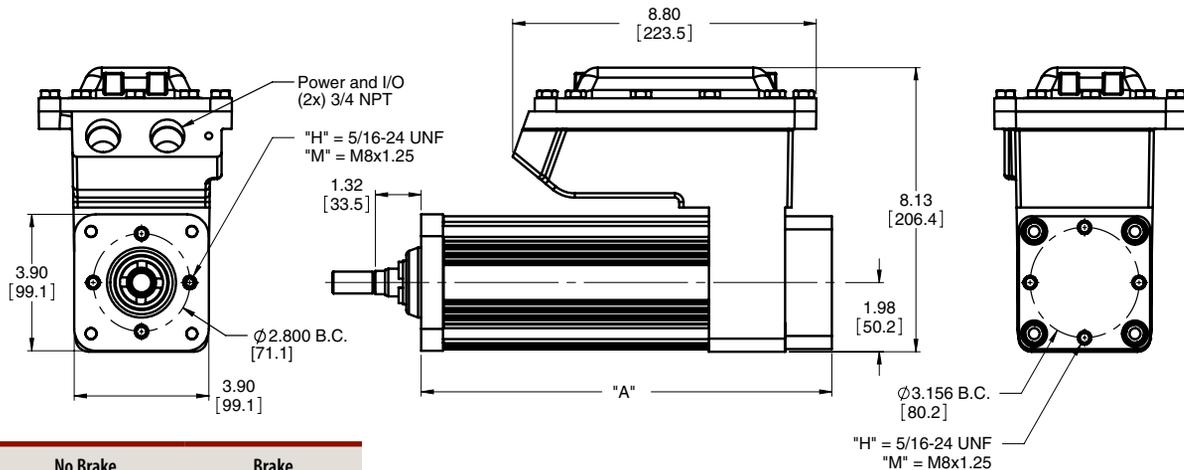
EL30 Base Unit



Dim	3" (76.2 mm) Stroke	6" (152.4 mm) Stroke
A	8.6 (218)	11.0 (281)
B	9.7 (246)	12.2 (309)

Hazardous Location EL Series Linear Actuators

EL100 Dimensions



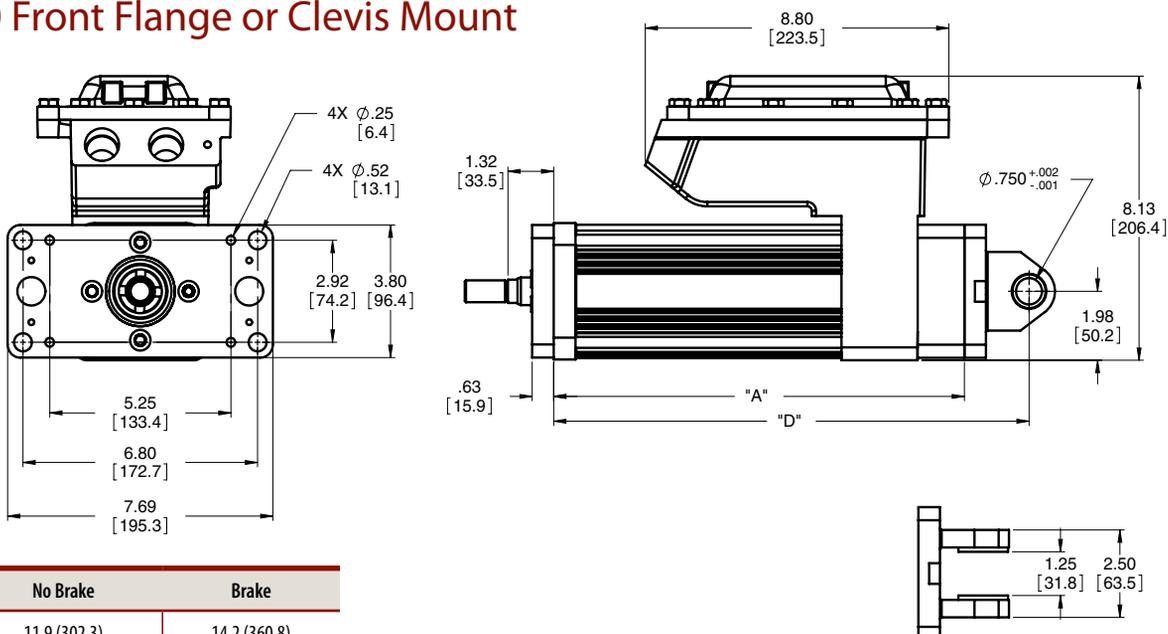
Dim	No Brake	Brake
A	11.9 (302.3)	14.2 (360.8)

EL100 Actuator Rod End Options



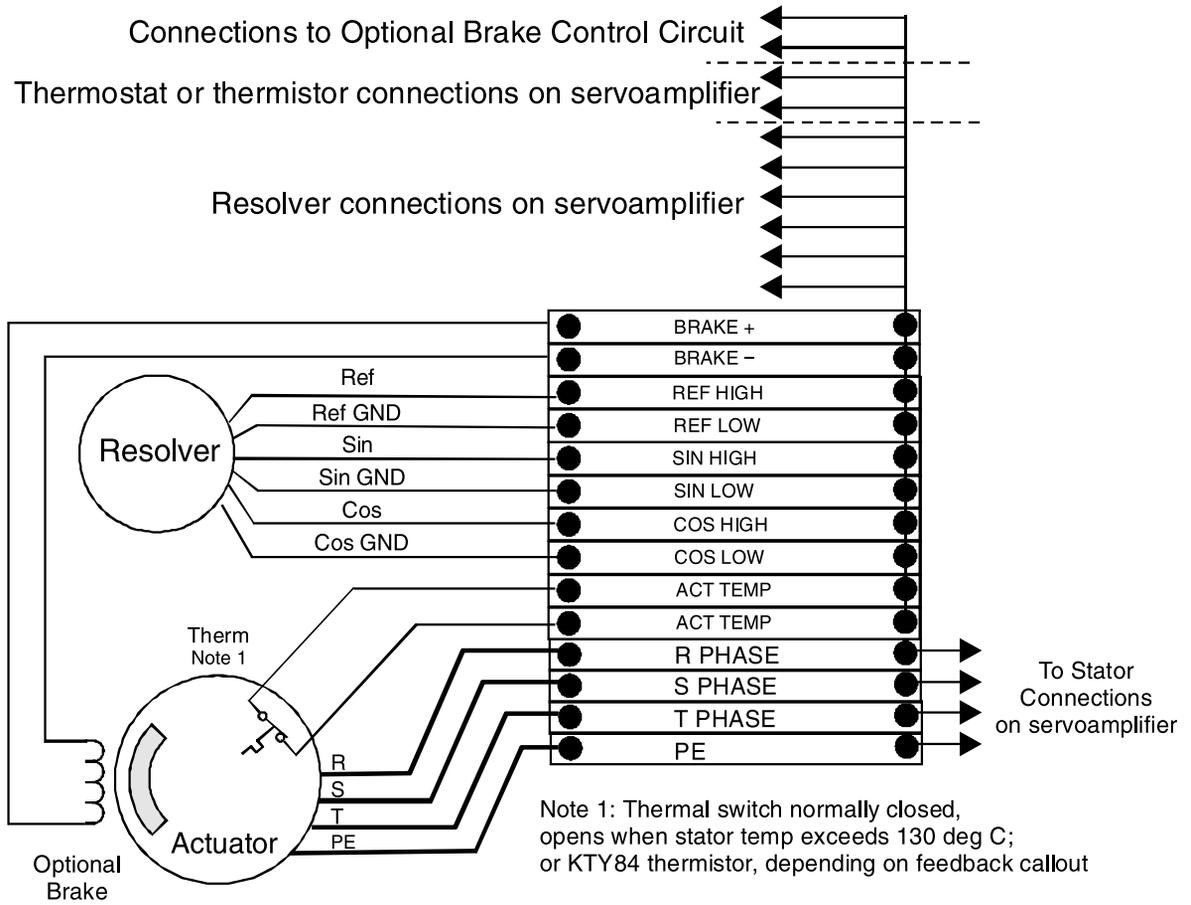
	A	B	ØC	D	ØE	F	Male "M" Inch	Male "A" Metric	Female "F" Inch	Female "B" Metric
EL100 in (mm)	1.250 (31.8)	0.625 (17.0)	0.787 (20.0)	0.281 (7.1)	0.725 (18.4)	1.000 (25.4)	1/2 - 20 UNF - 2A	M16 x 1.5 6g	1/2 - 20 UNF - 2B	M16 x 1.5 6h

EL100 Front Flange or Clevis Mount



Dim	No Brake	Brake
A	11.9 (302.3)	14.2 (360.8)
D	13.77 (349.9)	16.7 (408.2)

EL100 Terminal Box Wiring



EL30 = Model Series

AA = Frame Size

30 = 3 inch (80 mm) nominal

BB = Nominal Stroke Length

03 = 3 inch (76 mm) stroke

06 = 6 inch (152 mm) stroke

XX = Special stroke not to exceed 6 inch (152 mm)

CC = Screw Lead

01 = 0.1 inch lead

02 = 0.2 inch lead

05 = 0.5 inch lead

XX = Special

DDD = Connector Options

N## = Potted NPT with flying leads

= Length of flying leads in feet (not to exceed 99') Contact your local sales representative if longer length is needed.

E = Mounting Options

F = Front Flange

C = Rear Clevis

H = Threaded Face

X = Special Mounting

F = Rod Ends

M = Male, US std thread

A = Male, Metric std thread

F = Female, US std thread

B = Female, Metric std thread

GGG = FeedbackType

(Also specify the Amplifier/Drive Model being used when ordering) -- Standard Resolver
-- Size 15 1024 line (2068 cts) per rev, two phase resolver

XX1 = Custom Feedback -- Wiring and feedback device information must be provided and new feedback callout will be created -- contact your local sales representative. Resolver only.

AB6 = Allen-Bradley/Rockwell
-- Standard Resolver

AM3 = Advanced Motion Control -- Standard Resolver

AP1 = API Controls -- Standard Resolver

BD2 = Baldor -- Standard Resolver

BM2 = Baumuller -- Standard Resolver

BR1 = B&R Automation -- Standard Resolver

CO2 = Copley Controls -- Standard Resolver

CT5 = Standard Resolver -- FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

DT2 = Delta Tau Data Systems
-- Standard Resolver

EL1 = Elmo Motion Control
-- Standard Resolver

EX4 = Exlar -- Standard Resolver

IF1 = Infranor -- Standard Resolver

IN6 = Indramat/Bosch-Rexroth
-- Standard Resolver

JT1 = Jetter Technologies
-- Standard Resolver

KM5 = Kollmorgen/Danaher
-- Standard Resolver

LZ5 = Lenze/AC Tech -- Standard Resolver

MD1 = Modicon -- Standard Resolver

MG1 = Moog -- Standard Resolver

MN4 = Momentum -- Standard Resolver

MX1 = Metronix -- Standard Resolver

OR1 = Ormec -- Standard Resolver

PC7 = Parker -- Standard Resolver
-- European only

PC0 = Parker -- Standard Resolver -- US Only

PS3 = Pacific Scientific -- Standard Resolver

SM2 = Siemens -- Standard Resolver

SW1 = SEW/Eurodrive -- Standard Resolver

WD1 = Whedco/Fanuc -- Standard Resolver

HHH = Motor Stator all 8 pole

1A8 = 1 stack, 24 Vrms

218 = 2 stack, 115 Vrms

1B8 = 1 stack, 48 Vrms

238 = 2 stack, 230 Vrms

118 = 1 stack, 115 Vrms

258 = 2 stack, 400 Vrms

138 = 1 stack, 230 Vrms

268 = 2 stack, 460 Vrms

158 = 1 stack, 400 Vrms

318 = 3 stack, 115 Vrms²

168 = 1 stack, 460 Vrms

338 = 3 stack, 230 Vrms²

2A8 = 2 stack, 24 Vrms

358 = 3 stack, 400 Vrms²

2B8 = 2 stack, 48 Vrms

368 = 3 stack, 460 Vrms²

II = Motor Speed

01-99 = Two digit number - rated speed in rpm x 100

JJJ = Hazardous Location Temperature Rating

T3A = 180° C (Samarium Cobalt magnets)

T4 = 135° C (Neodymium-Iron-Boron magnets)

XX = Optional Speed & Mechanical

Designations -- Multiples possible

XL = Special Lubrication

PF = Preloaded follower¹

XT = Special travel option

= Part No. Designator for Specials

Optional 5 digit assigned part number to designate unique model numbers for specials.

Notes:

- The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw.
- Not available with 3" stroke.

EL100 = Model Series

CC = Stroke Length

06 = 5.9 inch (150 mm)

DD = Roller Screw Lead (Linear Travel per Screw Revolution)

01 = 0.1 in/rev (2.54 mm/rev)

02 = 0.2 in/rev (5.08 mm/rev)

05 = 0.5 in/rev (12.7 mm/rev)

XX = Special Lead

E = Connections

S = Terminal strips with 3/4" NPT port access, single row

F = Mounting

H = Threaded front and rear face, US standard thread

N = Threaded front and rear face, metric thread

B = Front and rear flange

F = Standard front flange

C = Standard rear clevis

R = Rear flange

X = Special flange, clevis or threaded face mount

G = Rod End

M = Male, US standard thread

A = Male, metric thread

F = Female, US standard thread

B = Female, metric thread

W = Male, US standard thread 17-4 SS

R = Male, metric thread 17-4 SS

V = Female, US standard thread 17-4 SS

L = Female, metric thread 17-4 SS

X = Special rod end (consult Exlar)

HHH = Controller Feedback Option

XX1 = Custom Feedback. Resolver only. Consult Exlar

AB6 = Allen-Bradley/Rockwell - standard resolver

AM3 = Advanced Motion Control - standard resolver

AP1 = API Controls - standard resolver

BD2 = Baldor - standard resolver

BM2 = Baumuller - standard resolver

BR1 = B&R Automation

CT5 = Control Techniques - standard resolver

CO2 = Copely Controls - standard resolver

DT2 = Delta Tau Data Systems - standard resolver

EL1 = Elmo Motion Control - standard resolver

EX4 = Exlar - standard resolver

IF1 = Infranor - standard resolver

IN6 = Indramat/Bosch-Rexroth - standard resolver

JT1 = Jetter Technologies - standard resolver

KM5 = Kollmorgen/Danaher - standard resolver

LZ5 = Lenze/AC Tech - standard resolver

MD1 = Modicon - standard resolver

MG1 = Moog - standard resolver

MN4 = Momentum - Standard Resolver

MX1 = Metronix - standard resolver

OR1 = Ormec - standard resolver

PC7 = Parker - standard resolver

- European only

PC0 = Parker - standard resolver - US only

PS3 = Pacific Scientific - standard resolver

SM2 = Siemens - standard resolver

SW1 = SEW/Eurodrive - standard resolver

WD1 = Whedco/Fanuc - standard resolver

I = Motor Stacks

2 = 2 stack motor

J = Rated Voltage

A = 24 VDC

B = 48 VDC

C = 120 VDC

1 = 115 Volt RMS

3 = 230 Volt RMS

5 = 400 Volt RMS

6 = 460 Volt RMS

X = Special voltage rating - not to exceed 460 Volt RMS

K = Motor Poles

8 = 8 Pole Motor

LL = Rated Motor Speed at Rated Voltage

01 - 99 = Two digit number x 100 = rated RPM

MM = Mechanical Option (Multiple options may apply - separated by "-")

XL = Special lubrication, Mobilgrease 28 or other (please specify)

PF = Pre-loaded roller screw follower¹

AR = External anti-rotate assembly (requires flange mount option)

RB = Rear brake

XT = Special housing option (see options below)

Hard anodized aluminum motor housing parts

Epoxy coated terminal housing

(casting)

NN = Haz Loc Temp Rating

T3 = 200° C max allowable surface temperature

= Part No. Designator for Specials

Optional 5 digit assigned part number to designate unique model numbers for specials.

Notes:

- The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw.

ER Series Explosion-Proof Rotary Motor and Gearmotor

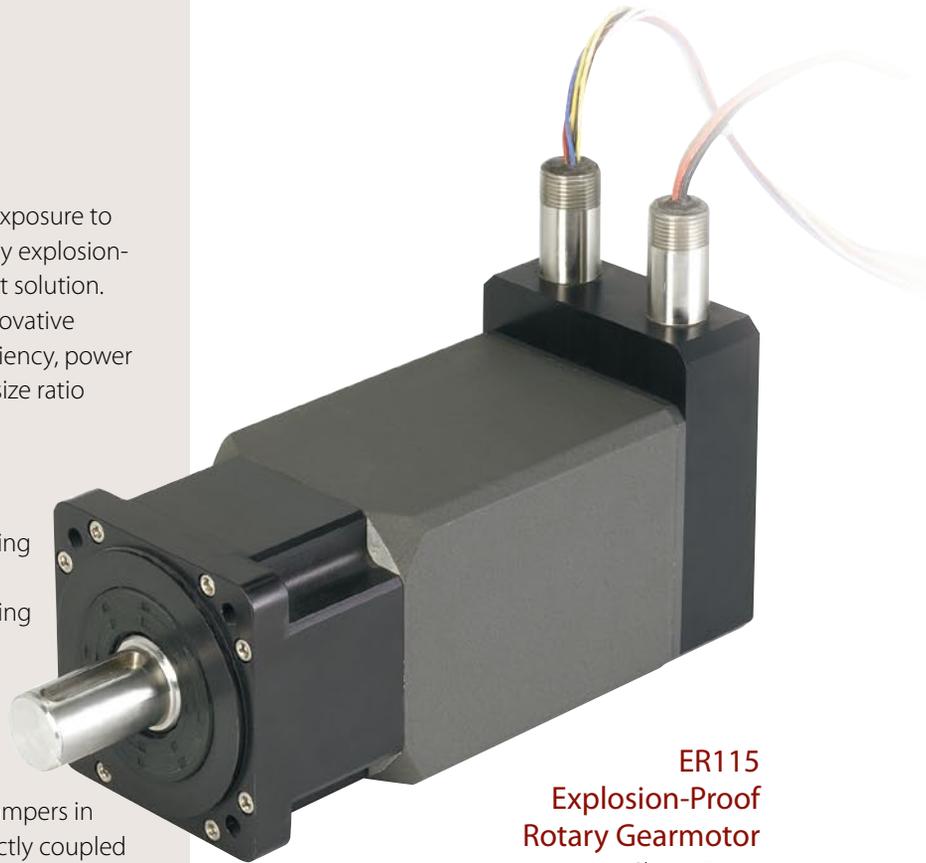
For hazardous duty environments with constant exposure to flammable gasses or vapors* Exlar's ER Series rotary explosion-proof motors and gearmotors provide an excellent solution. Exlar's motors utilizing T-LAM™ technology, an innovative segmented winding, have been designed for efficiency, power and durability and provide a very high torque-to-size ratio when compared to other suppliers' motors.

The gearmotor comprises a brushless permanent magnet motor optimized for use with an integral planetary gear set. Through the uniform load sharing of several gears acting in concert, planetary gear heads are a very compact, reliable solution providing high torque, low backlash and low maintenance.

The ER Series motors are compatible with nearly any manufacturers' resolver-based amplifier.

The ER Series actuators are ideal for operating quarter turn or multi turn valves or shaft driven dampers in hazardous environments. These actuators are directly coupled shaft-to-shaft, eliminating ungainly mechanisms needed by the linear motion of pneumatics. Our compact T-LAM™ servo motors outperform any standard motor, providing excellent continuous modulating service.

** ER Series motors are rated for Class I, Div 1, Groups B, C and D. "Class I" means that flammable gasses or vapors may be present in the air in quantities sufficient to produce explosive or ignitable mixtures. "Division 1" means that hazardous concentrations in the air may exist continuously, intermittently, or periodically under normal operating conditions. "Group B" allows for atmospheres containing hydrogen, or gasses (or vapors) of equivalent hazard, such as manufactured gas. "Group C" allows for atmospheres containing ethyl-ether vapors, ethylene or cyclo propane. "Group D" allows for atmospheres containing gasoline, hexane, naphtha, benzene, butane, alcohol, acetone, benzol, lacquer solvent vapors or natural gas. ER Series motors are not rated for operation in atmospheres containing acetylene.*



**ER115
Explosion-Proof
Rotary Gearmotor**
Class I, Div 1,
Groups B, C, D, T4, or T3B

Features

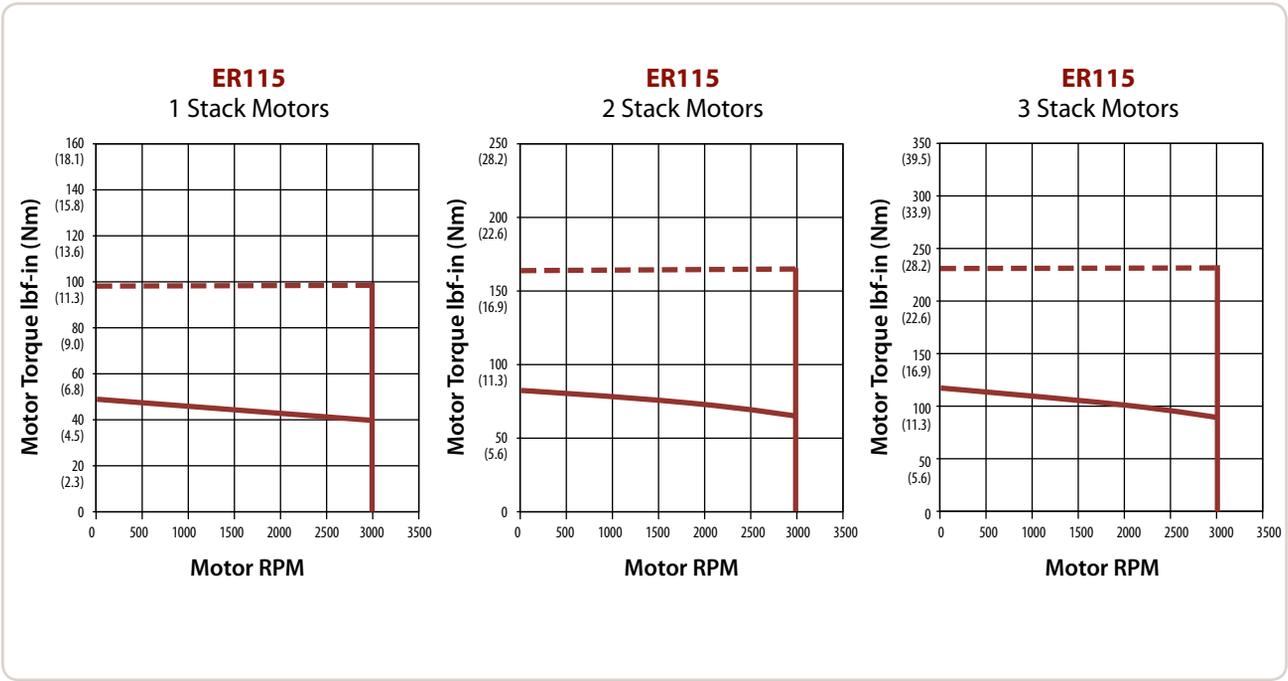
- T-LAM technology yielding 35% increase in continuous motor torque over traditional windings
- Resolver feedback
- 8 pole motors
- Rod end options
- 1, 2, or 3 stack motor availability compatible with nearly any resolver based servo amplifier
- Several mounting configurations
- Potted NPT leads
- Windings from 24 VDC to 460 VAC rms
- Class 180H insulation system
- IP65S rating

ER Series explosion-proof motors are well-suited to many applications:

- | | |
|--------------------|---------------------------|
| Turbine fuel flow | Chemical process plants |
| Printing presses | Fuel distribution systems |
| Engine test stands | Shipbound fuel management |
| Valve control | Paint booths |
| Damper control | Fuel Skids |

ER Speed/Torque Curves

----- Peak Torque
 ——— Continuous Torque
 Torque Rated at 80°C



Hazardous Location ER Series Motors

ER115 Electrical/Mechanical Specifications

Sinusoidal Commutation Data		1A8	1B8	118	138	158	168	2A8	2B8	238	258	268	338	358	368	
Continuous Motor Torque**	lbf-in (Nm)	49.6 (5.60)	49.6 (5.60)	50.4 (5.69)	50.4 (5.69)	50.5 (5.71)	50.4 (5.69)	83.1 (9.39)	83.1 (9.39)	83.9 (9.47)	82.4 (9.31)	83.9 (9.47)	117.1 (13.23)	117.4 (13.27)	120.2 (13.58)	
Peak Motor Torque	lbf-in (Nm)	99.1 (11.20)	99.1 (11.20)	100.8 (11.39)	100.8 (11.39)	101.1 (11.42)	100.8 (11.38)	166.3 (18.79)	166.3 (18.79)	167.7 (18.95)	164.7 (18.61)	167.7 (18.95)	234.2 (26.46)	234.8 (26.53)	240.4 (27.16)	
Torque Constant (Kt)**	lbf-in/A	5.3	5.3	4.3	8.7	15.7	17.3	5.3	5.3	8.7	15.8	17.3	8.5	15.8	17.5	
(+/- 10% @ 80°C)	(Nm/A)	0.60	0.6	0.5	1.0	1.8	2.0	0.6	0.6	1.0	1.8	2.0	1.0	1.8	2.0	
Continuous Current Rating	A	10.5	10.5	13.0	6.5	3.6	3.2	17.6	17.6	10.8	5.8	5.4	15.4	8.3	7.7	
Peak Current Rating	A	21.0	21.0	26.0	13.0	7.2	6.5	35.2	35.2	21.6	11.6	10.8	30.8	16.6	15.3	
O-PK SINUSOIDAL COMMUTATION DATA																
Continuous Motor Torque**	lbf-in (Nm)	49.6 (5.60)	49.6 (5.60)	50.4 (5.69)	50.4 (5.69)	50.5 (5.71)	50.4 (5.69)	83.1 (9.39)	83.1 (9.39)	83.9 (9.47)	82.4 (9.31)	83.9 (9.47)	117.1 (13.23)	117.4 (13.27)	120.2 (13.58)	
Peak Motor Torque	lbf-in (Nm)	99.1 (11.20)	99.1 (11.20)	100.8 (11.39)	100.8 (11.39)	101.1 (11.42)	100.8 (11.38)	166.3 (18.79)	166.3 (18.79)	167.7 (18.95)	164.7 (18.61)	167.7 (18.95)	234.2 (26.46)	234.8 (26.53)	240.4 (27.16)	
Torque Constant (Kt) (+/- 10% @ 80°C)	lbf-in/A (Nm/A)	3.7 (0.42)	3.7 (0.4)	3.1 (0.3)	6.1 (0.7)	11.1 (1.3)	12.3 (1.4)	3.7 (0.4)	3.7 (0.4)	6.1 (0.7)	11.2 (1.3)	12.3 (1.4)	6.0 (0.7)	11.2 (1.3)	12.4 (1.4)	
Continuous Current Rating	A	14.8	14.8	18.4	9.2	5.1	4.6	24.9	24.9	15.3	8.2	7.6	21.8	11.7	10.8	
Peak Current Rating	A	29.7	29.7	36.7	18.4	10.2	9.2	49.8	49.8	30.6	16.4	15.3	43.6	23.4	21.7	
MOTOR DATA																
Voltage Constant (Ke)**	Vpk/Krpm	36.1	36.1	29.6	59.2	106.9	118.5	36.1	36.1	59.2	108.2	118.5	58.0	108.2	119.8	
(+/- 10% @ 80°C)	Vrms/Krpm	51.1	51.0	41.9	83.8	151.2	167.6	51.0	51.0	83.8	153.0	167.6	82.0	153.0	169.4	
Pole Configuration		8	8	8	8	8	8	8	8	8	8	8	8	8	8	
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	0.31	0.31	0.20	0.80	2.60	3.21	0.127	0.13	0.34	1.17	1.35	0.20	0.69	0.81	
Inductance (L-L)(+/- 15%)	mH	4.8	4.8	3.3	13.0	42.4	52.1	2.3	2.3	6.3	21.1	25.3	4.0	13.9	17.1	
Armature Inertia	lb-in-sec ² (Kg-cm ²)	0.00555 (6.27)						0.00833 (9.42)					0.01112 (12.56)			
Mechanical Time Constant (tm)	ms	0.94	0.94	0.91	0.91	0.90	0.91	0.58	0.58	0.57	0.59	0.57	0.47	0.47	0.45	
Electrical Time Constant (te)	ms	15.73	15.73	16.26	16.26	16.34	16.25	18.41	18.41	18.72	18.06	18.72	20.08	20.19	21.16	
Friction Torque	lbf-in (Nm)	1.39 (0.16)	1.39 (0.157)	1.39 (0.157)	1.39 (0.157)	1.39 (0.157)	1.39 (0.157)	1.75 (0.197)	1.75 (0.197)	1.75 (0.197)	1.75 (0.197)	1.75 (0.197)	2.25 (0.254)	2.25 (0.254)	2.25 (0.25)	
Bus Voltage	Vrms	24VDC	48VDC	115	230	400	460	24VDC	48VDC	230	400	460	230	400	460	
Speed @ Bus Voltage	rpm	300	750	3000	3000	3000	3000	300	750	3000	3000	3000	3000	3000	3000	
Insulation Class		180 (H)														
Insulation System Volt Rating	Vrms	460														
Class Temperature	°C	T4 = 135° T3B = 180°														
Environmental Rating		IP65S														

ER115 Gearmotor Data

	1 Stack Motor	2 Stack Motor	3 Stack Motor
ER115 Armature Inertia* lbf-in-sec ² (Kg-cm ²)	0.00344 (3.89)	0.00441 (4.99)	0.00538 (6.08)

For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.

GEARING REFLECTED INERTIA	SINGLE REDUCTION			DOUBLE REDUCTION		
	Gear Stages	lbf-in-sec ²	(Kg-cm ²)	Gear Stages	lbf-in-sec ²	(Kg-cm ²)
	4:1	0.0000132	(0.0149)	16:1	0.0000121	(0.0137)
	5:1	0.0000087	(0.00984)	20:1, 25:1	0.0000080	(0.00906)
	10:1	0.0000023	(0.00261)	40:1, 50:1, 100:1	0.0000021	(0.00242)
Backlash at 1% rated torque:	10 Arc minutes Efficiency: Single reduction 91%			13 Arc minutes Double Reduction: 86%		

* Add armature inertia to gearing inertia for total ER system inertia

** For T3B Temperature Class multiply Kt and Ke ratings by 0.83; continuous current by 1.245; continuous torque by 1.095.

ER115 Series Gearmotor General Performance Specifications

Two torque ratings for the ER Series Gearmotors are given in the table below. The left hand columns give the maximum (peak) allowable output torque for the indicated ratios of each size ER Series Gearmotor. This IS NOT the rated output torque of the motor multiplied by the ratio of the reducer. It is possible to select a configuration of the motor selection and gear ratio such that the rated motor torque, multiplied by the gear ratio exceeds these ratings. It is the responsibility

of the user to ensure that the settings of the system, including the amplifier, do not allow these values to be exceeded.

The right hand columns give the output torque at the indicated speed which will result in 10,000 hour (L10). The setup of the system, including the amplifier, will determine the actual output torque and speed.

Output Torque Ratings – Mechanical

ER115 Ratio	Maximum Allowable Output Torque lbf-in (Nm)	Output Torque @ Speed for 10,000 Hour Life – lbf-in (Nm)		
		1000 RPM	3000 RPM	5000 RPM
4:1	4696 (530.4)	1392 (157.3)	1132 (127.9)	1000 (112.9)
5:1	4066 (459.4)	1445 (163.3)	1175 (132.8)	1040 (117.5)
10:1	2545 (287.5)	1660 (187.6)	1350 (152.6)	1200 (135.6)
16:1	4696 (530.4)	2112 (238.6)	1714 (193.0)	1518 (171.0)
20:1	4696 (530.4)	2240 (253.1)	1840 (207.9)	1620 (183.0)
25:1	4066 (459.4)	2350 (265.5)	1900 (214.7)	1675 (189.2)
40:1	4696 (530.4)	2800 (316.4)	2240 (253.1)	2000 (225.9)
50:1	4066 (459.4)	2900 (327.7)	2350 (265.5)	2100 (237.3)
100:1	2545 (287.5)	2500 (282.5)	2500 (282.5)	2400 (271.2)

Radial Load and Bearing Life

RPM	ER115 lbf (N)
50	939 (4177)
100	745 (3314)
250	549 (2442)
500	435 (1935)
1000	346 (1539)

Side load ratings shown below are for 10,000 hour bearing life at 25mm from motor face at given rpm.

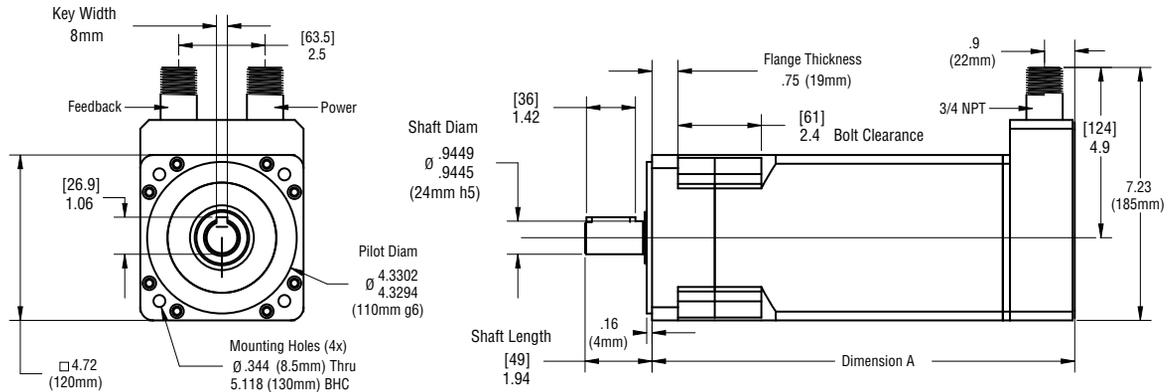
Visit www.exlar.com for full details on radial load and bearing life.

Motor and Gearmotor Weight

ER115	Motor lb (kg)	1 Stage lb (kg)	2 Stage lb (kg)
1 Stack	14.2 (6.4)	28 (12.7)	34 (15.4)
2 Stack	22.0 (10)	35.8 (16.2)	41.8 (18.9)
3 Stack	29.8 (13.5)	43.6 (19.8)	49.6 (22.5)

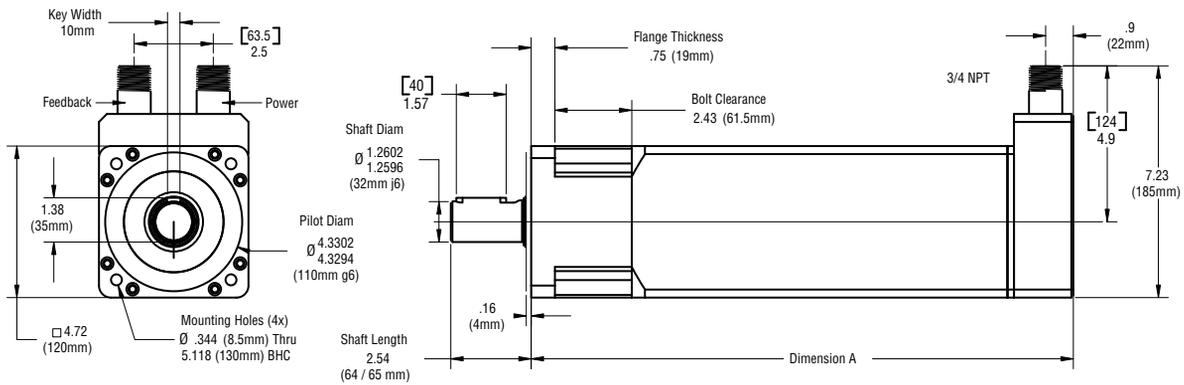
Hazardous Location ER Series Motors

ER115



Gear Reduction		Dimension "A"
Stages	Stacks	Length in (mm)
0	1	8.3 (210)
0	2	10.3 (261)
0	3	12.3 (311)

ER115 with Gear Reduction Option



Gear Reduction		Dimension "A"
Stages	Stacks	Length in (mm)
1	1	11.6 (293)
	2	13.6 (344)
	3	15.6 (395)

Gear Reduction		Dimension "A"
Stages	Stacks	Length in (mm)
2	1	13.2 (334)
	2	15.2 (385)
	3	17.2 (436)

Drawings subject to change. Consult Exlar for certified drawings.

ER115 Series

ER = Model Series

ER = Series

AAA = Frame Size

115 = 115 mm

BBB = Gear Reduction Ratio

(Optional - blank for motor)

004 = 4:1 Single stage reduction

005 = 5:1 Single stage reduction

010 = 10:1 Single stage reduction

016 = 16:1 Two stage reduction

020 = 20:1 Two stage reduction

025 = 25:1 Two stage reduction

040 = 40:1 Two stage reduction

050 = 50:1 Two stage reduction

100 = 100:1 Two stage reduction

C = Shaft Type

K = Keyed

R = Smooth /Round

X = Special shaft

DDD = Connection Options

N## = Potted NPT with flying leads

= length of flying leads in feet (not to exceed 99') contact your local sales representative if longer lengths are needed.

F = Brake Options

S = Standard no brake

GGG = Feedback Type

(Also specify the Amplifier/Drive Model being used when ordering) - Std Resolver - Size 15 1024 line (2048 cts) per rev., two pole resolver

XX1 = Custom Feedback - Wiring and feedback device information must be provided and new feedback callout will be created - contact your local sales representative - Resolver only

AB6 = Allen-Bradley/Rockwell - Standard Resolver

AM3 = Advanced Motion Control - Standard Resolver

AP1 = API Controls - Standard Resolver

BD2 = Baldor - Standard Resolver

BM2 = Baumuellner - Standard Resolver

BR1 = B&R Automation - Standard Resolver

CO2 = Copley Controls - Standard Resolver

CT5 = Standard Resolver

DT2 = Delta Tau Data Systems - Standard Resolver

EL1 = Elmo Motion Control - Standard Resolver

EX4 = Exlar - Standard Resolver

IF1 = Infranor - Standard Resolver

IN6 = Indramat/Bosch-Rexroth - Standard Resolver

JT1 = Jetter Technologies - Standard Resolver

KM5 = Kollmorgen/Danaher - Standard Resolver

LZ5 = Lenze/AC Tech - Standard Resolver

MD1 = Modicon - Standard Resolver

MG1 = Moog - Standard Resolver

MN4 = Momentum - Standard Resolver

MX1 = Metronix - Standard Resolver

OR1 = Ormec - Standard Resolver

PC7 = Parker - Standard Resolver - European only

PC0 = Parker - Standard Resolver - US only

PS3 = Pacific - Scientific Standard Resolver

SM2 = Siemens - Standard Resolver

SW1 = SEW/Eurodrive - Standard Resolver

WD1 = Whedco/Fanuc - Standard Resolver

HHH = Motor Stator, All 8 Pole

1A8 = 1 stack, 24 Vrms

1B8 = 1 stack, 48 Vrms

118 = 1 stack, 115 Vrms

138 = 1 stack, 230 Vrms

158 = 1 stack, 400 Vrms

168 = 1 stack, 460 Vrms

2A8 = 2 stack, 24 Vrms

2B8 = 2 stack, 48 Vrms

238 = 2 stack, 230 Vrms

258 = 2 stack, 400 Vrms

268 = 2 stack, 460 Vrms

338 = 3 stack, 230 Vrms

358 = 3 stack, 400 Vrms

368 = 3 stack, 460 Vrms

II = Speed Designations

01-99 Two digit number. Rated speed in rpm X 100

JJJ = Hazardous Location Temperature Rating

T3B = 180°C (Samarium Cobalt magnets)

T4 = 135°C (Neodymium-Iron-Boron magnets)

XX = Optional Speed & Mechanical Designations

XL = Special lubrication

= Part No. Designator for Specials

Optional 5 digit assigned part number to designate unique model numbers for specials.

GSX/GSM Linear Actuator with Class I Division 2 Option

The GSX and GSM linear actuators are available with Class I Division 2 certification for hazardous locations. A hazardous location is defined as a place where concentrations of flammable gases or vapors may occur. Electrical equipment that must be installed in these locations is designed and tested to ensure it does not initiate an explosion due to arcing contacts or high surface temperature of equipment.

The GSX or GSM actuators with this option offer the same product performance of the standard product offering as described in the GSX and GSM sections of this catalog. Please see those sections for performance and mechanical specifications.

Options for Class I Division 2 products:

- Resolver feedback
- Handwheel
- Brake

The GSX/M actuators are ideally suited for process control valve and damper applications in harsh environments. These actuators continuously hold the position of the valve stem or shaft allowing extremely fast response to the smallest command signal changes without overshoot even when friction is present. This results in improved loop performance and reduced process variability. With linear speeds up to 40 in/sec and long strokes, the GSX/M actuator has become a standard replacement for hydraulics on steam turbine applications.

Typical Applications

Chemical Processing
Turbine Control
Fuel Skids
Oil & Gas Upstream & Downstream
Power Utilities
Pulp & Paper
Damper Control
Valve Control



GSX/GSM
Linear Actuator



Features

T-LAM™ segmented lamination stator technology

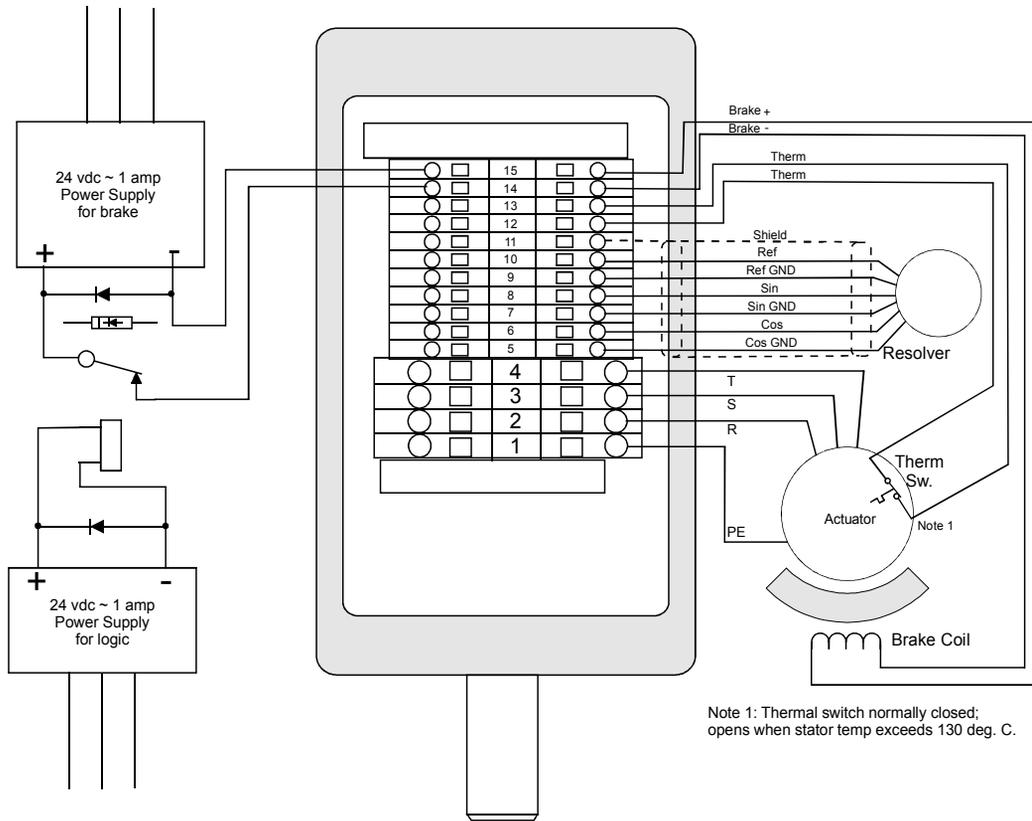
Linear speeds up to 40 in/sec

Resolver feedback

Class I, Division 2, Groups A, B, C & D certified

Terminal box with NPT ports

Terminal Box Wiring Diagram



Low Volt Terminal Block—Rockwell 1492-L3		Low Volt Terminal Block—Rockwell 1492-L6	
Voltage Rating	600 VAC/DC	Voltage Rating	600 VAC/DC
Current Rating	27 Amps	Current Rating	50 Amps
Wire Gauge Range	26-12 AWG	Wire Gauge Range	20-8 AWG

Ordering Information

Please use the ordering guide from the GSX (page 122) and GSM (page 125) sections with two callout selections as described below. The required connections selection is "T" and the required options selection is "NI"

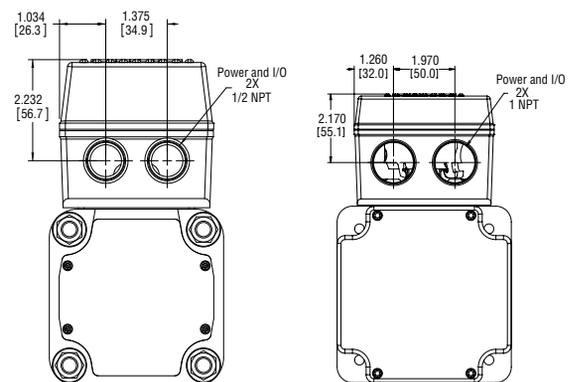
GSXAA - BBCC - **DEF** - GGG - HHH - II - (XX...XX)

↓
↓

T
NI

Connections
T = Terminal box with NPT ports
Options
NI = Non-Incendive

Terminal Box Dimensions

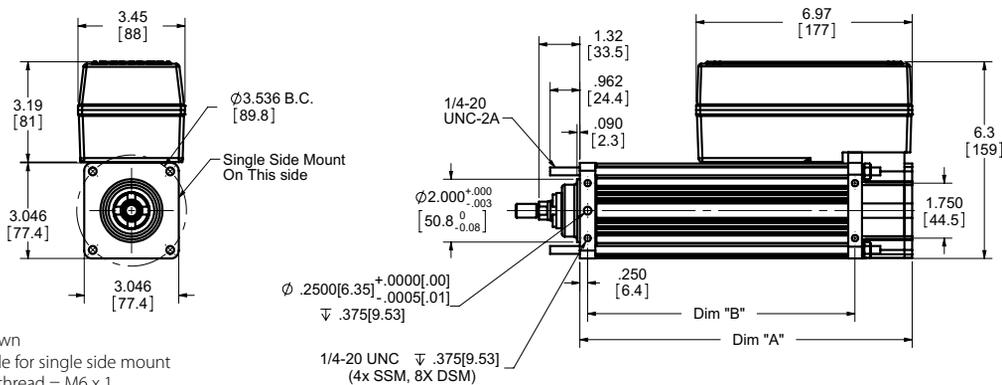


GSX/M30, GSM40*

GSX50, GSX60

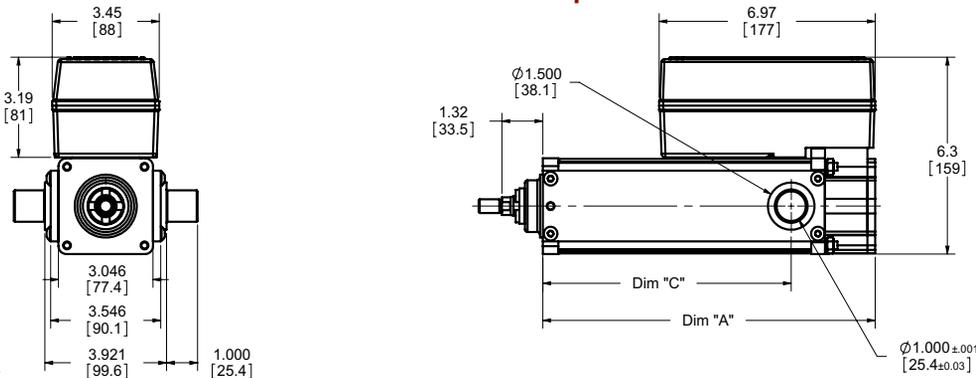
*Applications with >20A rms will require the larger terminal box.

GSX30 Single, Double Side Mounts or Extended Tie Rod Mount with Class I Div 2 Option



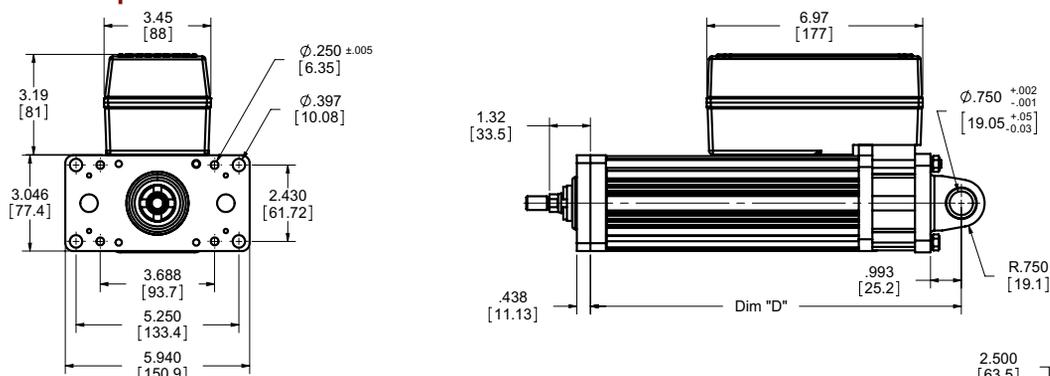
1. Three mounting styles shown
 2. Shown view is standard side for single side mount
- * If "M" metric tie rod option, thread = M6 x 1
 * If "J" or "K" metric side mount options, M6 x 1.0 ∇ 9 mm with \varnothing 6 mm M7 ∇ 9 mm Dowel Hole

GSX30 Side Trunnion Mount with Class I Div 2 Option

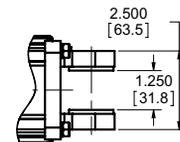


* If "Q" metric side trunnion option, \varnothing 25 mm h7

GSX30 Rear Clevis Mount or Front Flange Mount with Class I Div 2 Option



Dim	3" (76 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	14" (355 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	8.2 (209)	10.7 (272)	15.2 (387)	17.2 (437)	19.2 (488)	23.2 (590)
B	6.1 (156)	8.6 (219)	13.1 (333)	15.1 (384)	17.1 (435)	21.1 (536)
C	5.4 (137)	8.0 (203)	10.0 (254)	12.0 (305)	14.0 (356)	18.0 (457)
D	9.5 (241)	12.0 (304)	16.5 (418)	18.5 (469)	20.5 (520)	24.5 (621)

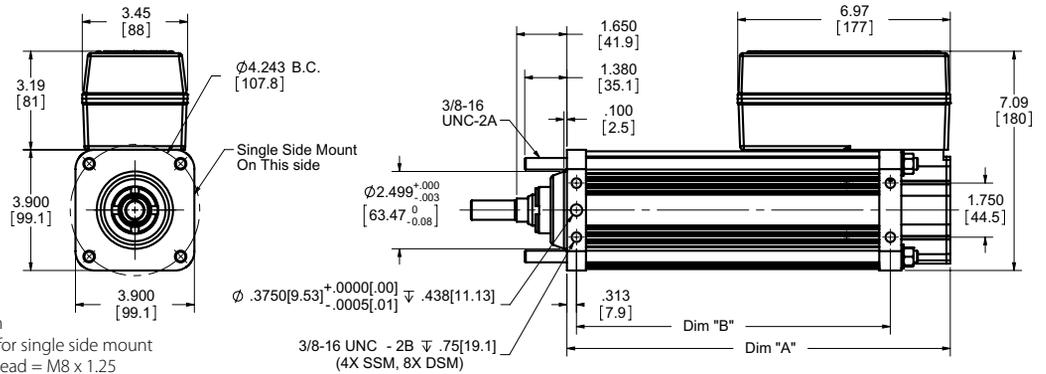


1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to top two drawings

Note: Add 1.6 Inches (40.64 mm) to Dims "A" & "D" if ordering a Brake.
 Applications with >20A rms will require the larger terminal box.

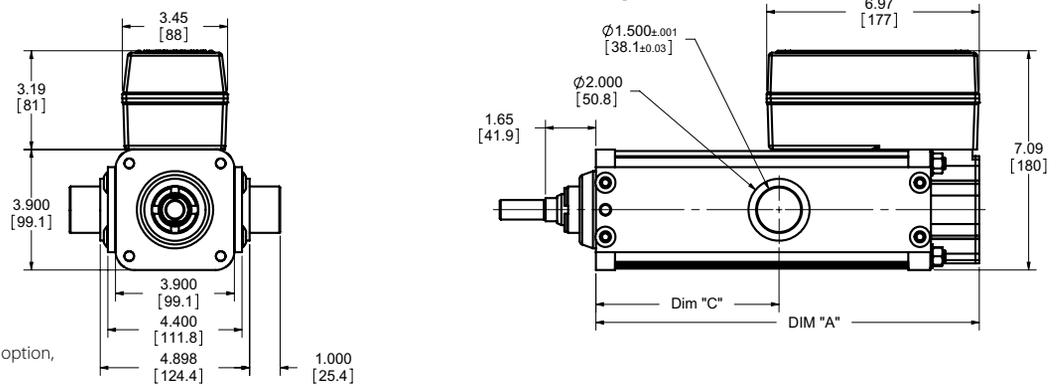
* If "G" metric clevis option, \varnothing 20 mm +0.00 / -0.07
 Drawings subject to change. Consult Exlar for certified drawings.

GSX40 Single, Double Side Mounts or Extended Tie Rod Mount with Class I Div 2 Option



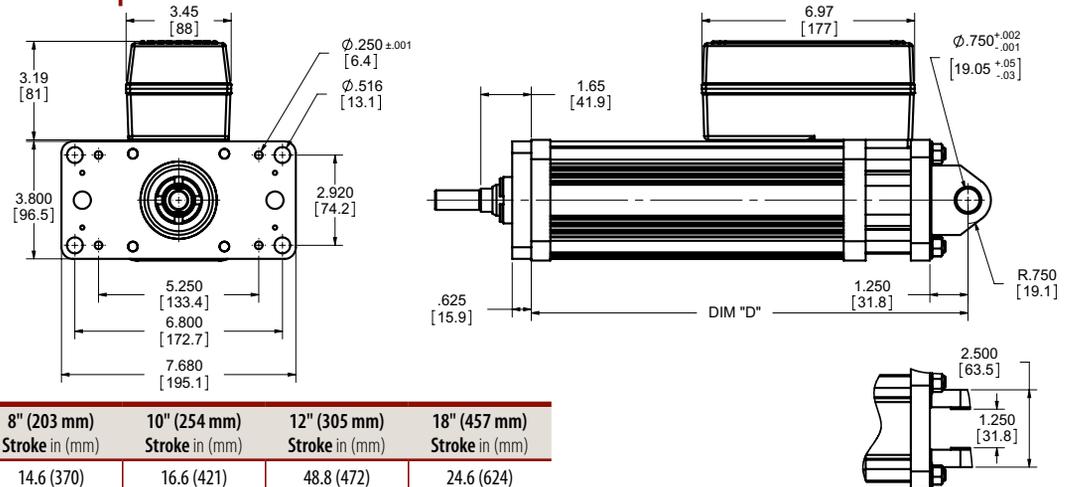
1. Three mounting styles shown
 2. Shown view is standard side for single side mount
- * If "M" metric tie rod option, thread = M8 x 1.25
 * If "J" or "K" metric side mount options, M10 x 1.5 ∇ 19 mm with \varnothing 8 mm M7 ∇ 12 mm Dowel Hole

GSX40 Side Trunnion Mount with Class I Div 2 Option



- * If "Q" metric side trunnion option, \varnothing 35 mm h7

GSX40 Rear Clevis Mount or Front Flange Mount with Class I Div 2 Option



Dim	6" (152 mm) Stroke in (mm)	8" (203 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	012.6 (320)	14.6 (370)	16.6 (421)	48.8 (472)	24.6 (624)
B	10.3 (262)	12.3 (313)	14.3 (364)	16.3 (414)	22.3 (567)
C	6.0 (152)	8.0 (203)	10.0 (254)	12.0 (305)	18.0 (457)
D	14.5 (364)	16.3 (415)	18.3 (466)	20.3 (516)	26.3 (669)

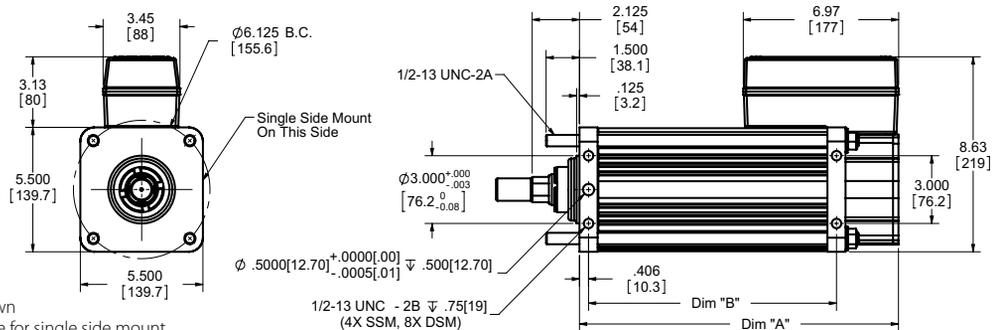
Note: Add 2.33 Inches (59.18 mm) to Dims "A" & "D" if ordering a Brake.
 Applications with >20A rms will require the larger terminal box.

* If "G" metric clevis option, \varnothing 20 mm +0.00 / -0.07
 Drawings subject to change. Consult Exlar for certified drawings.

1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to top two drawings

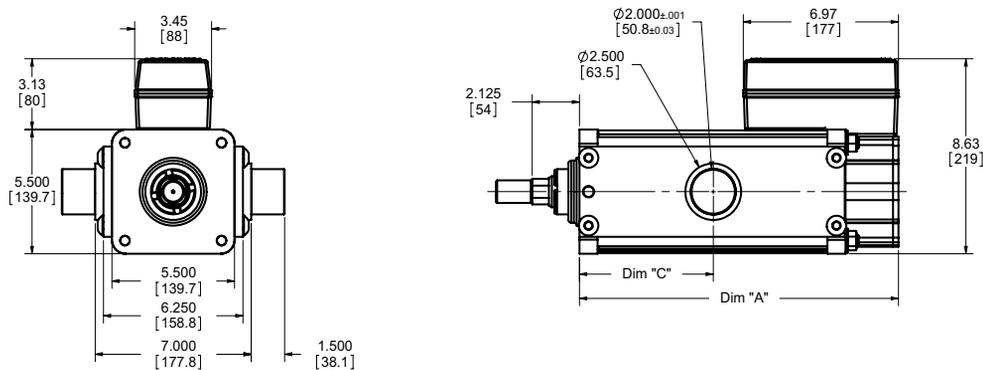
Hazardous Location GSX50 Class I Division 2

GSX50 Single, Double Side Mounts or Extended Tie Rod Mount with Class I Div 2 Option



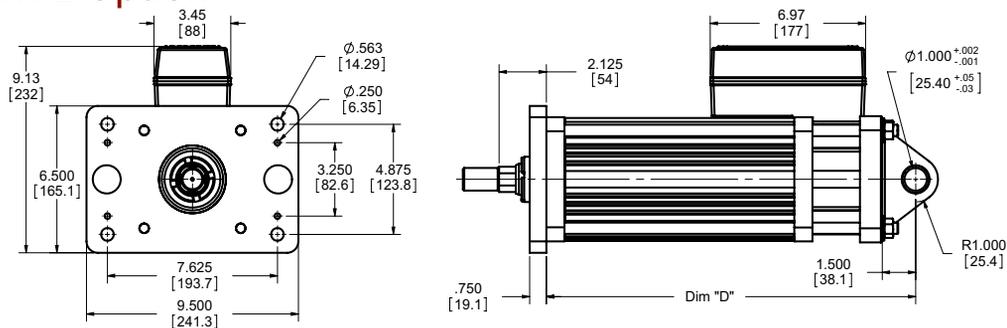
1. Three mounting styles shown
 2. Shown view is standard side for single side mount
- * If "M" metric tie rod option, thread = M8 x 1.25
 * If "J" or "K" metric side mount options, M12 x 1.75 ∇ 19 mm with \varnothing 12 mm M7 ∇ 12 mm Dowel Hole

GSX50 Side Trunnion Mount with Class I Div 2 Option



* If "Q" metric side trunnion option, \varnothing 50 mm h7

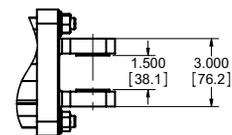
GSX50 Rear Clevis Mount or Front Flange Mount with Class I Div 2 Option



Dim	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	14" (355 mm) Stroke in (mm)
A	14.3 (364)	18.3 (465)	22.3 (567)
B	11.1 (282)	15.1 (384)	19.1 (486)
C	6.0 (152)	10.0 (254)	14.0 (356)
D	16.6 (421)	20.6 (522)	24.6 (624)

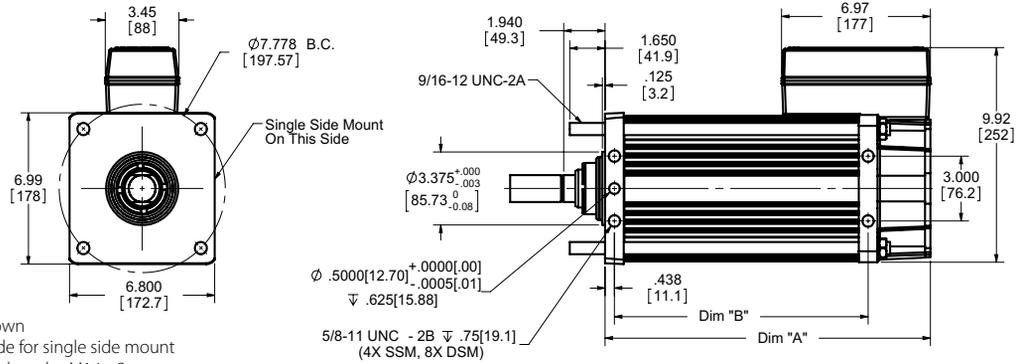
Note: Add 2.5 Inches to Dims "A" & "D" if ordering a Brake.

* If "G" metric clevis option, \varnothing 27 mm +0.00 / -0.06
 Drawings subject to change. Consult Exlar for certified drawings.



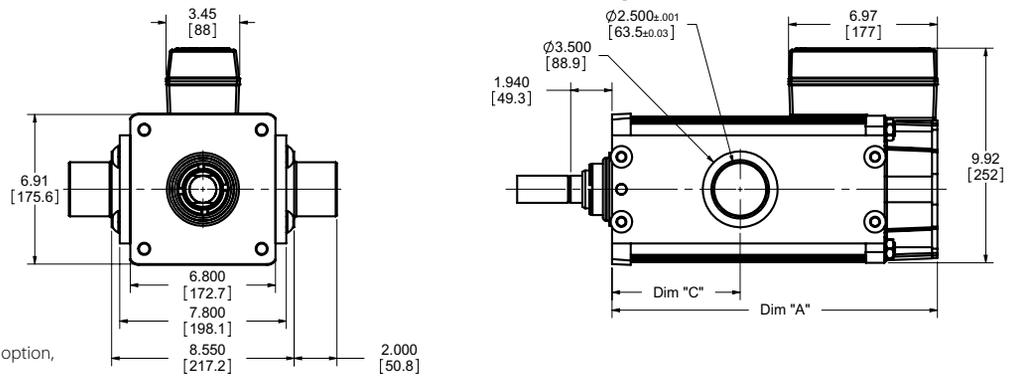
1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to top two drawings

GSX60 Single, Double Side Mounts or Extended Tie Rod Mount with Class I Div 2 Option



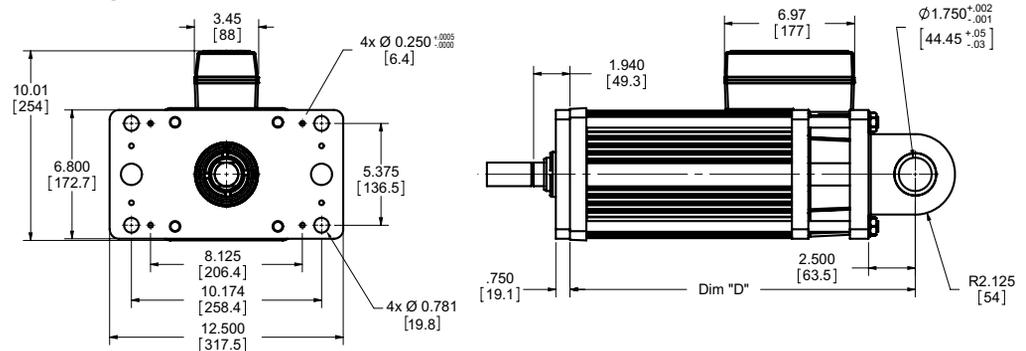
1. Three mounting styles shown
 2. Shown view is standard side for single side mount
- * If "M" metric tie rod option, thread = M14 x 2
 * If "J" or "K" metric side mount options, M16 x 2.0 ∇ 16 mm with \varnothing 12 mm M7 ∇ 12 mm Dowel Hole

GSX60 Side Trunnion Mount with Class I Div 2 Option



- * If "Q" metric side trunnion option, \varnothing 60 mm h9

GSX60 Rear Clevis Mount or Front Flange Mount with Class I Div 2 Option

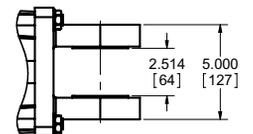


Dim	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)
A	15.2 (387)	19.2 (488)
B	11.9 (302)	15.9 (403)
C	6.0 (152)	10.0 (254)
D	18.5 (469)	22.5 (571)

1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to top two drawings

Note: Add 3.575 Inches to Dims "A" & "D" if ordering a Brake.

* If "G" metric clevis option, \varnothing 45 mm +0.00 / -0.08
 Drawings subject to change. Consult Exlar for certified drawings.



AA = Actuator Frame Size

- 30 = 3 inch (76 mm)
- 40 = 4 inch (102 mm)
- 50 = 5.5 inch (140 mm)
- 60 = 7 inch (178 mm)

BB = Stroke Length

- 03 = 3 inch (76 mm) GSX30
- 06 = 5.9 inch (152 mm) GSX30
6 inch (GSX20, 40, 50, 60)
- 08 = 8 inch (203 mm) GSX40
- 10 = 10 inch (254 mm) all models
- 12 = 12 inch (305 mm) GSX30, 40
- 14 = 14 inch (356 mm) GSX30, 50
- 18 = 18 inch (457 mm) GSX30, 40
- 24 = 24 inch (610 mm) GSX30

CC = Lead (position change per motor revolution)

- 01 = 0.1 inch (2.54 mm) GSX30, 40, 50⁸
- 02 = 0.2 inch (5.08 mm) GSX30, 40, 50
- 03 = 0.25 inch (6.35 mm) GSX60
- 05 = 0.5 inch (12.7 mm) GSX30, 40, GSX50, 60
- 08 = 0.75 inch (19.05 mm) GSX40³
- 10 = 1.0 inch (25.4 mm) GSX50, 60⁴
- XX = Special lead

D = Connections

- T = Terminal box with NPT ports
See pg 135

E = Mounting

- B = Front and rear flange
- C = Rear clevis
- F = Front flange
- R = Rear flange
- S = Side mount
- D = Double side mount
- T = Side trunnion
- E = Extended tie rods
- J = Metric side mount
- K = Metric double side mount
- Q = Metric side trunnion
- M = Metric extended tie rods
- G = Metric rear clevis
- X = Special (please specify)

F = Rod End

- M = Male, US std thread
- A = Male, metric thread
- F = Female, US std thread
- B = Female, metric thread
- W = Male, US std thread SS¹²
- R = Male metric thread SS¹²
- V = Female, US std thread SS¹²
- L = Female metric thread SS¹²
- X = Special (please specify)

GGG = Feedback Type (Also specify the Amplifier/Drive Model being used when ordering) Resolver Only.

Standard Resolver – Size 15, 1024 line
(2048 cts) per rev, 2 pole resolver

Custom Feedback: Please contact your local sales representative:

- XX1 = Wiring and feedback device information must be provided and new feedback callout will be created
- AB6 = Allen Bradley/Rockwell - Std Resolver
- AM3 = Advanced Motion Control - Std Resolver
- AP1 = API Controls - Std Resolver
- BD2 = Baldor - Std Resolver
- BM2 = Baumuller - Std Resolver
- BR1 = B&R Automation - Std Resolver
- CO2 = Copely Controls - Std Resolver
- CT5 = Control Techniques/Emerson - Std Resolver
- DT2 = Delta Tau Data Systems - Std Resolver
- EL1 = Elmo Motion Control - Std Resolver
- EX4 = Exlar - Std Resolver
- IF1 = Infranor - Std Resolver
- IN6 = Indramat/Bosch-Rexroth - Std Resolver
- JT1 = Jetter Technologies - Std Resolver
- KM5 = Kollmorgen/Danaher - Std Resolver
- LZ5 = Lenze/AC Tech - Std Resolver
- MD1 = Modicon - Std Resolver
- MG1 = Moog - Std Resolver
- MX1 = Metronix - Std Resolver
- MN4 = Momentum - Std Resolver
- OR1 = Ormec - Std Resolver
- PC7 = Parker Compumotor - Std Resolver – European only
- PC0 = Parker Compumotor - Std Resolver – US Only
- PS3 = Pacific Scientific - Std Resolver
- SM2 = Siemens - Std Resolver
- SW1 = SEW/Eurodrive - Std Resolver
- WD1 = Whedco - Std Resolver

H = Motor Stacks

- 1 = 1 stack magnets
- 2 = 2 stack magnets
- 3 = 3 stack magnets⁷
- x = Special

I = Voltage Rating

- A = 24 V DC
- B = 48 V DC
- C = 120 V DC
- 1 = 115 Volt RMS
- 3 = 230 Volt RMS
- 5 = 400 Volt RMS
- 6 = 460 Volt RMS
- X = Special voltage rating - not to exceed 460 Vrms

J = Motor Poles

- 8 = 8 motor poles

KK = Motor Speed

- 24 = 2400 rpm, GSX/M50, GSX60
- 30 = 3000 rpm, GSX/M30, 40
- 01-99 = Rated speed in RPM x 100

XX .. XX = Options (please list desired options)

Travel Options

- NI = Non-incendive construction required for Class 1, Div 2 (see pg 135)
- AR = External anti-rotate²
- HW = Manual drive, handwheel including Class I, Div 2 interlock switch¹¹
- PF = Preloaded follower¹
- RB = Rear electric brake
- RD = Manual drive, Simple Rear¹¹
- SD = Manual drive, Side Hex¹¹
- PB = Protective bellows¹⁰
- SR = Splined main rod¹²
- XT = Special travel options including high temp bellows¹⁰

Housing Options

- EN = Electroless nickel plating⁵
- FG = White epoxy
- HC = type III anodizing hard coat⁵
- SS = Stainless steel housing^{5,9}
- XH = Special housing option
- XL = Special lubrication (greases only)
- XM = Special motor option

= Part No. Designator for Specials

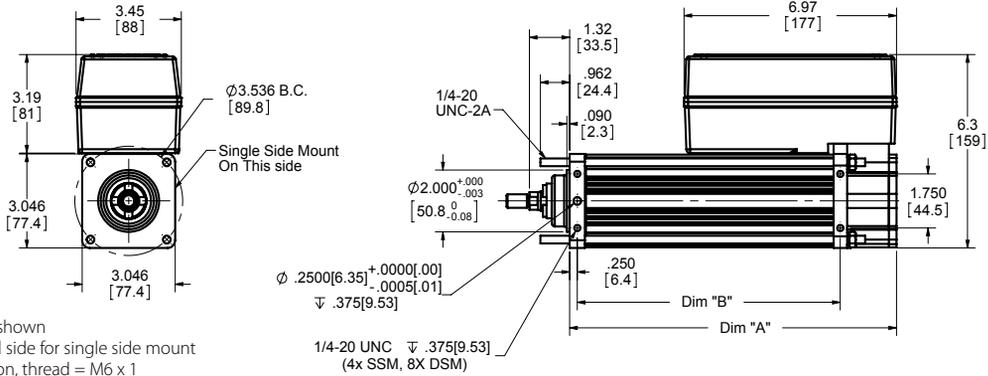
Optional 5 digit assigned part number to designate unique model numbers for specials.

Notes:

1. The dynamic load rating of preloaded screws is 63% of the rating of non-preloaded screws. Travel life of preloaded screw is 25% of non-preloaded screw of same size.
2. A second anti-rotate arm is used on GSX30 10 inch and longer stroke; GSX40 12 inch and longer.
3. 0.75 inch (19.05 mm) lead N/A above 12 inch (305 mm) stroke on GSX40.
4. 1.0 inch (25.4 mm) lead N/A above 10 inch (250 mm) stroke on GSX50 or 60.
5. These housing options may also indicate the need for special material main rods or mounting.
6. Due to reduced dia of splined main rod on GSX50, the std "A" male metric rod end is N/A. An "X" should be used in the rod end location of the model mask. If not otherwise specified by customer, an M24X2 male rod end will be used.
7. 3 stack stator not available on 3" stroke.
8. 0.1 inch lead N/A over 10" stroke on GSX50.
9. Force, torque and current ratings are reduced 25% with this option.
10. N/A with extended tie rod mounting option.
11. N/A with holding brake unless application details are discussed with your local sales representative.
12. Consult your local sales representative when ordering splined stainless steel main rod.

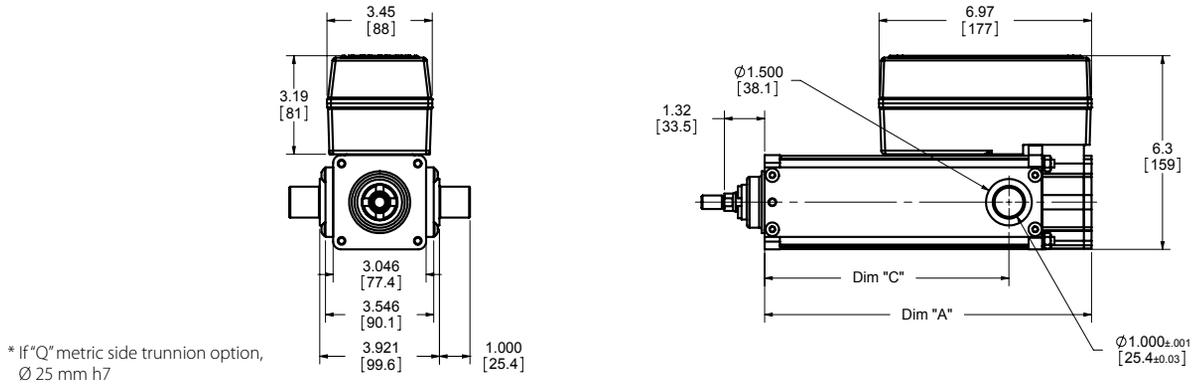
See page 26 for Accessories and page 96 for Cables.

GSM30 Single, Double Side Mounts or Extended Tie Rod Mount with Class I Div 2 Option



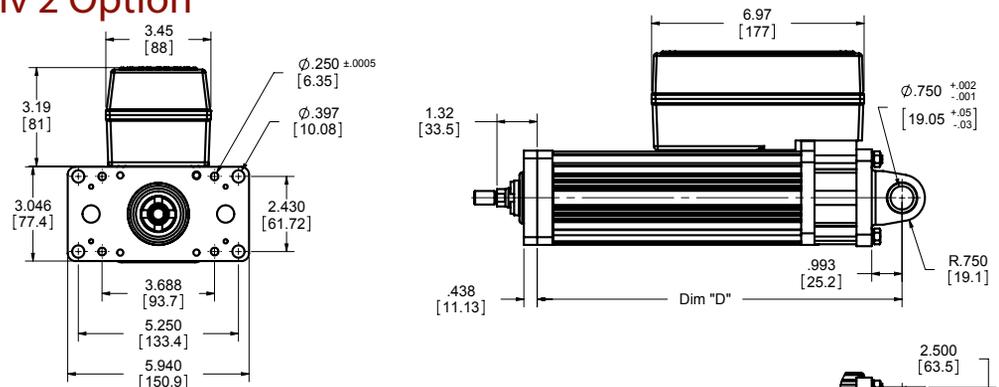
1. Three mounting styles shown
 2. Shown view is standard side for single side mount
- * If "M" metric tie rod option, thread = M6 x 1
 * If "J" or "K" metric side mount options, M6 x 1.0 ∇ 9 mm with \varnothing 6 mm M7 ∇ 9 mm Dowel Hole

GSM30 Side Trunnion Mount with Class I Div 2 Option



- * If "Q" metric side trunnion option, \varnothing 25 mm h7

GSM30 Rear Clevis Mount or Front Flange Mount with Class I Div 2 Option

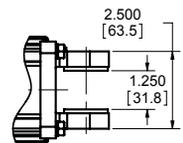


Dim	3" (76 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	14" (355 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	8.2 (209)	10.7 (272)	15.2 (387)	17.2 (437)	19.2 (488)	23.2 (590)
B	6.1 (156)	8.6 (219)	13.1 (333)	15.1 (384)	17.1 (435)	21.1 (536)
C	5.4 (137)	8.0 (203)	10.0 (254)	12.0 (305)	14.0 (356)	18.0 (457)
D	9.5 (241)	12.0 (304)	16.5 (418)	18.5 (469)	20.5 (520)	24.5 (621)

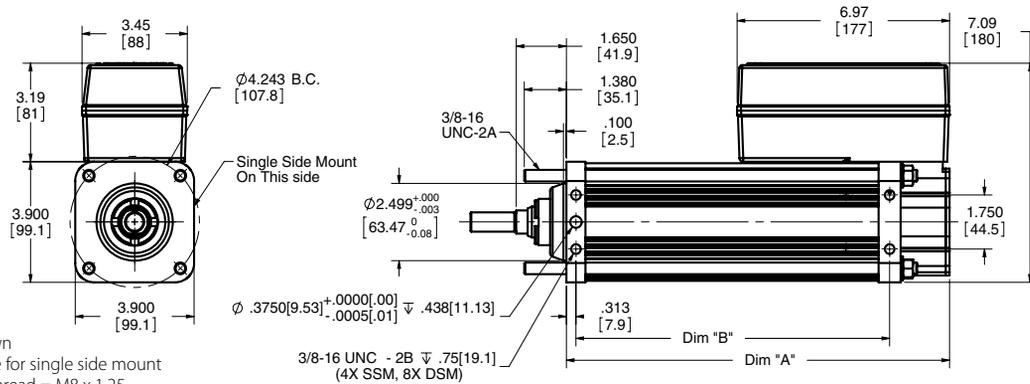
Note: Add 1.6 Inches (40.64 mm) to Dims "A & D" if ordering a Brake.
 Applications with >20A rms will require the larger terminal box.

* If "G" metric clevis option, \varnothing 20 mm +0.00 / -0.07
 Drawings subject to change. Consult Exlar for certified drawings.

1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to top two drawings

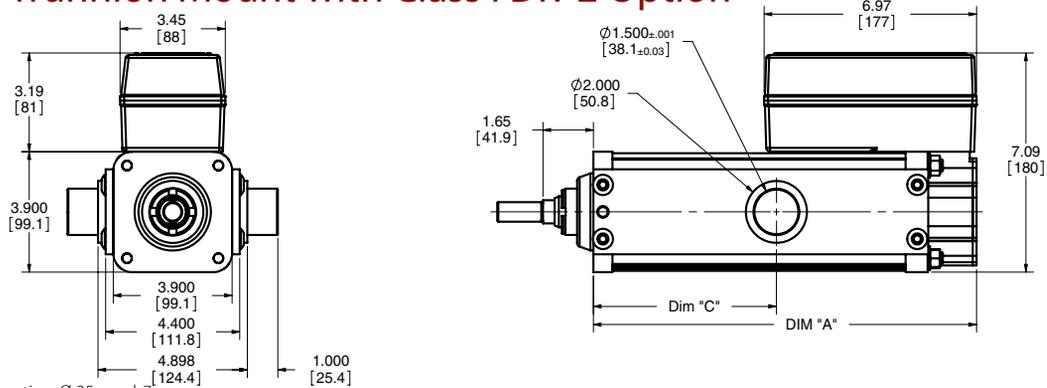


GSM40 Single, Double Side Mounts or Extended Tie Rod Mount with Class I Div 2 Option



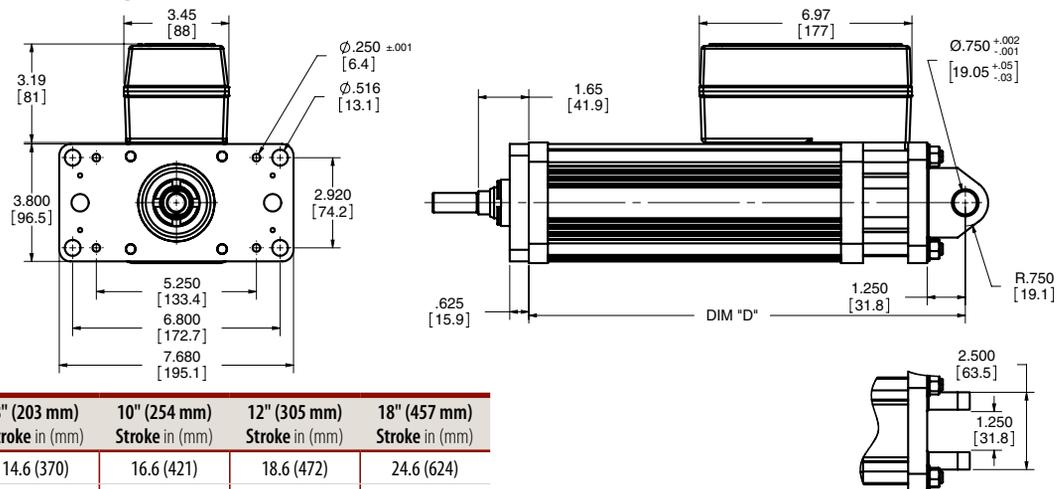
1. Three mounting styles shown
 2. Shown view is standard side for single side mount
- * If "M" metric tie rod option, thread = M8 x 1.25
 * If "J" or "K" metric side mount options, M10 x 1.5 ∇ 19 mm with \varnothing 8 mm M7 ∇ 12 mm Dowel Hole

GSM40 Side Trunnion Mount with Class I Div 2 Option



*If "Q" metric side trunnion option, \varnothing 35 mm h7

GSM40 Rear Clevis Mount or Front Flange Mount with Class I Div 2 Option



Dim	6" (152 mm) Stroke in (mm)	8" (203 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	012.6 (320)	14.6 (370)	16.6 (421)	18.6 (472)	24.6 (624)
B	10.3 (262)	12.3 (313)	14.3 (364)	16.3 (414)	22.3 (567)
C	6.0 (152)	8.0 (203)	10.0 (254)	12.0 (305)	18.0 (457)
D	14.5 (364)	16.3 (415)	18.3 (466)	20.3 (516)	26.3 (669)

1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to top two drawings

Note: Add 2.33 Inches (59.18 mm) to Dims "A & D" if ordering a Brake.
 Applications with >20A rms will require the larger terminal box.

* If "G" metric clevis option, \varnothing 20 mm +0.00 / -0.07
 Drawings subject to change. Consult Exlar for certified drawings.

AA = Actuator Frame Size

- 30 = 3 inch (75 mm)
- 40 = 4 inch (100 mm)

BB = Stroke Length

- 03 = 3 inch (76 mm) GSM30
- 06 = 6 inch (152 mm) all models
GSM30 = 5.9 inch
- 08 = 8 inch (203 mm) GSM40
- 10 = 10 inch (254 mm) all models
- 12 = 12 inch (305 mm) all models
- 18 = 18 inch (457 mm) GSM30, 40

CC = Lead (position change per motor revolution)

- 01 = 0.1 inch (2.54 mm)
- 02 = 0.2 inch (5.08 mm)
- 05 = 0.5 inch (12.7 mm) GSM30, 40
- 08 = 0.75 inch (19.05 mm)³GSM40

D = Connections

- T = Terminal Box with NPT ports (see pg 135)

E = Mounting

- B = Front and rear flange
- C = Rear clevis
- F = Front flange
- R = Rear flange
- S = Side mount
- D = Double side mount
- T = Side trunnion
- E = Extended tie rods
- J = Metric side mount
- K = Metric double side mount
- Q = Metric side trunnion
- M = Metric extended tie rods
- G = Metric rear clevis
- Z = Clevis mount with same pin to pin as SR Series
- X = Special (please specify)

F = Rod End

- M = Male, US std thread
- A = Male, metric thread
- F = Female, US std thread
- B = Female, metric thread
- W = Male, US std thread SS⁶
- R = Male metric thread SS⁶
- V = Female, US std thread SS⁶
- L = Female metric thread SS⁶
- X = Special (please specify)

GGG = Feedback Type (Also specify the Amplifier/Drive Model being used when ordering) Resolver Only

Standard Resolver – Size 15, 1024 line (2048 cts) per rev, 2 pole resolver

Custom Feedback: Please contact your local sales representative:

- XX1 = Wiring and feedback device
information must be provided and new feedback callout will be created
- AB6 = Allen Bradley/Rockwell - Std Resolver
- AM3 = Advanced Motion Control - Std Resolver
- AP1 = API Controls - Std Resolver
- BD2 = Baldor - Std Resolver - BSM motor wiring w/M23 connectors for "M" option
- BM2 = Baumuller - Std Resolver
- BR1 = B&R Automation - Std Resolver
- CO2 = Copely Controls - Std Resolver
- CT5 = Control Techniques/Emerson - Std Resolver – FM/UM/EZ motor wiring w/M23 euro connectors for "M" option
- DT2 = Delta Tau Data Systems - Std Resolver
- EL1 = Elmo Motion Control - Std Resolver
- EX4 = Exlar - Std Resolver
- IF1 = Infranor - Std Resolver
- IN6 = Indramat/Bosch-Rexroth-Std Resolver – MKD/MHD motor wiring w/M23 euro connectors for "M" option
- JT1 = Jetter Technologies - Std Resolver – JH/JL motor wiring w/M23 euro connectors for "M" option
- KM5 = Kollmorgen/Danaher - Std Resolver – AKM motor wiring w/M23 euro connectors for "M" option
- LZ5 = Lenze/AC Tech - Std Resolver – MCS motor wiring w/M23 euro connectors for "M" option
- MD1 = Modicon - Std Resolver
- MG1 = Moog - Std Resolver
- MX1 = Metronix - Std Resolver
- MN4 = Momentum - Std Resolver
- OR1 = Ormec - Std Resolver
- PC7 = Parker Compumotor - Std Resolver – SMH motor wiring w/M23 connectors for "M" option – European only
- PC0 = Parker Compumotor - Std Resolver – MPP motor wiring w/PS connectors for "M" option – US Only
- PS3 = Pacific Scientific - Std Resolver – PMA motor wiring w/M23 connectors for "M" option
- SM2 = Siemens - Std Resolver – 1FK7 motor wiring w/M23 connectors for "M" option
- SW1 = SEW/Eurodrive - Std Resolver – CM motor wiring w/ M23 euro connectors for "M" option
- WD1 = Whedco - Std Resolver

H = Motor Stacks

- 1 = 1 stack magnets
- 2 = 2 stack magnets
- x = Special

I = Voltage Rating

- A = 24 Volt DC
- B = 48 Volt DC
- C = 120 Volt DC
- 1 = 115 Volt RMS
- 3 = 230 Volt RMS
- 5 = 400 Volt RMS
- 6 = 460 Volt RMS
- X = Special Voltage Rating - Not to exceed 460 Vrms

J = Motor Poles

- 8 = 8 Motor Poles

KK = Motor Speed

- 24 = 2400 rpm, GSX/M50, GSX60
- 30 = 3000 rpm, GSX/M30, 40
- 01-99 = Rated speed in RPM x 100

XX .. XX = Options (please list desired options)

Travel Options

- NI = Non-incendive construction required for Class 1, Div 2 (see pg 117)
- AR = External anti-rotate⁴
- PF = Preloaded follower¹
- RB = Rear electric brake
- RD = Manual drive, Simple Rear
- SD = Manual drive, Side Hex
- HW = Manual drive, handwheel including Class I, Div 2 interlock switch
- P5 = IP65S
- PB = Protective bellows⁵
- SR = Splined main rod⁶
- XT = Special travel options, high temp bellows⁵, or angular contact bearings

Housing Options

- EN = Electroless nickel plating²
- HC = type III anodizing hard coat²
- XH = Special housing option
- XL = Special lubrication (greases only)
- XM = Special motor option

= Part No. Designator for Specials

Optional 5 digit assigned part number to designate unique model numbers for specials.

Notes:

1. The dynamic load rating of preloaded screws is 63% of the rating of non-preloaded screws. Travel life of preloaded screw is 25% of non-preloaded screw of same size.
2. These housing options may also indicate the need for special material main rods or mounting.
3. 0.75 inch (19.05 mm) lead N/A over 12 inch (450 mm) stroke.
4. A second anti-rotate arm is used on GSM30 10 inch and longer stroke; GSM40 12 inch and longer stroke.
5. Not available with extended tie rod mounting option.
6. Consult your local sales representative when ordering splined stainless steel main rod.

SLM/SLG Series Motors with Class I Division 2 Option

The SLM/G rotary motors are available with Class I Division 2 certification for hazardous locations. A hazardous location is defined as a place where concentrations of flammable gases or vapors occur. Electrical equipment that must be installed in these locations is designed and tested to ensure it does not initiate an explosion due to arcing contacts or high surface temperature of equipment.

The SLM/G motors with this option offer the same product performance of the standard product offering as described in the SLM/G section of this catalog. Please see those sections for mechanical specifications.

Class I Division 2 Options include:

- Resolver feedback
- Handwheel
- Brake

The SLM/G actuators are ideal for operating quarter turn or multi turn valves or shaft driven dampers in hazardous environments. These actuators are directly coupled shaft-to-shaft, eliminating ungainly mechanisms needed by the linear motion of pneumatics. Our compact T-LAM™ servo motors outperform any standard motor, providing excellent continuous modulating service.

Typical Applications

Chemical Processing
Fuel Skids
Oil & Gas Upstream & Downstream
Power Utilities
Basis Weight
Pulp and Paper
Damper Control
Valve Control



SLM/SLG
Rotary Actuator



163694
Class I, Division 2

Features

T-LAM™ Segmented lamination stator technology

Resolver feedback

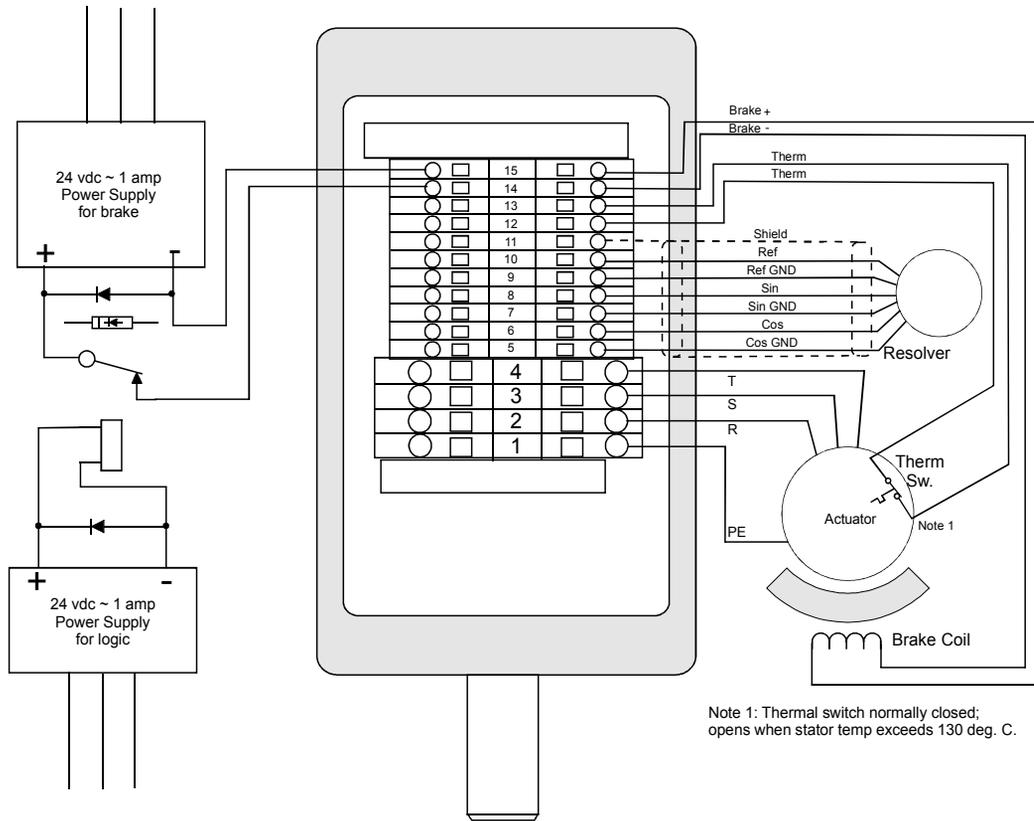
High load bearing design

Integrated armature and sun gear for SLG models

Class I, Div 2 groups A, B, C & D certified

Terminal box with NPT ports

Terminal Box Wiring Diagram



Low Volt Terminal Block—Rockwell 1492-L3		Low Volt Terminal Block—Rockwell 1492-L6	
Voltage Rating	600 VAC/DC	Voltage Rating	600 VAC/DC
Current Rating	27 Amps	Current Rating	50 Amps
Wire Gauge Range	26-12 AWG	Wire Gauge Range	20-8 AWG

Ordering Information

Please use the ordering guide from the SLM and SLG (page 133) sections with two callout selections as described below. The required connections selection is "T" and the required options selection is "NI".

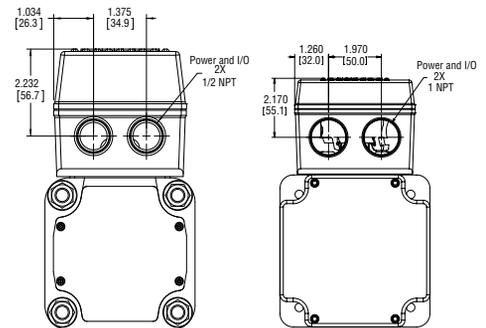
SLM/GAAA - BBB - CDEF - GGG - HHH - II - (XX-#####)

↓
↓

T
NI

Connections
T = Terminal box with NPT ports
Options
NI = Non-Incendive

Terminal Box Dimensions



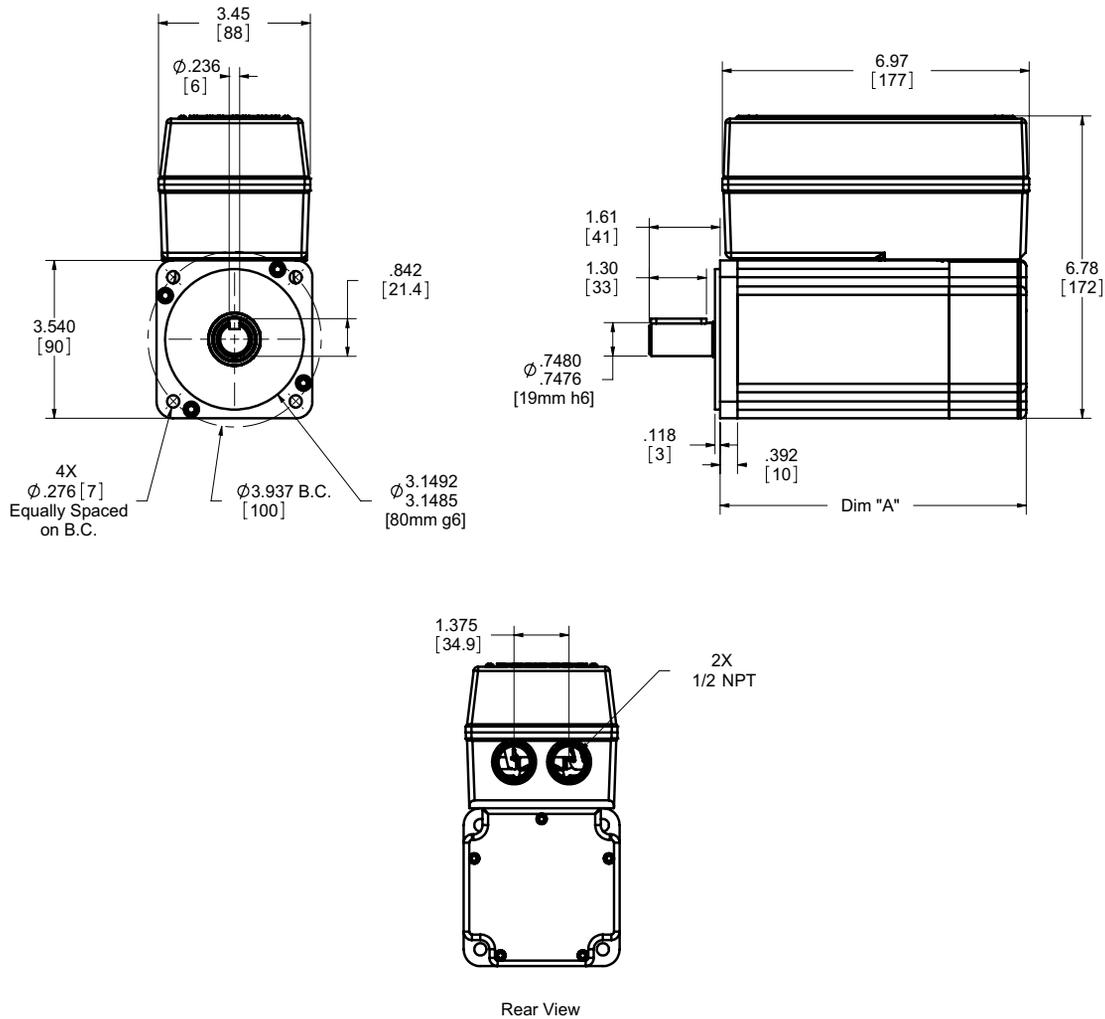
SLM/G090, SLM/G115*

*Applications with >20A rms will require the larger terminal box.

SLM142, SLM180

Hazardous Location SLM090 Class I Division 2

SLM090 Class I Div 2 Option

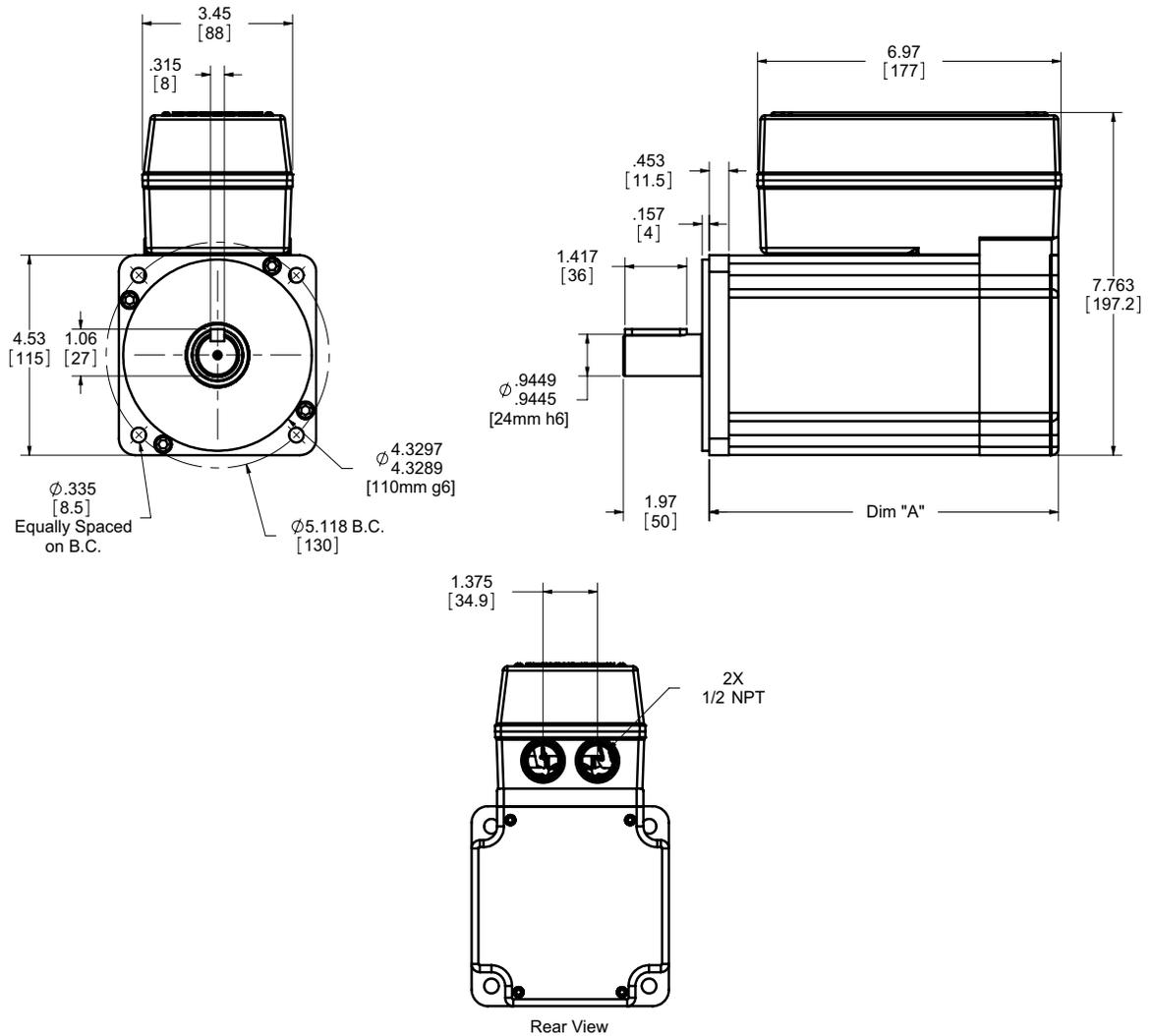


SLM090 Dim. in. (mm)	1 Stack Stator	2 Stack Stator	3 Stack Stator	1 Stack Stator with Brake	2 Stack Stator with Brake	3 Stack Stator with Brake
A	NA	5.65 (144)	6.65 (169)	5.96 (151)	6.96 (177)	7.96 (202)

Face plate edge is not intended for alignment of shaft (use pilot)
Applications with >20A rms will require the larger terminal box.

Drawings subject to change. Consult Exlar for certified drawings.

SLM115 Class I Div 2 Option



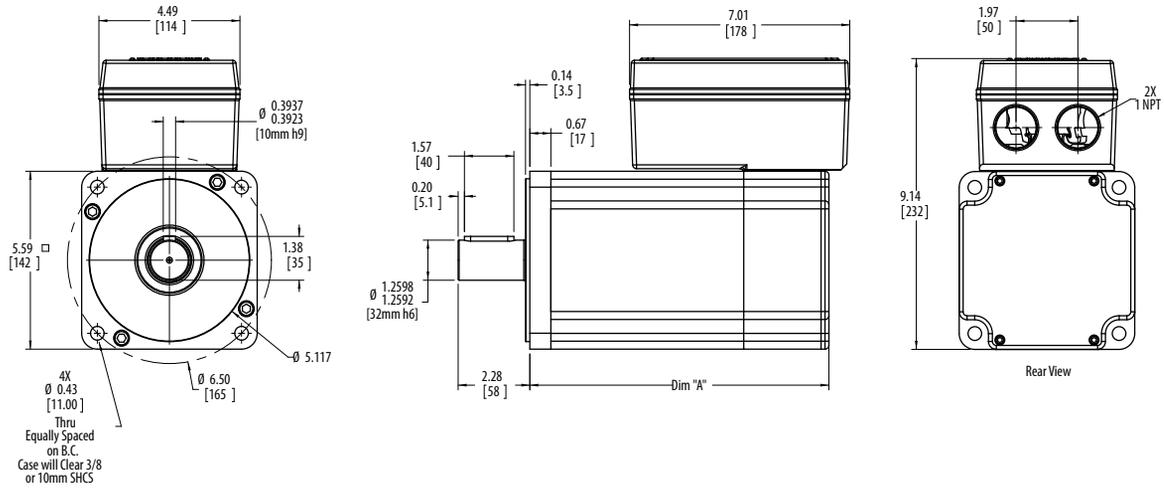
SLM115 Dim in. (mm)	1 Stack Stator	2 Stack Stator	3 Stack Stator	1 Stack Stator with Brake	2 Stack Stator with Brake	3 Stack Stator with Brake
A	6.02 (153)	8.02 (203.7)	10.02 (254.5)	7.75 (196.9)	9.75 (247.7)	11.75 (298.5)

Face plate edge is not intended for alignment of shaft (use pilot)
Applications with >20A rms will require the larger terminal box.

Drawings subject to change. Consult Exlar for certified drawings.

Hazardous Location SLM142 Class I Division 2

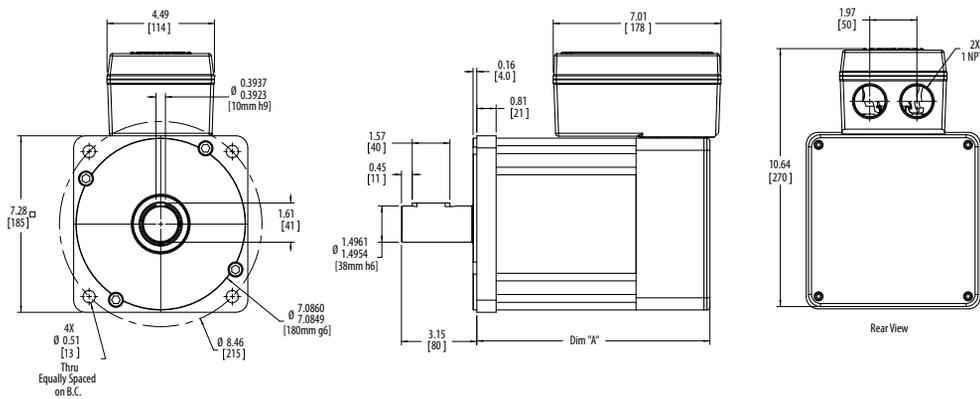
SLM142 Class I Div 2 Option



SLM142	1 Stack Stator	2 Stack Stator	3 Stack Stator	1 Stack Stator with Brake	2 Stack Stator with Brake	3 Stack Stator with Brake
Dim A in. (mm)	7.87 (199.8)	9.62 (244.2)	11.37 (288.7)	9.53 (241.9)	11.28 (286.4)	13.03 (330.8)

Face plate edge is not intended for alignment of shaft (use pilot)

SLM180 Class I Div 2 Option

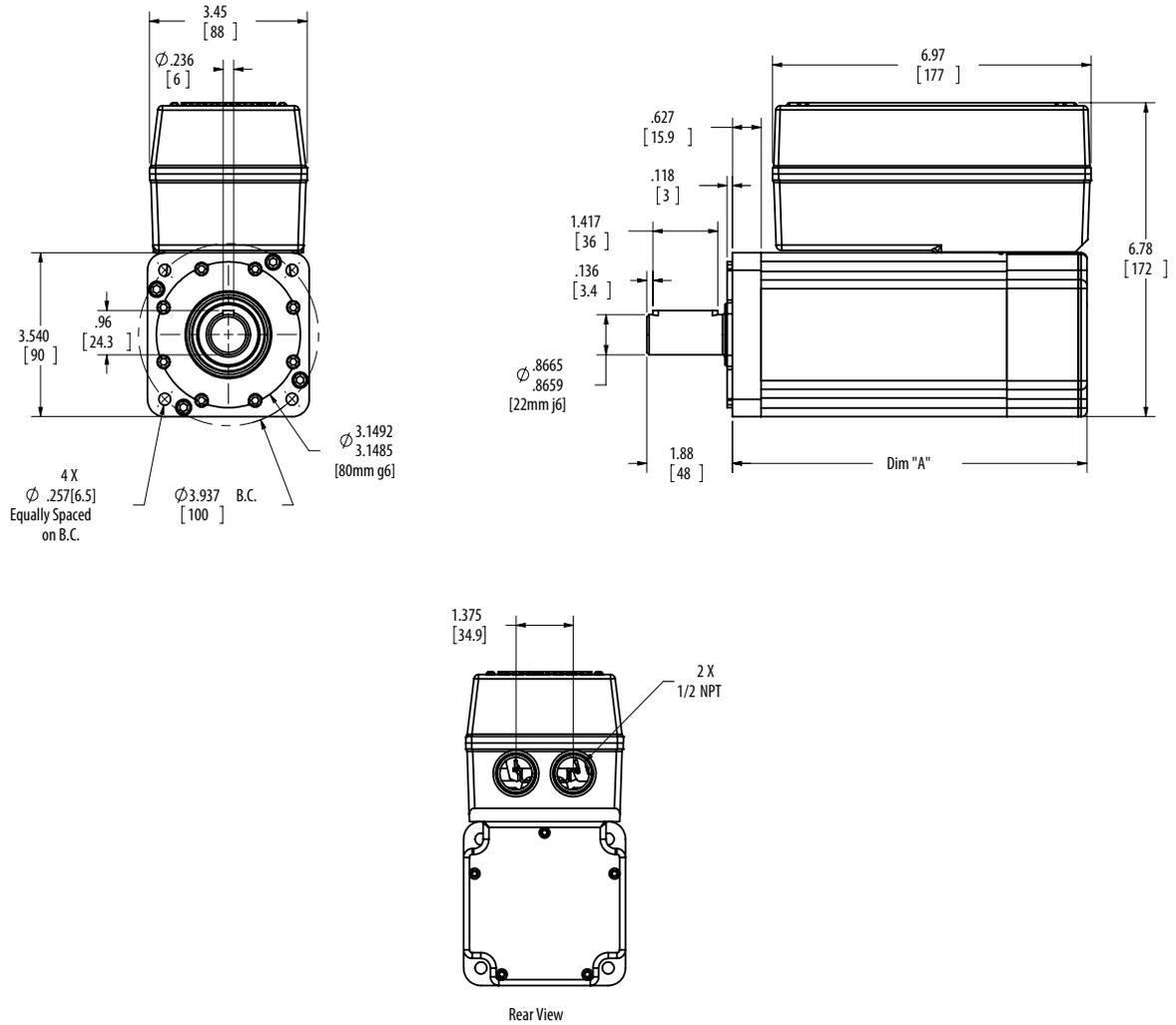


SLM180	1 Stack Stator	2 Stack Stator	3 Stack Stator	1 Stack Stator with Brake	2 Stack Stator with Brake	3 Stack Stator with Brake
Dim A in. (mm)	9.74 (247)	12.24 (311)	14.74 (374)	11.64 (296)	14.14 (359)	16.64 (423)

Face plate edge is not intended for alignment of shaft (use pilot)

Drawings subject to change. Consult Exlar for certified drawings.

SLG090 Class I Div 2 Option



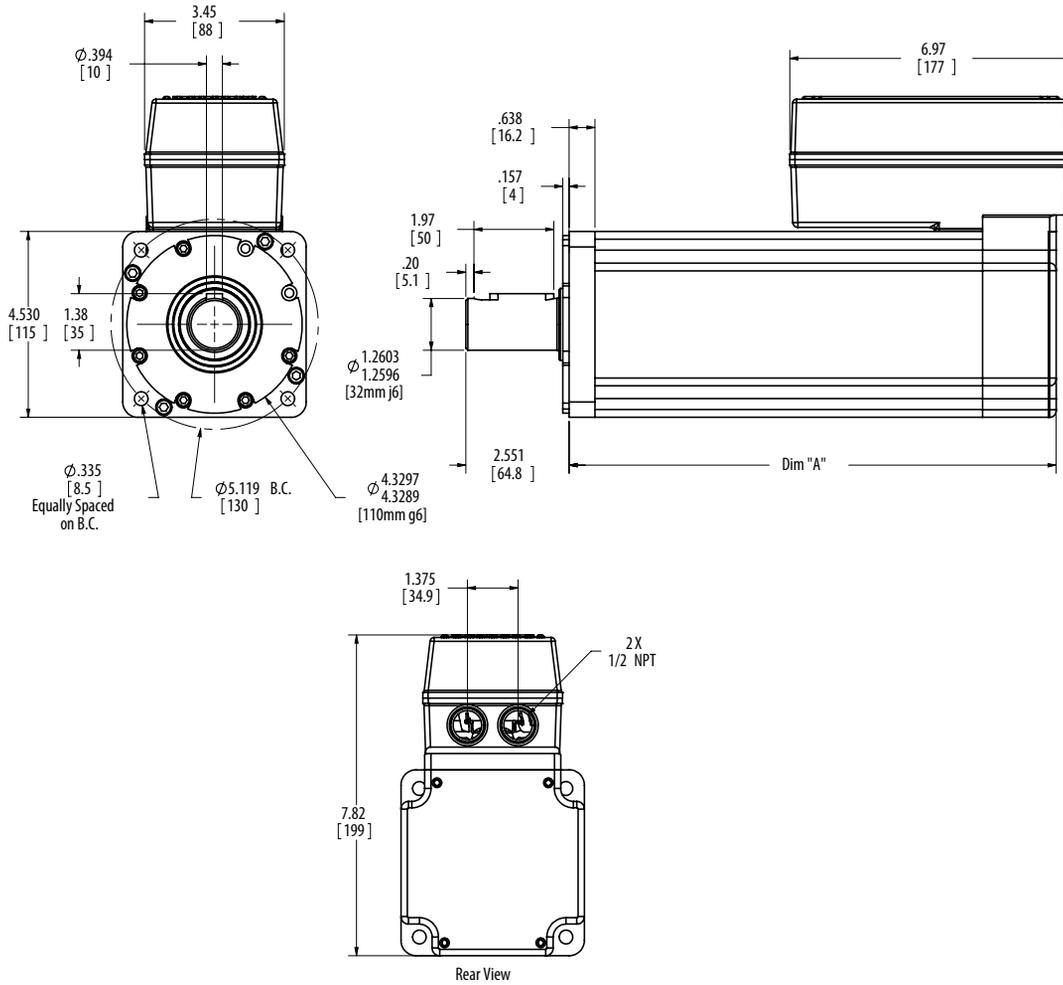
SLG090 Dim. in. (mm)	1 Stack Stator	2 Stack Stator	3 Stack Stator	1 Stack Stator with Brake	2 Stack Stator with Brake	3 Stack Stator with Brake
A 1 Stage Gearhead	7.76 (197)	8.76 (223)	9.96 (248)	9.07 (230)	10.07 (256)	11.07 (281)
A 2 Stage Gearhead	9.03 (229)	10.03 (255)	11.03 (280)	10.34 (263)	11.34 (288)	12.34 (313)

Face plate edge is not intended for alignment of shaft (use pilot)
Applications with >20A rms will require the larger terminal box.

Drawings subject to change. Consult Exlar for certified drawings.

Hazardous Location SLG115 Class I Division 2

SLG115 Class I Div 2 Option



SLG115 Dim. in. (mm)	1 Stack Stator	2 Stack Stator	3 Stack Stator	1 Stack Stator with Brake	2 Stack Stator with Brake	3 Stack Stator with Brake
A 1 Stage Gearhead	10.03 (254.8)	12.03 (305.6)	14.03 (356.4)	11.58 (294.2)	13.58 (345)	15.58 (395.8)
A 2 Stage Gearhead	11.64 (295.7)	13.64 (346.5)	15.64 (397.3)	13.19 (335.1)	15.19 (385.9)	17.19 (436.7)

Face plate edge is not intended for alignment of shaft (use pilot)
Applications with >20A rms will require the larger terminal box.

Drawings subject to change. Consult Exlar for certified drawings.

SLM/G = Model Series

SLG = SLG Series Servo Gearmotor
 SLM = SLM Series Servo Motor
 (no gear reduction)

AAA = Motor Frame Size

090 = 90 mm
 115 = 115 mm
 142 = 142 mm
 180 = 180 mm

BBB = Gear Reduction Ratio

(leave blank for SLM Motor)
 004 = 4:1 Single Reduction
 005 = 5:1 Single Reduction
 010 = 10:1 Single Reduction
 016 = 16:1 Double Reduction
 020 = 20:1 Double Reduction
 025 = 25:1 Double Reduction
 040 = 40:1 Double Reduction
 050 = 50:1 Double Reduction
 100 = 100:1 Double Reduction

C = Shaft Type

K = Keyed
 R = Smooth/round
 X = Special shaft

D = Connections

T = Terminal box with NPT ports, see pg 139

E = Coating Options (1)

G = Exlar standard
 E = Electroless nickel plated
 F = Smooth white epoxy
 X = Special coating

F = Brake Options

B = Brake
 S = Standard no brake

GGG = Feedback Type (Also specify the Amplifier/Drive Model being used when ordering) Resolver Only.

Standard Resolver – Size 15, 1024 line
 (2048 cts) per rev, 2 pole resolver

Custom Feedback: Please contact your local sales representative:

XX1 = Wiring and feedback device information must be provided and new feedback callout will be created
 AB6 = Allen Bradley/Rockwell - Std Resolver
 AM3 = Advantec Motion Control - Std Resolver
 AP1 = API Controls - Std Resolver
 BD2 = Baldor - Std Resolver - BSM motor wiring w/M23 connectors for "M" option
 BM2 = Baumüller - Std Resolver
 BR1 = B&R Automation - Std Resolver
 CO2 = Copely Controls - Std Resolver
 CT5 = Control Techniques/Emerson - Standard Resolver – FM/UM/EZ motor wiring w/M23 euro connectors for "M" option
 DT2 = Delta Tau Data Systems - Std Resolver
 EL1 = Elmo Motion Control - Std Resolver
 EX4 = Exlar - Std Resolver
 IF1 = Infranor - Std Resolver
 IN6 = Indramat/Bosch-Rexroth - Std Resolver – MKD/MHD motor wiring w/M23 Euro connectors for "M" option
 JT1 = Jetter Technologies - Std Resolver – JH/JL motor wiring w/M23 euro connectors for "M" option
 KM5 = Kollmorgen/Danaher - Std Resolver – AKM motor wiring w/M23 euro connectors for "M" option
 LZ5 = Lenze/AC Tech - Std Resolver – MCS motor wiring w/ M23 euro connectors for "M" option
 MD1 = Modicon - Std Resolver
 MG1 = Moog - Std Resolver
 MX1 = Metronix - Std Resolver
 MN4 = Momentum - Std Resolver - MN motor wiring w/M23 connectors for "M" option
 OR1 = Ormec - Std Resolver
 PC7 = Parker Compumotor - Std Resolver – SMH motor wiring w/M23 connectors for "M" option – European only
 PC0 = Parker Compumotor - Std Resolver – MPP motor wiring w/PS connectors for "M" option – US Only
 PS3 = Pacific Scientific - Std Resolver – PMA motor wiring w/M23 connectors for "M" option
 SM2 = Siemens - Std Resolver – 1FK7 motor wiring w/M23 connectors for "M" option
 SW1 = SEW/Eurodrive - Std Resolver – CM motor wiring w/ M23 euro connectors for "M" option
 WD1 = Whedco - Std Resolver

H = Motor Stacks

1 = 1 stack magnets
 2 = 2 stack magnets²
 3 = 3 stack magnets²
 x = Special

I = Voltage Rating

A = 24 Volt DC
 B = 48 Volt DC
 C = 120 Volt DC
 1 = 115 Volt RMS²
 3 = 230 Volt RMS
 5 = 400 Volt RMS
 6 = 460 Volt RMS
 X = Special voltage rating – not to exceed 460 Vrms

J = Motor Poles

8 = 8 motor poles

KK = Motor Speed

24 = 2400 rpm, SLM142, SLM180
 30 = 3000 rpm, SLM/G115
 40 = 4000 rpm, SLM/G090
 01-99 Special speed, consult your local sales representative

XX .. XX = Options

(please list desired options)

Special Options

NI = Non-incendive construction required for Class I, Div 2, see pg 127
 HW = Manual drive, handwheel including Class I, Div 2 interlock switch
 RD = Manual drive, Simple Rear
 SD = Manual drive, Side Hex
 RB = Rear brake
 HC = Type III anodizing hard coat
 SS = Stainless Steel³
 XH = Special housing option
 XL = Special lubrication
 XM = Special motor option
 XF = Special feedback

= Part No. Designator for Specials

Optional 5 digit assigned part number to designate unique model numbers for specials.

Notes:

1. These housing may indicate the need for special material main rods or mounting.
2. 115 Vrms is not available on a 2 or 3 stack SLM/G, or a 3 stack SLM/G090.
3. Force, torque and current ratings are reduced 25% with this option.

Sizing and Selection of Exlar Linear and Rotary Actuators

Move Profiles

The first step in analyzing a motion control application and selecting an actuator is to determine the required move profile. This move profile is based on the distance to be traveled and the amount of time available in which to make that move. The calculations below can help you determine your move profile.

Each motion device will have a maximum speed that it can achieve for each specific load capacity. This maximum speed will determine which type of motion profile can be used to complete the move. Two common types of move profiles are trapezoidal and triangular. If the average velocity of the profile, is less than half the max. velocity of the actuator, then triangular profiles can be used. Triangular Profiles result in the lowest possible acceleration and deceleration. Otherwise a trapezoidal profile can be used. The trapezoidal profile below with 3 equal divisions will result in 25% lower maximum speed and 12.5% higher acceleration and deceleration. This is commonly called a 1/3 trapezoidal profile.

The following pages give the required formulas that allow you to select the proper Exlar linear or rotary actuator for your application.

The first calculation explanation is for determining the required thrust in a linear application. The second provides the necessary equations for determining the torque required from a linear or rotary application. For rotary applications this includes the use of reductions through belts or gears, and for linear applications, through screws.

Pages are included to allow you to enter your data and easily perform the required calculations. You can also describe your application graphically and fax it to Exlar for sizing. Reference tables for common unit conversions and motion system constants are included at the end of the section.

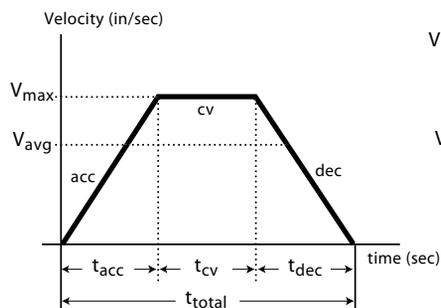
Linear Move Profile Calculations

- V_{max} = max.velocity-in/sec (m/sec)
- V_{avg} = avg. velocity-in/sec (m/sec)
- t_{acc} = acceleration time (sec)
- t_{dec} = deceleration time (sec)
- t_{cv} = constant velocity (sec)
- t_{total} = total move time (sec)
- acc = accel-in/sec² (m/sec²)
- dec = decel-in/sec² (m/sec²)
- cv = constant vel.-in/sec (m/sec)
- D = total move distance-in (m) or revolutions (rotary)

Standard Equations

- $V_{avg} = D / t_{total}$
- If $t_{acc} = t_{dec}$ Then: $V_{max} = (t_{total} / (t_{total} - t_{acc})) (V_{avg})$
- and
- $D = \text{Area under profile curve}$
- $D = (1/2)(t_{acc} + t_{dec} + t_{cv})(V_{max})$

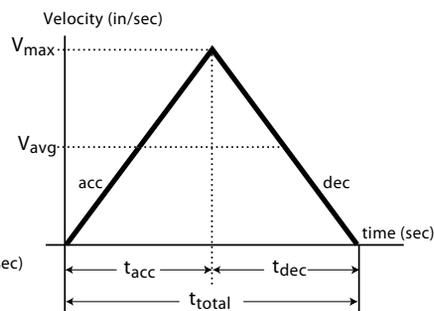
Trapezoidal Move Profile



Trapezoidal Equations

- If $t_{acc} = t_{cv} = t_{dec}$ Then:
- $V_{max} = 1.5 (V_{avg})$
- $D = (2/3) (t_{total}) (V_{max})$
- $acc = dec = \frac{V_{max}}{t_{acc}}$

Triangular Move Profile



Triangular Equations

- If $t_{acc} = t_{total}/2$ Then:
- $V_{max} = 2.0 (V_{avg})$
- $D = (1/2) (t_{total}) (V_{max})$
- $acc = dec = \frac{V_{max}}{t_{acc}}$

Terms and (units)

- THRUST** = Total linear force-lbf (N)
 θ = Angle of inclination (deg)
F_{friction} = Force from friction-lbf (N)
t_{acc} = Acceleration time (sec)
F_{acc} = Acceleration force-lbf (N)
v = Change in velocity-in/sec (m/s)
F_{gravity} = Force due to gravity-lbf (N)
 μ = Coefficient of sliding friction
F_{applied} = Applied forces-lbf (N)
 (refer to table on page 136 for different materials)
WL = Weight of Load-lbf (N)
 g = 386.4: Acceleration of gravity - in/sec² (9.8 m/sec²)

Thrust Calculation Equations

$$\text{THRUST} = F_{\text{friction}} + [F_{\text{acceleration}}] + F_{\text{gravity}} + F_{\text{applied}}$$

$$\text{THRUST} = WL\mu\cos\theta + [(WL/386.4)(v/t_{\text{acc}})] + WL\sin\theta + F_{\text{applied}}$$

Sample Calculations: Calculate the thrust required to accelerate a 200 pound mass to 8 inches per second in an acceleration time of 0.2 seconds. Calculate this thrust at inclination angles(θ) of 0°, 90° and 30°. Assume that there is a 25 pound spring force that is applied against the acceleration.

$$WL = 200 \text{ lbf}, v = 8.0 \text{ in/sec}, t_{\text{acc}} = 0.2 \text{ sec}, F_{\text{app.}} = 25 \text{ lbf}, \mu = 0.15$$

$$\theta = 0^\circ$$

$$\begin{aligned} \text{THRUST} &= WL\mu\cos\theta + [(WL/386.4)(v/t_{\text{acc}})] + WL\sin\theta + F_{\text{applied}} \\ &= (200)(0.15)(1) + [(200/386.4)(8.0/0.2)] + (200)(0) + 25 \\ &= 30 \text{ lbs} + 20.73 \text{ lbs} + 0 \text{ lbs} + 25 \text{ lbs} = \mathbf{75.73 \text{ lbs force}} \end{aligned}$$

$$\theta = 90^\circ$$

$$\begin{aligned} \text{THRUST} &= WL\mu\cos\theta + [(WL/386.4)(v/t_{\text{acc}})] + WL\sin\theta + F_{\text{applied}} \\ &= (200)(0.15)(0) + [(200/386.4)(8.0/0.2)] + (200)(1) + 25 \\ &= 0 \text{ lbs} + 20.73 \text{ lbs} + 200 \text{ lbs} + 25 \text{ lbs} = \mathbf{245.73 \text{ lbs force}} \end{aligned}$$

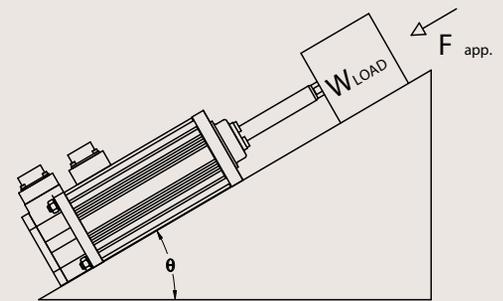
$$\theta = 30^\circ$$

$$\begin{aligned} \text{THRUST} &= WL\mu\cos\theta + [(WL/386.4)(v/t_{\text{acc}})] + WL\sin\theta + F_{\text{applied}} \\ &= (200)(0.15)(0.866) + [(200/386.4)(8.0/0.2)] + (200)(0.5) + 25 \\ &= 26 \text{ lbs} + 20.73 \text{ lbs} + 100 + 25 = \mathbf{171.73 \text{ lbs force}} \end{aligned}$$

Thrust Calculations

Definition of thrust:

The thrust necessary to perform a specific move profile is equal to the sum of four components of force. These are the force due to acceleration of the mass, gravity, friction and applied forces such as cutting and pressing forces and overcoming spring forces.



Angle of Inclination

90°	Note: at $\theta = 0^\circ$ $\cos\theta = 1$; $\sin\theta = 0$ at $\theta = 90^\circ$ $\cos\theta = 0$; $\sin\theta = 1$
0°	
-90°	

It is necessary to calculate the required thrust for an application during each portion of the move profile, and determine the worst case criteria. The linear actuator should then be selected based on those values. The calculations at the right show calculations during acceleration which is often the most demanding segment of a profile.

Motor Torque Calculations

When selecting an actuator system it is necessary to determine the required motor torque to perform the given application. These calculations can then be compared to the torque ratings of the given amplifier and motor combination that will be used to control the actuator's velocity and position.

When the system uses a separate motor and screw, like the FT actuator, the ratings for that motor and amplifier are consulted. In the case of the GSX Series actuators with their integral brushless motors, the required torque divided by the torque constant of the motor (K_t) must be less than the current rating of the GSX or SLM motor.

Inertia values and torque ratings can be found in the GSX, FT, I and SLM/SLG Series product specifications.

For the GSX Series the screw and motor inertia are combined.

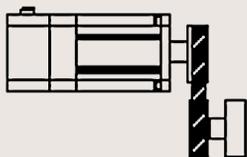
Motor with screw (GSX, GSM, FT, I & EL)



Motor & motor with reducer (SLM/SLG & ER)



Motor with belt and pulley



Terms and (units)

- λ = Required motor torque, lbf-in (N-m)
- λ_a = Required motor acceleration torque, lbf-in (N-m)
- F** = Applied force load, non inertial, lbf (N)
- S** = Screw lead, in (mm)
- R** = Belt or reducer ratio
- T_L** = Torque at driven load lbf-in (N-m)
- v_L** = Linear velocity of load in/sec (m/sec)
- ω_L = Angular velocity of load rad/sec
- ω_m = Angular velocity of motor rad/sec
- η = Screw or ratio efficiency
- g** = Gravitational constant, 386.4 in/s² (9.75 m/s²)
- α = Angular acceleration of motor, rad/s²
- m** = Mass of the applied load, lb (N)
- J_L** = Reflected Inertia due to load, lbf-in-s² (N-m-s²)
- J_r** = Reflected Inertia due to ratio, lbf-in-s² (N-m-s²)
- J_s** = Reflected Inertia due to external screw, lbf-in-s² (N-m-s²)
- J_m** = Motor armature inertia, lbf-in-s² (N-m-s²)
- L** = Length of screw, in (m)
- ρ = Density of screw material, lb/in³ (kg/m³)
- r** = Radius of screw, in (m)
- π = pi (3.14159)
- C** = Dynamic load rating, lbf (N)

Velocity Equations

Screw drive: $V_L = \omega_m \cdot S / 2\pi$ in/sec (m/sec)

Belt or gear drive: $\omega_m = \omega_L \cdot R$ rad/sec

Torque Equations

Torque Under Load

Screw drive (GS, FT or separate screw): $\lambda = \frac{S \cdot F}{2 \cdot \pi \cdot \eta}$ lbf-in (N-m)

Belt and Pulley drive: $\lambda = T_L / R \eta$ lbf-in (N-m)

Gear or gear reducer drive: $\lambda = T_L / R \eta$ lbf-in (N-m)

Torque Under Acceleration

$\lambda_a = (J_m + J_r + (J_s + J_L)/R^2)\alpha$ lbf-in

α = angular acceleration = ((RPM / 60) x 2 π) / t_{acc}, rad/sec².

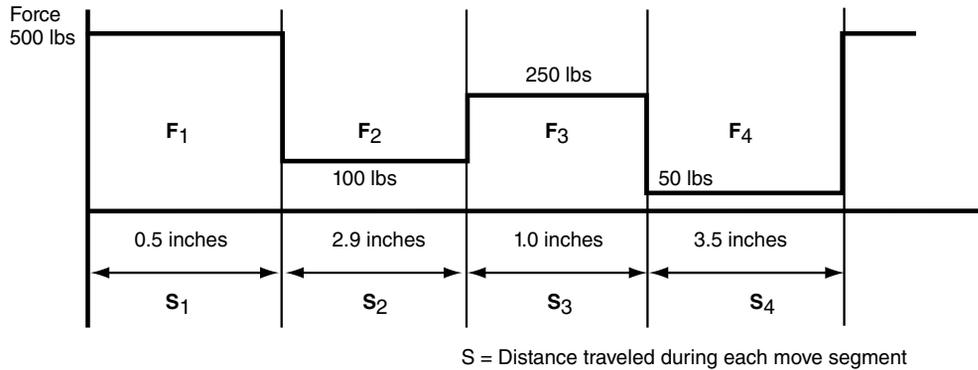
$J_s = \frac{\pi \cdot L \cdot \rho \cdot r^4}{2 \cdot g}$ lb-in-s² (N-m-s²)

Total Torque per move segment

$\lambda_T = \lambda_a + \lambda$ lbf-in (N-m)

Mean Load Calculations

For accurate lifetime calculations of a roller screw in a linear application, the cubic mean load should be used. Following is a graph showing the values for force and distance as well as the calculation for cubic mean load. Forces are shown for example purposes. Negative forces are shown as positive for calculation.



Cubic Mean Load Equation

$$\sqrt[3]{\frac{F_1^3 S_1 + F_2^3 S_2 + F_3^3 S_3 + F_4^3 S_4}{S_1 + S_2 + S_3 + S_4}}$$

Value from example numbers is 217 lbs.

Lifetime Calculations

The expected L_{10} life of a roller screw is expressed as the linear travel distance that 90% of the screws are expected to meet or exceed before experiencing metal fatigue. The mathematical formula that defines this value is below. *The life is in millions of inches (mm)*. This standard L_{10} life calculation is what is expected of 90% of roller screws manufactured and is not a guarantee. Travel life estimate is based on a properly maintained screw that is free of contaminants and properly lubricated. Higher than 90% requires de-rating according to the following factors:

95% x 0.62	96% x 0.53
97% x 0.44	98% x 0.33
99% x 0.21	

Single (non-preloaded) nut:

$$L_{10} = \left(\frac{C}{F}\right)^3 \times S$$

Note: The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw for the same application.

Thrust Calculations

Total Thrust Calculations

Terms and (units)

THRUST = Total linear force-lbf (N)
F_{friction} = Force from friction-lbf (N)
F_{acc} = Acceleration force-lbf (N)
F_{gravity} = Force due to gravity-lbf (N)
F_{applied} = Applied forces-lbf (N)
 386.4 = Acceleration of gravity - in/sec² (9.8 m/sec²)

Variables

\emptyset = Angle of inclination - deg..... = _____
t_{acc} = Acceleration time - sec..... = _____
v = Change in velocity - in/sec (m/s)..... = _____
 μ = Coefficient of sliding friction..... = _____
W_L = Weight of Load-lbm (kg) = _____
F_{applied} = Applied forces-lbf (N) = _____

Thrust Calculation Equations

$$\text{THRUST} = [\text{F}_{\text{friction}}] + [\text{F}_{\text{acceleration}}] + \text{F}_{\text{gravity}} + \text{F}_{\text{applied}}$$

$$\text{THRUST} = [\text{W}_L \times \mu \times \cos \emptyset] + [(\text{W}_L / 386.4) \times (\text{v} / \text{t}_{\text{acc}})] + \text{W}_L \sin \emptyset + \text{F}_{\text{applied}}$$

$$\text{THRUST} = [() \times () \times ()] + [(/ 386.4) \times (/)] + [() ()] + ()$$

$$\text{THRUST} = [\quad] + [() \times ()] + [\quad] + ()$$

= _____ lbf.

Calculate the thrust for each segment of the move profile. Use those values in calculations below. Use the units from the above definitions.

Cubic Mean Load Calculations

$$\sqrt[3]{ \frac{\text{F}_1^3 \text{S}_1 + \text{F}_2^3 \text{S}_2 + \text{F}_3^3 \text{S}_3 + \text{F}_4^3 \text{S}_4}{\text{S}_1 + \text{S}_2 + \text{S}_3 + \text{S}_4} }$$

$$\text{F}_1 = \text{_____} \quad \text{S}_1 = \text{_____} \quad \text{F}_1^3 \text{S}_1 = \text{_____}$$

$$\text{F}_2 = \text{_____} \quad \text{S}_2 = \text{_____} \quad \text{F}_2^3 \text{S}_2 = \text{_____}$$

$$\text{F}_3 = \text{_____} \quad \text{S}_3 = \text{_____} \quad \text{F}_3^3 \text{S}_3 = \text{_____}$$

$$\text{F}_4 = \text{_____} \quad \text{S}_4 = \text{_____} \quad \text{F}_4^3 \text{S}_4 = \text{_____}$$

Move Profiles may have more or less than four components. Adjust your calculations accordingly.

Torque Calculations

Terms and (units)

λ	= Torque, lb-in (N-m).....	= -----
F	= Applied Load, non inertial, lbf (N).....	= -----
S	= Screw lead, in (m).....	= -----
η	= Screw or ratio efficiency (~85% for roller screws).....	= -----
g	= Gravitational constant, 386 in/s ² (9.8 m/s ²).....	= -----
α	= Acceleration of motor, rad/s ²	= -----
R	= Belt or reducer ratio.....	= -----
T_L	= Torque at driven load, lbf-in (N-m).....	= -----
V_L	= Linear velocity of load, in/sec (m/sec).....	= -----
ω_L	= Angular velocity of load, rad/sec.....	= -----
ω_m	= Angular velocity of motor, rad/sec.....	= -----
m	= Mass of the applied load, lbm (kg).....	= -----
J_R	= Reflected Inertia due to ratio, lb-in-s ² (N-m-s ²).....	= -----
J_S	= Reflected Inertia due to screw, lb-in-s ² (N-m-s ²).....	= -----
J_L	= Reflected Inertia due to load, lb-in-s ² (N-m-s ²).....	= -----
J_M	= Motor armature inertia, lb-in-s ² (N-m-s ²).....	= -----
π	= pi.....	= 3.14159
K_t	= Motor Torque constant, lb-in/amp (N-m/amp).....	= -----

* For the GS Series J_S and J_M are one value from the GS Specifications.

Torque Equations

Torque From Calculated Thrust.

$$\lambda = \frac{SF}{2 \cdot \pi \cdot \eta} \text{ lb-in (N-m)} = (\quad) \times (\quad) / 2\pi (0.85) = (\quad) \times (\quad) / 5.34 = \text{-----}$$

Torque Due To Load, Rotary.

Belt and pulley drive: $\lambda = T_L / R \eta$ lbf-in (N-m)

Gear or gear reducer drive: $\lambda = T_L / R\eta$ lbf-in (N-m)

Torque During Acceleration due to screw, motor, load and reduction, linear or rotary.

$$I = (J_m + (J_S + J_L) / R^2) \alpha \text{ lb-in (N-m)} = [(\quad) + (\quad + \quad) / (\quad)] (\quad) = \text{-----}$$

Total Torque = Torque from calculated Thrust + Torque due to motor, screw and load

$$(\quad) + (\quad) + (\quad) = \text{-----}$$

Motor Current = $\lambda / K_t = (\quad) / (\quad) = \text{-----}$

Exlar Application Worksheet

FAX to:
Exlar Corporation
(952) 368-4877
Attn: Applications Engineering

Date: _____ Company Name: _____

Address: _____

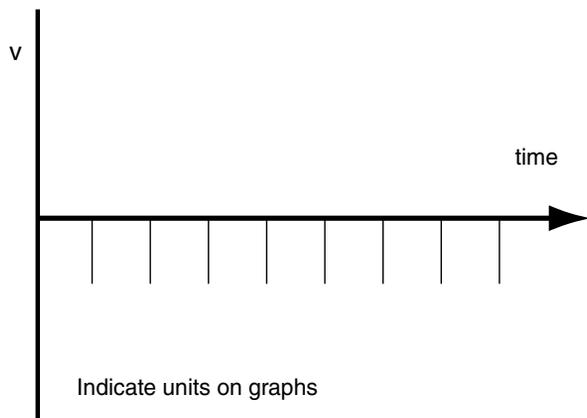
City: _____ State: _____ Zip Code: _____

Phone: _____ Fax: _____

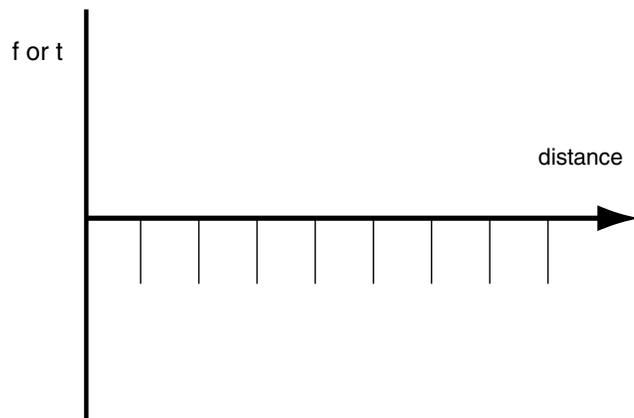
Contact: _____ Title: _____

Sketch/Describe Application

Velocity vs. Time



Force or Torque vs. Distance



Exlar Application Worksheet

Date: _____ Contact: _____ Company: _____

Stroke & Speed Requirements

Maximum Stroke Needed _____ inches (mm), revs
Index Stroke Length _____ inches (mm), revs
Index Time _____ sec
Max Speed Requirements _____ in/sec (mm/sec), revs/sec
Min Speed Requirements _____ in/sec (mm/sec), revs/sec
Required Positional Accuracy _____ inches (mm), arc min

Load & Life Requirements

Gravitational Load _____ lb (N)
External Applied Load _____ lbf (N)
Inertial Load _____ lbf (N)
Friction Load _____ lbf (N)
Rotary Inertial Load _____ lbf-in-sec^2 (Kg-m^2)
or rotary mass, radius of gyr. _____ lb (kg) _____ in (mm)
Side Load (rot. or lin. actuator) _____ lb (N)
Force Direction _____ Extend _____ Retract _____ Both
Actuator Orientation _____ Vertical Up _____ Vertical Down _____ Horizontal
_____ Fixed Angle _____ Degrees from Horizontal
_____ Changing Angle _____ to _____
Cycling Rate _____ Cycles/min/hr/day
Operating Hours per Day _____ Hours
Life Requirement _____ Cycles/hr/inches/mm

Configuration

Mounting: _____ Side _____ Flange _____ Ext Tie Rod _____ Clevis _____ Trunnion
Rod End: _____ Male _____ Female _____ Sph Rod Eye _____ Rod Eye _____ Clevis
Rod Rotation Limiting: _____ Appl Inherent _____ External Required
Holding Brake Required: _____ Yes _____ No
Cable Length: _____ ft (m)

Rotary Inertia

To obtain a conversion from A to B, multiply by the value in the table.

B	Kg-m ²	Kg-cm ²	g-cm ²	kgf-m-s ²	kgf-cm-s ²	gf-cm-s ²	oz-in ²	ozf-in-s ²	lb-in ²	lbf-in-s ²	lb-ft ²	lbf-ft-s ²
A												
Kg-m ²	1	10 ⁴	10 ⁷	0.10192	10.1972	1.01972x10 ⁴	5.46745x10 ⁴	1.41612x10 ²	3.41716x10 ³	8.850732	23.73025	0.73756
Kg-cm ²	10 ⁻⁴	1	10 ³	1.01972x10 ⁵	1.01972x10 ³	1.01972	5.46745	1.41612x10 ⁻²	0.341716	8.85073x10 ⁻⁴	2.37303x10 ⁻³	7.37561x10 ⁻⁵
g-cm ²	10 ⁻⁷	10 ⁻³	1	1.01972x10 ⁻⁸	1.01972x10 ⁻⁶	1.01972x10 ⁻³	5.46745x10 ⁻³	1.41612x10 ⁻⁵	3.41716x10 ⁻⁴	8.85073x10 ⁻⁷	2.37303x10 ⁻⁶	7.37561x10 ⁻⁸
kgf-m-s ²	9.80665	9.80665x10 ⁴	9.80665x10 ⁷	1	10 ²	10 ⁵	5.36174x10 ⁵	1.388674x10 ³	3.35109x10 ⁴	86.79606	2.32714x10 ²	7.23300
kgf-cm-s ²	9.80665x10 ⁻²	9.80665x10 ²	9.80665x10 ⁵	10 ⁻²	1	10 ⁵	5.36174 x10 ³	13.8874	3.35109x10 ⁻²	0.86796	2.32714	7.23300x10 ⁻²
gf-cm-s ²	9.80665x10 ⁻⁵	0.980665	9.80665x10 ²	10 ⁻⁵	10 ⁻³	1	5.36174	1.38874 x10 ⁻²	0.335109	8.67961x10 ⁻⁴	2.32714x10 ⁻³	7.23300x10 ⁻⁵
oz-in ²	1.82901x10 ⁻⁵	0.182901	1.82901x10 ²	1.86505x10 ⁻⁶	1.86505x10 ⁻⁴	0.186506	1	2.59008 x10 ⁻³	6.25 x10 ⁻²	1.61880x10 ⁻⁴	4.34028x10 ⁻⁴	1.34900x10 ⁻³
ozf-in-s ²	7.06154x10 ⁻³	70.6154	7.06154x10 ⁴	7.20077x10 ⁴	7.20077x10 ⁻²	72.0077	3.86089x10 ²	1	24.13045	6.25 x10 ⁻²	0.167573	5.20833x10 ⁻⁴
lb-in ²	2.92641x10 ⁻⁴	2.92641	2.92641x10 ³	2.98411x10 ⁵	2.98411x10 ³	2.98411	16	4.14414 x10 ²	1	2.59008x10 ³	6.94444x10 ⁻³	2.15840x10 ⁻⁴
lbf-in-s ²	0.112985	1.129x10 ³	1.12985x10 ⁶	1.15213x10 ²	1.15213	1.51213 x10 ³	6.1774 x10 ³	16	3.86088x10 ²	1	2681175	8.3333x10 ⁻²
lbf-ft ²	4.21403x10 ⁻²	4.21403x10 ²	4.21403x10 ⁵	4.29711x10 ³	0.429711	4.297114	2.304 x10 ³	5.96755	144	0.372971	1	3.10809x10 ⁻²
lbf-ft-s ²	1.35583	1.35582x10 ⁴	1.35582x10 ⁷	0.138255	13.82551	1.38255x10 ⁴	7.41289x10 ⁴	192	4.63306x10 ³	12	32.17400	1

Torque

To obtain a conversion from A to B, multiply A by the value in the table.

B	N-m	N-cm	dyn-cm	Kg-m	Kg-cm	g-cm	oz-in	ft-lb	in-lb
A									
N-m	1	10 ²	10 ⁷	0.109716	10.19716	1.019716 x10 ⁴	141.6199	0.737562	8.85074
N-cm	102	1	10 ⁵	1.019716 x10 ³	0.1019716	1.019716 x10 ²	1.41612	7.37562 x10 ⁻³	8.85074 x10 ⁻²
dyn-cm	10 ⁻⁷	10 ⁻⁵	1	1.019716 x10 ⁻⁸	1.019716 x10 ⁻⁶	1.019716 x10 ⁻³	1.41612 x10 ⁻⁵	7.2562 x10 ⁻⁸	8.85074 x10 ⁻⁷
Kg-m	9.80665	980665x10 ²	9.80665 x10 ⁷	1	10 ²	10 ⁵	1.38874 x10 ³	7.23301	86.79624
Kg-cm	9.80665x10 ⁻²	9.80665	9.80665 x10 ⁵	10 ⁻²	1	10 ³	13.8874	7.23301 x10 ⁻²	0.86792
g-cm	9.80665x10 ⁻⁵	9.80665x10 ⁻³	9.80665 x10 ²	10 ⁻⁵	10 ⁻³	1	1.38874 x10 ⁻²	7.23301 x10 ⁻⁵	8.679624 x10 ⁻⁴
oz-in	7.06155x10 ⁻³	0.706155	7.06155 x10 ⁴	7.20077 x10 ⁻⁴	7.20077 x10 ⁻²	72,077	1	5.20833 x10 ⁻³	6.250 x10 ⁻²
ft-lb	1.35582	1.35582x10 ²	1.35582 x10 ⁷	0.1382548	13.82548	1.382548 x10 ⁴	192	1	12
in-lb	0.113	11.2985	1.12985 x10 ⁶	1.15212 x10 ⁻²	1.15212	1.15212 x10 ³	16	8.33333 x10 ⁻²	1

Common Material Densities

Material	oz/in ³	gm/cm ³
Aluminum (cast or hard drawn)	1.54	2.66
Brass (cast or rolled)	4.80	8.30
Bronze (cast)	4.72	8.17
Copper (cast or hard drawn)	5.15	8.91
Plastic	0.64	1.11
Steel (hot or cold rolled)	4.48	7.75
Wood (hard)	0.46	0.80
Wood (soft)	0.28	0.58

Coefficients of Sliding Friction

Materials in contact	μ
Steel on Steel (dry)	0.58
Steel on Steel (lubricated)	0.15
Aluminum on Steel	0.45
Copper on Steel	0.36
Brass on Steel	0.44
Plastic on Steel	0.20
Linear Bearings	0.001



Headquartered at our design and manufacturing center in Chanhassen, Minnesota, Exlar serves a global customer base with an extensive electric linear and rotary actuator offering and complete engineering support for standard or custom applications.

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